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Global well-posedness for KdV in Sobolev spaces of negative index *

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Abstract

The initial value problem for the Korteweg-deVries equation on the line is shown to be globally well-posed for rough data. In particular, we show global well-posedness for initial data in $H^{s}(\mathbb{R})$ for -3/10 < s.

1 Introduction

Consider the initial value problem for the Korteweg-deVries (KdV) equation

$$\partial_t u + \partial_x^3 u + \frac{1}{2} \partial_x (u^2) = 0, \quad x \in \mathbb{R},$$

$$u(0) = \phi,$$

(1.1)

for rough initial data $\phi \in H^s(\mathbb{R})$, s < 0. The initial data ϕ and the solution u are assumed to take values in \mathbb{R} . This problem is known [9] to be locally well-posed provided -3/4 < s. For $s \ge 0$, the local result and L^2 norm conservation imply (1.1) is globally well-posed [1]. Recently, a direct adaptation [7] of Bourgain's high-low frequency technique [3], [2] showed (1.1) is globally well-posed for $\phi \in$ $H^s \cap \dot{H}^a$ for certain s, a < 0. A modification of the high-low frequency technique, first used in [8], is presented in this paper which establishes global well-posedness of (1.1) in $H^s(\mathbb{R}), -3/10 < s$.

A subsequent paper [6] will establish that (1.1) is globally well-posed in $H^s(\mathbb{R})$ for -3/4 < s. The simplicity of the argument presented here may extend more easily to other situations, such as in our treatment [5] of cubic *NLS* on \mathbb{R}^2 and *NLS* with derivative in \mathbb{R} [4].

The Multiplier operator I

Let s < 0 and $N \gg 1$ be fixed. Define the Fourier multiplier operator

$$\widehat{Iu}(\xi) = m(\xi)\widehat{u}(\xi), \quad m(\xi) = \begin{cases} 1, & |\xi| < N, \\ N^{-s}|\xi|^s, & |\xi| \ge 10N \end{cases}$$
(1.2)

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bilinear estimates.

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with m smooth and monotone. The operator I (barely) maps $H^s(\mathbb{R}) \longmapsto L^2(\mathbb{R})$. Observe that on low frequencies $\{\xi : |\xi| < N\}$, I is the identity operator. Note also that I commutes with differential operators. The operator I^{-1} is the Fourier multiplier operator with multiplier $\frac{1}{m(\ell)}$.

An almost L^2 conservation property of (1.1)

Let $\phi \in H^s(\mathbb{R})$, -3/4 < s < 0 in (1.1). There is a $\delta = \delta(\|\phi\|_{H^s}) > 0$ such that (1.1) is well-posed for $t \in [0, \delta]$. We observe using the Fundamental Theorem of Calculus, the equation, and integration by parts that

$$\begin{split} \|Iu(\delta)\|_{L^{2}}^{2} &= \|Iu(0)\|_{L^{2}}^{2} + \int_{0}^{\delta} \frac{d}{d\tau} (Iu(\tau), Iu(\tau)) d\tau, \\ &= \|Iu(0)\|_{L^{2}}^{2} + 2 \int_{0}^{\delta} (I\dot{u}(\tau), Iu(\tau)) d\tau, \\ &= \|Iu(0)\|_{L^{2}}^{2} + 2 \int_{0}^{\delta} (I(-u_{xxx} - \frac{1}{2}\partial_{x}[u^{2}])(\tau), Iu(\tau)) d\tau \\ &= \|Iu(0)\|_{L^{2}}^{2} + \int_{0}^{\delta} (I(-\partial_{x}[u^{2}]), Iu) d\tau. \end{split}$$

Finally, we add $0 = \int_0^{\delta} \int \partial_x (I(u)^2) I(u) d\tau$ to observe

$$\|Iu(\delta)\|_{L^2}^2 = \|Iu(0)\|_{L^2}^2 + \int_0^\delta \int \partial_x \left\{ (I(u))^2 - I(u^2) \right\} Iu \, dx d\tau.$$
(1.3)

This last step enables us to take advantage of some internal cancellation. We apply Cauchy-Schwarz as in [10] and bound the integral above by

$$\left\|\partial_x \{ (I(u))^2 - I(u^2) \} \right\|_{X^{\delta}_{0,-\frac{1}{2}-}} \|Iu\|_{X^{\delta}_{0,\frac{1}{2}+}}.$$
 (1.4)

The space $X_{s,b}^{\delta}$ of functions of space-time is defined via the Fourier restriction norm $\|u\|_{X_{s,b}^{\delta}} = \inf\{\|w\|_{X_{s,b}} := \|(1+|k|)^s(1+|\tau-k^3|)^b\widehat{w}(k,\tau)\|_{L^2_{k,\tau}} : w = u \text{ for } t \in [0,\delta]\}.$

Remark 1 An effort to find a term providing more cancellation than $\int_0^{\delta} \int \partial_x (I(u)^2) I(u) d\tau$ used above led to the general procedure described in [6].

Proposition 1 (A variant of local well-posedness) The initial value problem (1.1) is locally well-posed in the Banach space

 $I^{-1}L^2 = \{\phi \in H^s \text{ with norm } \|I\phi\|_{L^2}\}$ with existence lifetime δ satisfying

$$\delta \gtrsim \|I\phi\|_{L^2}^{-\alpha}, \text{ for some } \alpha > 0, \tag{1.5}$$

and moreover

$$\|Iu\|_{X_{0,\frac{1}{2}+}^{\delta}} \le C \|I\phi\|_{L^{2}}.$$
(1.6)

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This proposition is not difficult to prove using the argument in [9]. Using Duhamel's formula and $X_{s,b}$ space properties reduces matters to proving the bilinear estimate

$$\|\partial_x I(uv)\|_{X_{0,-\frac{1}{2}+}} \le C \|Iu\|_{X_{0,\frac{1}{2}+}} \|Iv\|_{X_{0,\frac{1}{2}+}}$$
(1.7)

to obtain the contraction. The space-time norm bound is then implied by the contraction estimate. The estimate (1.7) follows from the next proposition and the bilinear estimate of Kenig, Ponce and Vega [9].

Proposition 2 (Extra smoothing) The bilinear estimate

$$\|\partial_x \{I(u)I(v) - I(uv)\}\|_{X^{\delta}_{0,-\frac{1}{2}-}} \le CN^{-\frac{3}{4}+} \|Iu\|_{X^{\delta}_{0,\frac{1}{2}+}} \|Iv\|_{X^{\delta}_{0,\frac{1}{2}+}}.$$
 (1.8)

holds.

Recall the bilinear estimate $\|\partial_x(uv)\|_{X_{0,-\frac{1}{2}+}} \leq C \|u\|_{X_{0,\frac{1}{2}+}} \|v\|_{X_{0,\frac{1}{2}+}}$ from [9]. Proposition 2 reveals a smoothing beyond the recovery of the first derivative for the particular quadratic expression encountered above in (1.3). We prove Proposition 2 in the next section.

The required pieces are now in place for us to give the proof of global wellposedness of (1.1) in $H^s(\mathbb{R})$, -3/10 < s. Global well-posedness of (1.1) will follow if we show well-posedness on [0,T] for arbitrary T > 0. We re-normalize things a bit via scaling. If u solves (1.1) then $u_{\lambda}(x,t) = \left(\frac{1}{\lambda}\right)^2 u(\frac{x}{\lambda},\frac{t}{\lambda^3})$ solves (1.1) with initial data $\phi_{\lambda}(x,t) = \left(\frac{1}{\lambda}\right)^2 \phi(\frac{x}{\lambda})$. Note that u exists on [0,T] if and only if u_{λ} exists on $[0,\lambda^3T]$. A calculation shows that

$$\|I\phi_{\lambda}\|_{L^{2}} \le C\lambda^{-\frac{3}{2}-s}N^{-s}\|\phi\|_{H^{s}}.$$
(1.9)

Here N = N(T) will be selected later but we choose $\lambda = \lambda(N)$ right now by requiring

$$C\lambda^{-\frac{3}{2}-s}N^{-s}\|\phi\|_{H^s} \sim 1 \implies \lambda \sim N^{-\frac{2s}{3+2s}}.$$
(1.10)

We now drop the λ subscript on ϕ by assuming that

$$\|I\phi\|_{L^2} = \epsilon_0 \ll 1 \tag{1.11}$$

and our goal is to construct the solution of (1.1) on the time interval $[0, \lambda^3 T]$.

The local well-posedness result of Proposition 1 shows we can construct the solution for $t \in [0, 1]$ if we choose ϵ_0 small enough. The almost L^2 conservation property shows $||Iu(1)||_2^2 \leq ||Iu(0)||_2^2 + N^{-\frac{3}{4}+} ||Iu||_{X_{0,\frac{1}{2}+}}^3$. Using (1.6) and (1.11) gives

$$||Iu(1)||_2^2 \le \epsilon_0^2 + N^{-\frac{3}{4}+}.$$

We can iterate this process $N^{\frac{3}{4}-}$ times before doubling $||Iu(t)||_{L^2}$. Therefore, we advance the solution by taking $N^{\frac{3}{4}-}$ time steps of size O(1). We now restrict s by demanding that

$$N^{\frac{3}{4}-} \gtrsim \lambda^3 T = N^{\frac{-6s}{3+2s}} T$$
 (1.12)

is ensured for large enough N, so s > -3/10.

2 Proof of the bilinear smoothing estimate

This section establishes Proposition 2. We distinguish the **very low frequen**cies $\{\xi : |\xi| \leq 1\}$, the **low frequencies** $\{\xi : 1 \leq |\xi| \leq \frac{1}{2}N\}$ and the **high frequencies** $\{\xi : \frac{1}{2}N \leq |\xi|\}$. Decompose the factor u in the bilinear estimate by writing $u = u_{vl} + u_l + u_h$ with \hat{u}_l supported on the low frequencies and similarly for the very low and high frequency pieces. We decompose v the same way. Since I is the identity operator on the low and very low frequencies, we can assume one of the factors u, v in the estimate to be shown has its Fourier transform supported in the high frequencies. Symmetry allows us to assume $u = u_h$ and we need to consider the three possible interactions of u_h with v_{vl} , v_l and v_h . Finally, since we are considering (weighted) L^2 norms, we can replace \hat{u} and \hat{v} by $|\hat{u}|$ and $|\hat{v}|$. Assume therefore that $\hat{u}, \hat{v} \geq 0$.

Very low/high interaction

An explicit calculation shows that

$$\mathcal{F}\left(\partial_x \{ I(u_h v_{vl}) - I(u_h) v_{vl} \} \right)(\xi) = \int_{\xi = \xi_1 + \xi_2} i\xi [m(\xi) - m(\xi_1)] \widehat{u_h}(\xi_1) \widehat{v_{vl}}(\xi_2),$$
(2.1)

where \mathcal{F} denotes the Fourier transform. The mean value theorem gives

$$|m(\xi) - m(\xi_1)| \le |m'(\tilde{\xi_1})| |\xi_2|,$$

which may be interpolated with the trivial estimate to give

$$|m(\xi) - m(\xi_1)| \le CN^{-s} |\xi_1|^s |\xi_1|^{-\theta} |\xi_2|^{\theta}$$
(2.2)

for $0 \le \theta \le 1$. Recall that *m* was defined to be smooth and monotone in (1.2). Therefore, upon defining $\mathcal{F}(\nabla^{\theta} f)(\xi) = |\xi|^{\theta} \widehat{f}(\xi)$, we can write

$$|\mathcal{F}(\partial_x \{I(u_h v_{vl}) - I(u_h) v_{vl}\})(\xi)| \le |\mathcal{F}(\partial_x (\nabla^{-\theta} I(u_h) (\nabla^{\theta} v_{vl}))(\xi)|.$$

We now estimate the left side of the bilinear estimate in this interaction by

$$\left\|\partial_x (\nabla^{-\theta} I(u_h)) (\nabla^{\theta} v_{vl})\right\|_{X_{0,\frac{1}{2}+}}$$
(2.3)

and by the bilinear estimate of Kenig, Ponce and Vega

$$\leq C \left\| \nabla^{-\theta} I(u_h) \right\|_{X_{0,\frac{1}{2}+}} \left\| \nabla^{\theta} v_{vl} \right\|_{X_{0,\frac{1}{2}+}}.$$
(2.4)

The frequency support of v_{vl} shows that $\|\nabla^{\theta} v_{vl}\|_{X_{0,\frac{1}{2}+}} \lesssim \|v_{vl}\|_{X_{0,\frac{1}{2}+}}$. A moments thought shows

$$\left\|\nabla^{-\theta}I(u_{h})\right\|_{X_{0,\frac{1}{2}+}} \le N^{-\theta}\|I(u_{h})\|_{X_{0,\frac{1}{2}+}}$$
(2.5)

and the claim of the Proposition follows for the (very low)(high) interaction by choosing $\theta > 3/4$.

Low/high interaction

The preceding calculations reduce matters to controlling

$$\left\|\partial_x \nabla^{-\theta} I(u_h) \nabla^{\theta} v_l \right\|_{X_{0,\frac{1}{2}+}} \tag{2.6}$$

and we know that $\widehat{u_h}$ and $\widehat{v_l}$ are supported outside the very low frequencies.

Lemma 1 Assume \hat{u} and \hat{v} are supported outside $\{|\xi| < 1\}$. Then

$$\|\partial_x(uv)\|_{X_{\alpha,-\frac{1}{2}+}} \le C \|u\|_{X_{-\gamma_1,\frac{1}{2}+}} \|v\|_{X_{-\gamma_2,\frac{1}{2}+}}$$
(2.7)

provided

$$\begin{aligned} \alpha - (\gamma_1 + \gamma_2) &< \frac{3}{4}, \\ \alpha - \gamma_i &< \frac{1}{2}, \ i = 1, 2. \end{aligned}$$

We will apply the lemma momentarily with $\alpha = 0, \gamma_1 = \gamma_2 = -3/8+$.

The proof of the lemma is contained in the proof of Theorem 2 in [7]. In particular, the support properties on \hat{u} , \hat{v} reduce matters to considering Cases A.3, A.4, A.6, B.3, B.4, B.5 and B.6 in [7]. The restriction $\alpha - (\gamma_1 + \gamma_2) < 3/4$ arises in Case A.4.c.ii of [7] which is the region containing the counterexample of [9]. Case B.4.b of [7] requires the other condition $\alpha - \gamma_i < \frac{1}{2}$.

The lemma applied to (2.6) gives

$$\leq C \left\| \nabla^{-\theta} I(u_h) \right\|_{X_{-\frac{3}{8}+,\frac{1}{2}+}} \left\| \nabla^{\theta} v_l \right\|_{X_{-\frac{3}{8}+,\frac{1}{2}+}}$$

Setting $\theta = \frac{3}{8}$ - leaves

$$C \left\| \nabla^{-\frac{3}{4}+} I(u_h) \right\|_{X_{0,\frac{1}{2}+}} \|v_l\|_{X_{0,\frac{1}{2}+}} \le C N^{-\frac{3}{4}+} \|I(u_h)\|_{X_{0,\frac{1}{2}+}} \|v_l\|_{X_{0,\frac{1}{2}+}}$$

which was to be shown.

High/high interaction

In this region of the interaction, we do not take advantage of any cancellation and estimate the difference with the triangle inequality

$$\|\partial_x \{I(u_h)I(v_h)\}\|_{X_{0,-\frac{1}{2}+}} + \|\partial_x \{I(u_hv_h)\}\|_{X_{0,-\frac{1}{2}+}}.$$

For the first contribution we use the lemma to get

$$\|I(u_h)\|_{X_{-\frac{3}{8}+,\frac{1}{2}+}}\|I(v_h)\|_{X_{-\frac{3}{8}+,\frac{1}{2}+}} \le N^{-\frac{3}{4}+}\|I(u_h)\|_{X_{0,\frac{1}{2}+}}\|I(v_h)\|_{X_{0,\frac{1}{2}+}}.$$
 (2.8)

The second contribution is bounded by throwing away ${\cal I}$ and applying the lemma,

$$\begin{split} \|\partial_x \{u_h v_h\}\|_{X_{0,-\frac{1}{2}+}} &\leq \|u_h\|_{X_{-\frac{3}{8}+,\frac{1}{2}+}} \|u_h\|_{X_{-\frac{3}{8}+,\frac{1}{2}+}} \\ &\leq N^{-\frac{3}{8}+s+} \|u_h\|_{X_{s,\frac{1}{2}+}} N^{-\frac{3}{8}+s+} \|v_h\|_{X_{s,\frac{1}{2}+}} \\ &\leq N^{-\frac{3}{4}+} \|u_h\|_{X_{0,\frac{1}{2}+}} \|v_h\|_{X_{0,\frac{1}{2}+}}. \end{split}$$

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