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## A CHARACTERIZATION OF BALLS USING THE DOMAIN DERIVATIVE

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ABSTRACT. In this note we give a characterization of balls in  $\mathbb{R}^N$  using the domain derivative. As a byproduct we will show that an overdetermined Stekloff eigenvalue problem is solvable if and only if the domain of interest is a ball.

## 1. INTRODUCTION

In this note we give a characterization of balls in  $\mathbb{R}^N$  using the domain derivative. As an application we prove that an overdetermined Stekloff eigenvalue problem is solvable if the domain of interest is a ball. This work is motivated by the following result.

**Theorem 1.1.** A domain  $D \subset \mathbb{R}^N$  is a ball if and only if there exists a constant c such that the following integral equality is valid

$$\int_{D} h \, dx = c \int_{\partial D} h \, d\sigma, \tag{1.1}$$

for every harmonic function h.

For the proof of the above theorem, the reader is referred to [1, 3].

Our characterization replaces (1.1) by another integral equation which involves the domain derivative of the solution of the Saint-Venant equation in D. This result will enable us to show that an overdetermined Stekloff eigenvalue problem is solvable if and only if the domain of the problem is a ball.

## 2. Main result

To state the main result we need some preparation. Henceforth D is a smooth simply connected bounded domain in  $\mathbb{R}^N$ . By u we denote the unique solution of the Saint-Venant problem in D; i.e.,

$$-\Delta u = 1 \quad \text{in } D$$
  
$$u = 0 \quad \text{on } \partial D \tag{2.1}$$

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Given a vector field  $V \in C^2(\mathbb{R}^N; \mathbb{R}^N)$ , we denote by u', the domain derivative of u at D in direction of V; the reader is referred to [5] for a thorough treatment of the concept of domain derivatives. Using [5, Theorems 3.1 and 3.2], it follows that

$$\Delta u' = 0 \quad \text{in } D$$
  
$$u' = -\frac{\partial u}{\partial \nu} V \cdot \nu \quad \text{on } \partial D,$$
  
(2.2)

where  $\nu$  stands for the unit outward normal vector on  $\partial D$ . Now we state our main result.

**Theorem 2.1.** The domain D is a ball if and only if there exists a constant c such that the following integral equation is valid

$$\int_{D} u' \, dx = c \int_{\partial D} u' \, d\sigma, \tag{2.3}$$

for every vector field  $V \in C^2(\mathbb{R}^N; \mathbb{R}^N)$ .

We need the following result.

**Lemma 2.2.** Suppose  $f \in C(\partial D)$  and the following equation holds

$$\int_{\partial D} f V \cdot \nu \, d\sigma = 0, \tag{2.4}$$

for every  $V \in C^2(\mathbb{R}^N, \mathbb{R}^N)$ . Then f vanishes on  $\partial D$ .

*Proof.* To derive a contradiction suppose  $f(x_0) \neq 0$ , for some  $x_0 \in \partial D$ . Let us assume that in fact  $f(x_0) > 0$ ; the case  $f(x_0) < 0$  can be addressed similarly. Since f is continuous, we readily infer existence of an open component of  $\partial D$ , denoted  $\gamma$ , where

$$f(x) \ge \frac{1}{k}, \quad \forall x \in \gamma$$

for some integer k. Thanks to smoothness of  $\partial D$  we can make the following observation; namely,  $\partial D$  is locally star-shaped. This means: For every  $\xi \in \partial D$ , there exists a ball  $B_{\xi}$  centered at  $\xi$ , and a point  $x_{\xi} \in D$ , such that

$$(x - x_{\xi}) \cdot \nu(x) > 0, \quad \forall x \in B_{\xi} \cap \partial D.$$

Without loss of generality we may assume there exists  $x^* \in D$  such that

$$(x - x^*) \cdot \nu(x) > 0, \quad \forall x \in \gamma.$$

Let us now consider a non-negative test function  $\phi \in C_0^{\infty}(\mathbb{R}^N)$ , where the intersection of the support of  $\phi$  with  $\partial D$  is a proper subset of  $\gamma$  and has positive measure. Now we choose  $V = \phi(x)(x - x^*)$  in (2.4); note that V is admissible since it belongs to  $C^2(\mathbb{R}^N, \mathbb{R}^N)$ . Thus

$$\int_{\gamma} f(x)\phi(x)(x-x^*)\cdot\nu(x)\,d\sigma = 0.$$
(2.5)

However

$$\int_{\gamma} f(x)\phi(x) \ (x-x^*) \cdot \nu(x) \ d\sigma \ge \frac{1}{k} \int_{\mathrm{support}(\phi)\cap\gamma} \phi(x)(x-x^*) \cdot \nu(x) \ d\sigma > 0,$$

which contradicts (2.5). Thus f must vanish on  $\partial D$ , as desired.

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Proof of Theorem 2.1. Assume that (2.3) is satisfied. Let us fix  $V \in C^2(\mathbb{R}^N; \mathbb{R}^N)$ . We claim

$$\int_{D} u' \, dx = \int_{\partial D} \left(\frac{\partial u}{\partial \nu}\right)^2 V \cdot \nu \, d\sigma.$$
(2.6)

To prove (2.6) we observe that from the differential equation in (2.1) we have  $\int_D u' dx = -\int_D u' \Delta u \, dx$ . Since u' is harmonic in D it then follows that

$$\int_{D} u' \, dx = \int_{D} (u\Delta u' - u'\Delta u) \, dx$$

Now an application of the Green identity to the right hand side of the above equation yields

$$\int_{D} u' \, dx = \int_{\partial D} \left( u \frac{\partial u'}{\partial \nu} - u' \frac{\partial u}{\partial \nu} \right) \, d\sigma.$$

Since u vanishes on  $\partial D$ , the above equation implies

$$\int_{D} u' \, dx = -\int_{\partial D} u' \, \frac{\partial u}{\partial \nu} \, d\sigma. \tag{2.7}$$

From (2.7) and the boundary condition in (2.2) we derive (2.6). From the hypothesis and (2.6) we obtain  $c \int_{\partial D} u' \, d\sigma = \int_{\partial D} \left(\frac{\partial u}{\partial \nu}\right)^2 V \cdot \nu \, d\sigma$ . So again using the boundary condition in (2.2) we derive

$$-c\int_{\partial D} \partial u/\partial \nu V \cdot \nu \, d\sigma = \int_{\partial D} \left(\frac{\partial u}{\partial \nu}\right)^2 V \cdot \nu \, d\sigma.$$

 $\operatorname{So}$ 

$$\int_{\partial D} \left( \left( \frac{\partial u}{\partial \nu} \right)^2 + c \frac{\partial u}{\partial \nu} \right) V \cdot \nu \, d\sigma = 0.$$

Since  $V \in C^2(\mathbb{R}^N; \mathbb{R}^N)$  is arbitrary Lemma 2.2, applied to the above equation, guarantees that

$$\frac{\partial u}{\partial \nu} \left( \frac{\partial u}{\partial \nu} + c \right) = 0 \quad \text{on } \partial D.$$

By the Hopf boundary point lemma applied to (2.1) we infer that  $\partial u/\partial \nu$  is negative on  $\partial D$ . So the last equation implies  $\partial u/\partial \nu = -c$  on  $\partial D$ . This result added to (2.1) yields the following overdetermined boundary value problem

$$-\Delta u = 1 \quad \text{in } D$$

$$u = 0 \quad \text{on } \partial D$$

$$\frac{\partial u}{\partial \nu} = -c \quad \text{on } \partial D$$
(2.8)

It is classical, see [4, 6], that (2.8) is solvable if and only if D is a ball.

Conversely, let us assume that D is a ball. Without loss of generality we may assume that D is the ball with radius R centered at the origin. Note that in this case the solution of (2.1) is

$$u(x) = \frac{1}{2N}(R^2 - |x|^2).$$

Therefore  $\partial u/\partial \nu$  will be equal to -R/N on  $\partial D$ . So if we apply (2.7) we find that

$$\int_D u' \, dx = -\frac{R}{N} \int_{\partial D} u' \, d\sigma$$

which coincides with the integral equation (2.3), with c = -R/N. This completes the proof.

Note that c = -R/N, as in the above argument, could also be written as  $c = -\frac{\omega_N R^N}{N\omega_N R^{N-1}} = -\frac{V(D)}{S(D)}$ , where  $\omega_N$  stands for the volume of the unit N-dimensional ball, and V(D), S(D) denote the volume and the surface area of D, respectively.

In the remaining of this section we focus on the Stekloff eigenvalue problem; i.e.,

$$\Delta w = 0 \quad \text{in } D.$$
  
$$\frac{\partial w}{\partial \nu} = pw \quad \text{on } \partial D \tag{2.9}$$

In (2.9), p denotes the eigenvalue. It is well known that there are infinitely many eigenvalues  $0 = p_1 < p_2 \le p_3 \le \ldots$  for which (2.9) has non trivial solutions. These solutions are the corresponding eigenfunctions denoted by  $w_1, w_2, \ldots$ , where  $w_1$  is clearly constant. We now prove the following result.

**Theorem 2.3.** The overdetermined boundary-value problem

$$\Delta w = 0 \quad in \ D$$

$$\frac{\partial w}{\partial \nu} = pw \quad on \ \partial D$$

$$\int_{D} w_k \ dx = 0 \quad \forall k \ge 2.$$
(2.10)

is solvable if and only if D is a ball.

*Proof.* Let us assume D is a ball. Let  $w_k$  be an eigenfunction corresponding to  $p_k, k = 2, 3, \ldots$  Since  $w_k$  is harmonic it follows from the mean value property that

$$\int_D w_k \, dx = d \int_{\partial D} w_k \, d\sigma$$

for some constant d. Thus using the boundary condition in (2.9) in conjunction with the Divergence Theorem we infer

$$\int_D w_k \, dx = \frac{d}{p_k} \int_D \Delta w_k \, dx.$$

Since  $w_k$  is harmonic in D we obtain  $\int_D w_k dx = 0$ , as desired.

To prove the converse we proceed along the same lines as in [2, Theorem 2] to prove the converse. To this end, let u be the solution of the Saint-Venant problem in  $D, V \in C^2(\mathbb{R}^N; \mathbb{R}^N)$ , and u' the domain derivative of u in direction of V. Since D is smooth it follows from (2.2) that  $u' \in C^2(\overline{D})$ . Hence u' can be represented in terms of the eigenfunctions  $w_k$  as follows

$$u'(x) = \sum_{i=1}^{\infty} \gamma_i \ w_i(x),$$

where

$$\gamma_i = \int_{\partial D} w_i u' \, d\sigma.$$

Integrating the equation before the last, over D, and taking into account that  $\int_D w_i dx = 0$ , for  $i = 2, 3, \ldots$  yields

$$\int_D u' \, dx = \gamma_1 \int_D w_1 \, dx = k \int_{\partial D} u' \, d\sigma,$$

where k is a constant independent of the vector field V. Since V is arbitrary we can apply Theorem 2.1 to conclude that D must be a ball, as desired.  $\Box$ 

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