

## EXISTENCE AND ASYMPTOTIC BEHAVIOUR OF POSITIVE SOLUTIONS FOR SEMILINEAR ELLIPTIC SYSTEMS IN THE EUCLIDEAN PLANE

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ABSTRACT. We study the semilinear elliptic system

$$\Delta u = \lambda p(x)f(v), \Delta v = \lambda q(x)g(u),$$

in an unbounded domain  $D$  in  $\mathbb{R}^2$  with compact boundary subject to some Dirichlet conditions. We give existence results according to the monotonicity of the nonnegative continuous functions  $f$  and  $g$ . The potentials  $p$  and  $q$  are nonnegative and required to satisfy some hypotheses related on a Kato class.

### 1. INTRODUCTION

Semilinear elliptic systems of the form

$$\begin{aligned} \Delta u &= F(u, v), \\ \Delta v &= G(u, v), \end{aligned} \tag{1.1}$$

in  $\mathbb{R}^n$  have been extensively treated recently. Lair and Wood [9] studied the semilinear elliptic system

$$\begin{aligned} \Delta u &= p(|x|)v^\alpha, \\ \Delta v &= q(|x|)u^\beta, \end{aligned} \tag{1.2}$$

in  $\mathbb{R}^n$  ( $n \geq 3$ ). They showed the existence of entire positive radial solutions. More precisely, for the sublinear case where  $\alpha, \beta \in (0, 1)$ , they proved the existence of bounded solutions of (1.2) if  $p$  and  $q$  satisfy the decay conditions

$$\int_0^\infty tp(t)dt < \infty, \quad \int_0^\infty tq(t)dt < \infty, \tag{1.3}$$

and the existence of large solutions if

$$\int_0^\infty tp(t)dt = \infty, \quad \int_0^\infty tq(t)dt = \infty. \tag{1.4}$$

For the superlinear case, where  $\alpha, \beta \in (1, +\infty)$ . The authors proved the existence of an entire large positive solution of problem (1.2), provided that the functions  $p$  and  $q$  satisfy (1.3).

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Peng and Song [13] considered the semilinear elliptic system

$$\begin{aligned}\Delta u &= p(|x|)f(v), \\ \Delta v &= q(|x|)g(u),\end{aligned}\tag{1.5}$$

in  $\mathbb{R}^n$  ( $n \geq 3$ ), under the assumptions:

- (A1) The functions  $p$  and  $q$  satisfy condition (1.3).  
 (A2) The functions  $f$  and  $g$  are positive nondecreasing, satisfying the Keller-Osserman condition [8, 12]

$$\int_1^\infty \frac{1}{\sqrt{\int_0^s f(t)dt}} ds < \infty, \quad \int_1^\infty \frac{1}{\sqrt{\int_0^s g(t)dt}} ds < \infty.\tag{1.6}$$

- (A3) The functions  $f$  and  $g$  are convex on  $[0, +\infty)$ .

The authors proved the existence of an entire large positive solution of problem (1.5). We remark that Peng and Song extended their results to the superlinear case in [9].

Cirstea and Radulescu [5] gave existence results for system (1.5). They adopted the assumptions (A1)-(A2) and the assumption

$$(A3') \quad f, g \in C^1[0, +\infty), \quad f(0) = g(0) = 0, \quad \lim_{t \rightarrow +\infty} \inf \frac{f(t)}{g(t)} > 0,$$

to prove the existence of entire large positive solutions.

Recently, Ghanmi et al [7] considered the semilinear elliptic system

$$\begin{aligned}\Delta u &= \lambda p(x)f(v), \\ \Delta v &= \mu q(x)g(u),\end{aligned}$$

in a domain  $D$  of  $\mathbb{R}^n$  ( $n \geq 3$ ) with compact boundary subject to some Dirichlet conditions. They assumed that the functions  $f, g$  are nonnegative continuous monotone on  $(0, \infty)$ , the nonnegative potentials  $p$  and  $q$  are required to satisfy some hypotheses related to a Kato class [3, 10]. In particular, in the case where  $f$  and  $g$  are nondecreasing and for given positive constants  $\lambda_0, \mu_0$ , they showed that for each  $\lambda \in [0, \lambda_0)$  and  $\mu \in [0, \mu_0)$ , there exists a positive bounded solution  $(u, v)$  satisfying the boundary conditions

$$u|_{\partial^\infty D} = \varphi \mathbf{1}_{\partial D} + a \mathbf{1}_{\{\infty\}}, \quad v|_{\partial^\infty D} = \psi \mathbf{1}_{\partial D} + b \mathbf{1}_{\{\infty\}}$$

where  $\varphi$  and  $\psi$  are nontrivial nonnegative continuous functions on  $\partial D$ .

In this article, we consider an unbounded domain  $D$  in  $\mathbb{R}^2$  with compact non-empty boundary  $\partial D$  consisting of finitely many Jordan curves. We are concerned with the semilinear elliptic system

$$\begin{aligned}\Delta u &= \lambda p(x)f(v), \quad \text{in } D \\ \Delta v &= \mu q(x)g(u), \quad \text{in } D \\ u|_{\partial D} &= a\varphi, \quad v|_{\partial D} = b\psi, \\ \lim_{|x| \rightarrow +\infty} \frac{u(x)}{\ln|x|} &= \alpha, \quad \lim_{|x| \rightarrow +\infty} \frac{v(x)}{\ln|x|} = \beta,\end{aligned}\tag{1.7}$$

where  $a, b, \alpha$  and  $\beta$  are nonnegative constants such that  $a + \alpha > 0$ ,  $b + \beta > 0$ . The functions  $\varphi$  and  $\psi$  are nontrivial nonnegative and continuous on  $\partial D$ . We will give two existence results according to the monotonicity of the functions  $f$  and  $g$ .

Throughout this paper, we denote by  $H_D\varphi$  the bounded continuous solution of the Dirichlet problem

$$\begin{aligned} \Delta w &= 0 \quad \text{in } D, \\ w|_{\partial D} &= \varphi, \quad \lim_{|x| \rightarrow +\infty} \frac{w(x)}{\ln|x|} = 0, \end{aligned} \quad (1.8)$$

where  $\varphi$  is a nonnegative continuous function on  $\partial D$ .

We remark that the solution  $H_D\varphi$  of (1.8) belongs to  $\mathcal{C}(\overline{D} \cup \{\infty\})$  and satisfies  $\lim_{|x| \rightarrow +\infty} H_D\varphi(x) = C > 0$  (See [6, p. 427]).

For the sake of simplicity we denote

$$\tilde{\varphi} := aH_D\varphi + \alpha h, \quad \tilde{\psi} := bH_D\psi + \beta h, \quad (1.9)$$

where  $h$  is the harmonic function defined by (2.2), below.

The outline of this paper is as follows. In section 2, we will give some notions related to the Green function  $G_D$  of the domain  $D$  associated to the Laplace operator  $\Delta$  and properties of the functions belonging to a some Kato class  $K(D)$  (See [10, 14]). In section 3, we will first give an example and then we give the proof of the existence result for the problem (1.7). More precisely, we adopt in section 3 the following hypotheses

- (H1) The functions  $f, g : [0, \infty) \rightarrow [0, \infty)$  are nondecreasing and continuous.
- (H2) The functions  $\tilde{p} := pf(\tilde{\psi})$  and  $\tilde{q} := qg(\tilde{\varphi})$  belong to the Kato class  $K(D)$ .
- (H3)  $\lambda_0 := \inf_{x \in D} \frac{\tilde{\varphi}(x)}{V(\tilde{p})(x)} > 0$  and  $\mu_0 := \inf_{x \in D} \frac{\tilde{\psi}(x)}{V(\tilde{q})(x)} > 0$ , where  $V$  is the Green kernel defined by (2.1) below.

We prove the following result.

**Theorem 1.1.** *Assume (H1)–(H3), then for each  $\lambda \in [0, \lambda_0)$  and  $\mu \in [0, \mu_0)$ , problem (1.7) has a positive continuous solution  $(u, v)$  satisfying, on  $D$ ,*

$$\begin{aligned} \left(1 - \frac{\lambda}{\lambda_0}\right)[aH_D\varphi + \alpha h] &\leq u \leq aH_D\varphi + \alpha h, \\ \left(1 - \frac{\mu}{\mu_0}\right)[bH_D\psi + \beta h] &\leq v \leq bH_D\psi + \beta h. \end{aligned}$$

In the last section, we fix  $\lambda = \mu = 1$  and a nontrivial nonnegative continuous function  $\Phi$  on  $\partial D$  and we note  $h_0 = H_D\Phi$ . Then we give an existence result for problem (1.7) with  $a = 1$  and  $b = 1$ , under the following hypotheses:

- (H4) The functions  $f, g : [0, \infty) \rightarrow [0, \infty)$  are nonincreasing and continuous.
- (H5) The functions  $p_0 := p\frac{f(h_0)}{h_0}$  and  $q_0 := q\frac{g(h_0)}{h_0}$  belong to the Kato class  $K(D)$ .

More precisely, we obtain the following result.

**Theorem 1.2.** *Assume (H4)–(H5), then there exists a constant  $c > 1$  such that if  $\varphi \geq c\Phi$  and  $\psi \geq c\Phi$  on  $\partial D$ , then problem (1.7) with  $a = 1$  and  $b = 1$  has a positive continuous solution  $(u, v)$  satisfying, on  $D$ ,*

$$\begin{aligned} h_0 + \alpha h &\leq u \leq H_D\varphi + \alpha h, \\ h_0 + \beta h &\leq v \leq H_D\psi + \beta h. \end{aligned}$$

Note that this result generalizes those by Athreya [2] and Toumi and Zeddini [14], stated for semilinear elliptic equations.

## 2. PRELIMINARIES

In the reminder of this paper, we will adopt the following notation.

$\mathcal{C}(\overline{D} \cup \{\infty\}) = \{f \in \mathcal{C}(\overline{D}) : \lim_{|x| \rightarrow +\infty} f(x) \text{ exists}\}$ . We note that  $\mathcal{C}(\overline{D} \cup \{\infty\})$  is a Banach space endowed with the uniform norm  $\|f\|_\infty = \sup_{x \in D} |f(x)|$ .

For  $x \in D$ , we denote by  $\delta_D(x)$  the distance from  $x$  to  $\partial D$ , by  $\rho_D(x) := \min(1, \delta_D(x))$  and by  $\lambda_D(x) := \delta_D(x)(1 + \delta_D(x))$ .

Let  $f$  and  $g$  be two positive functions on a set  $S$ . We denote  $f \sim g$  if there exists a constant  $c > 0$  such that

$$\frac{1}{c}g(x) \leq f(x) \leq cg(x) \quad \text{for all } x \in S.$$

For a Borel measurable and nonnegative function  $f$  on  $D$ , we denote by  $Vf$  the Green kernel of  $f$  defined on  $D$  by

$$Vf(x) = \int_D G_D(x, y)f(y)dy. \quad (2.1)$$

We recall that if  $f \in L^1_{\text{loc}}(D)$  and  $Vf \in L^1_{\text{loc}}(D)$ , then we have  $\Delta(Vf) = -f$  in  $D$ , in the distributional sense (See [4, p 52]).

We note that the Green function satisfies

$$G_D(x, y) \sim \ln\left(1 + \frac{\lambda_D(x)\lambda_D(y)}{|x - y|^2}\right)$$

on  $D^2$  (See [11]).

**Definition 2.1.** A Borel measurable function  $q$  in  $D$  belongs to the Kato class  $K(D)$  if  $q$  satisfies

$$\lim_{\alpha \rightarrow 0} \left( \sup_{x \in D} \int_{D \cap B(x, \alpha)} \frac{\rho_D(y)}{\rho_D(x)} G_D(x, y)|q(y)|dy \right) = 0,$$

and

$$\lim_{M \rightarrow +\infty} \left( \sup_{x \in D} \int_{D \cap \{|y| \geq M\}} \frac{\rho_D(y)}{\rho_D(x)} G_D(x, y)|q(y)|dy \right) = 0.$$

**Example 2.2.** Let  $p > 1$  and  $\gamma, \theta \in \mathbb{R}$  such that  $\gamma < 2 - \frac{2}{p} < \theta$ . Then using the Hölder inequality and the same arguments as in [14, Proposition 3.4] it follows that for each  $f \in L^p(D)$ , the function defined in  $D$  by  $\frac{f(x)}{(1+|x|)^{\theta-\gamma}(\delta_D(x))^\gamma}$  belongs to  $K(D)$ .

Throughout this article,  $h$  will be the function defined on  $D$  by

$$h(x) = 2\pi \lim_{|y| \rightarrow +\infty} G_D(x, y) \quad (2.2)$$

**Proposition 2.3** ([15]). *The function  $h$  defined by (2.2) is harmonic positive in  $D$  and satisfies*

$$\lim_{x \rightarrow z \in \partial D} h(x) = 0, \quad \lim_{|x| \rightarrow +\infty} \frac{h(x)}{\ln|x|} = 1.$$

In the sequel, we use the notation

$$\|q\|_D = \sup_{x \in D} \int_D \frac{\rho_D(y)}{\rho_D(x)} G_D(x, y)|q(y)|dy, \quad (2.3)$$

$$\alpha_q = \sup_{x, y \in D} \int_D \frac{G_D(x, z)G_D(z, y)}{G_D(x, y)} |q(z)|dz. \quad (2.4)$$

It is shown in [14], that if  $q \in K(D)$ , then  $\|q\|_D < \infty$ , and  $\alpha_q \sim \|q\|_D$ . For stating our results we need the following result.

**Proposition 2.4** ([14]). *Let  $q$  in  $K(D)$ , then the following assertions hold*

(i) *For any nonnegative superharmonic function  $w$  in  $D$ , we have*

$$V(wq)(x) = \int_D G_D(x, y)w(y)|q(y)|dy \leq \alpha_q w(x), \forall x \in D. \tag{2.5}$$

(ii) *The potential  $Vq \in C(\bar{D} \cup \infty)$  and  $\lim_{x \rightarrow z \in \partial D} Vq(x) = 0$ .*  
 (iii) *Let  $\Lambda_q = \{p \in K(D) : |p| \leq q\}$ . Then the family of functions*

$$\mathfrak{F}_q = \left\{ \int_D G_D(\cdot, y)h_0(y)p(y)dy : p \in \Lambda_q \right\}$$

*is uniformly bounded and equicontinuous in  $\bar{D} \cup \{\infty\}$ . Consequently, it is relatively compact in  $C(\bar{D} \cup \{\infty\})$ .*

### 3. PROOF OF THEOREM 1.1

Before stating the proof, we give an example where (H2) and (H3) are satisfied.

**Example 3.1.** Let  $D = \overline{B(0,1)}^c$  be the exterior of the unit closed disk. Let  $\alpha = b = 1$  and  $\beta = a = 0$ . Assume that  $\psi \geq c_1 > 0$  on  $\partial D$ . Let  $p_1, \tilde{q}$  be nonnegative functions in  $K(D)$  such that the function  $p := p_1h$  is in  $K(D)$ . Then using the fact that the function  $f$  is continuous and  $H_D\psi$  is bounded on  $D$  we obtain that  $\tilde{p} := pf(H_D\psi) \in K(D)$  and so the hypothesis (H2) is satisfied. Now, since  $\tilde{p}_1 := p_1f(H_D\psi) \in K(D)$  then by Proposition 2.4 (i) we obtain

$$V(\tilde{p}) \leq \alpha_{\tilde{p}_1}h.$$

Therefore, for each  $x \in D$

$$\frac{h(x)}{V(\tilde{p})(x)} \geq \frac{1}{\alpha_{p_1}} > 0;$$

that is,  $\lambda_0 > 0$ . On the other hand we have

$$\frac{H_D\psi(x)}{V(\tilde{q})(x)} \geq \frac{c_1}{\alpha_{\tilde{q}}} > 0,$$

which yields  $\mu_0 > 0$ . Thus the hypothesis (H3) is satisfied.

*Proof of Theorem 1.1.* Let  $\lambda \in [0, \lambda_0)$  and  $\mu \in [0, \mu_0)$ . We intend to prove that the problem (1.7) has a positive continuous solution. To this aim we define the sequences  $(u_k)_{k \in \mathbb{N}}$  and  $(v_k)_{k \in \mathbb{N}}$  as follows:

$$\begin{aligned} v_0 &= \tilde{\psi}, \\ u_k &= \tilde{\varphi} - \lambda V(pf(v_k)), \\ v_{k+1} &= \tilde{\psi} - \mu V(qg(u_k)), \end{aligned}$$

where  $\tilde{\varphi}$  and  $\tilde{\psi}$  are defined by (1.9). We shall prove by induction that for each  $k \in \mathbb{N}$ ,

$$\begin{aligned} 0 &< \left(1 - \frac{\lambda}{\lambda_0}\right)\tilde{\varphi} \leq u_k \leq u_{k+1} \leq \tilde{\varphi}, \\ 0 &< \left(1 - \frac{\mu}{\mu_0}\right)\tilde{\psi} \leq v_{k+1} \leq v_k \leq \tilde{\psi}. \end{aligned}$$

First, using hypothesis (H3) we obtain, on  $D$ ,

$$\lambda_0 V(pf(\tilde{\psi})) \leq \tilde{\varphi}.$$

Then by the monotonicity of  $f$ , it follows that

$$\tilde{\varphi} \geq u_0 = \tilde{\varphi} - \lambda V(pf(\tilde{\psi})) \geq \left(1 - \frac{\lambda}{\lambda_0}\right) \tilde{\varphi} > 0.$$

So

$$v_1 - v_0 = -\mu V(qg(u_0)) \leq 0$$

and consequently

$$u_1 - u_0 = \lambda V(p[f(v_0) - f(v_1)]) \geq 0.$$

Moreover, the hypothesis (H3) yields

$$\mu_0 V(qg(\tilde{\varphi})) \leq \tilde{\psi}.$$

Then using the fact that the function  $g$  is nondecreasing we have

$$v_1 \geq \tilde{\psi} - \mu V(qg(\tilde{\varphi})) \geq \left(1 - \frac{\mu}{\mu_0}\right) \tilde{\psi} > 0.$$

In addition, we have  $u_1 \leq \tilde{\varphi}$ , then it follows that

$$u_0 \leq u_1 \leq \tilde{\varphi} \quad \text{and} \quad v_1 \leq v_0 \leq \tilde{\psi}.$$

Suppose that

$$u_k \leq u_{k+1} \leq \tilde{\varphi} \quad \text{and} \quad \left(1 - \frac{\mu}{\mu_0}\right) \tilde{\psi} \leq v_{k+1} \leq v_k.$$

Therefore,

$$\begin{aligned} v_{k+2} - v_{k+1} &= \mu V(q[g(u_k) - g(u_{k+1})]) \leq 0, \\ u_{k+2} - u_{k+1} &= \lambda V(p[f(v_{k+1}) - f(v_{k+2})]) \geq 0. \end{aligned}$$

Furthermore, since  $u_{k+1} \leq \tilde{\varphi}$  the monotonicity of the function  $g$  yields

$$v_{k+2} \geq \tilde{\psi} - \lambda V(qg(\tilde{\varphi})) \geq \left(1 - \frac{\mu}{\mu_0}\right) \tilde{\psi} > 0.$$

Thus, we obtain

$$u_{k+1} \leq u_{k+2} \leq \tilde{\varphi} \quad \text{and} \quad \left(1 - \frac{\mu}{\mu_0}\right) \tilde{\psi} \leq v_{k+2} \leq v_{k+1}.$$

Hence, the sequences  $(u_k)$  and  $(v_k)$  converge respectively to two functions  $u$  and  $v$  satisfying

$$0 < \left(1 - \frac{\lambda}{\lambda_0}\right) \tilde{\varphi} \leq u \leq \tilde{\varphi}, \quad 0 < \left(1 - \frac{\mu}{\mu_0}\right) \tilde{\psi} \leq v \leq \tilde{\psi}.$$

Furthermore, for each  $k \in \mathbb{N}$ , we have

$$f(v_k) \leq f(\tilde{\psi}), \quad g(u_k) \leq g(\tilde{\varphi}). \quad (3.1)$$

Therefore, using hypothesis (H2) and Proposition 2.4 (ii) we deduce by Lebesgue's theorem that  $V(pf(v_k))$  and  $V(qg(u_k))$  converge respectively to  $V(pf(v))$  and  $V(qg(u))$  as  $k$  tends to infinity. Then, on  $D$ ,  $(u, v)$  satisfies

$$\begin{aligned} u &= \tilde{\varphi} - \lambda V(pf(v)) \\ v &= \tilde{\psi} - \mu V(qg(u)). \end{aligned} \quad (3.2)$$

Moreover, by (3.2) and the monotonicity of the functions  $f$  and  $g$  we obtain  $pf(v) \leq \tilde{p}$  and  $qg(u) \leq \tilde{q}$ . So  $pf(v), qg(u) \in K(D)$  and consequently by Proposition 2.4 (ii) we have  $V(pf(v)), V(qg(u)) \in \mathcal{C}(\bar{D} \cup \{\infty\})$ . Now using the fact

that the functions  $\tilde{\varphi}$  and  $\tilde{\psi}$  are continuous we conclude that  $u$  and  $v$  are continuous and satisfy in the distributional sense  $\Delta u = \lambda pf(v)$  and  $\Delta v = \mu qg(u)$  in  $D$ . Now, since  $H_D\varphi = \varphi$  on  $\partial D$ ,  $\lim_{x \rightarrow z \in \partial D} h(x) = 0$ , and  $\lim_{x \rightarrow z \in \partial D} V(\tilde{p})(x) = 0$ , we conclude that  $\lim_{x \rightarrow z \in \partial D} u(x) = a\varphi(z)$ . By similar arguments we have  $\lim_{x \rightarrow z \in \partial D} v(x) = b\psi(z)$ . Furthermore, by Proposition 2.4 (ii) and Proposition 2.3, we have  $\lim_{|x| \rightarrow +\infty} \frac{1}{h(x)} V(pf(v)) = 0$  and  $\lim_{|x| \rightarrow +\infty} \frac{1}{h(x)} V(qg(u)) = 0$ . Hence  $(u, v)$  is a continuous positive solution of the problem (1.7), which completes the proof.  $\square$

#### 4. PROOF OF THEOREM 1.2

In the sequel, we recall that  $h_0 = H_D\Phi$  is a fixed positive harmonic function in  $D$  and  $h$  is the function defined by (2.2).

*Proof.* Let  $\alpha_{p_0}$  and  $\alpha_{q_0}$  be the constants defined by (2.4) associated respectively to the functions  $p_0$  and  $q_0$  given in the hypothesis (H5). Put  $c = 1 + \alpha_{p_0} + \alpha_{q_0}$ . Suppose that

$$\varphi(x) \geq c\Phi(x) \quad \text{and} \quad \psi(x) \geq c\Phi(x), \quad \forall x \in \partial D.$$

Then by the maximum principle it follows that for each  $x \in D$

$$H_D\varphi(x) \geq ch_0(x), \tag{4.1}$$

$$H_D\psi(x) \geq ch_0(x). \tag{4.2}$$

Consider the nonempty convex set  $\Omega$  given by

$$\Omega := \{w \in \mathcal{C}(\overline{D} \cup \{\infty\}) : h_0 \leq w \leq H_D\varphi\}.$$

Let  $T$  be the operator defined on  $\Omega$  by

$$Tw := H_D\varphi - V(pf[\beta h + H_D\psi - V(qg(w + \alpha h))]).$$

We shall prove that the operator  $T$  has a fixed point. First, let us prove that the operator  $T$  maps  $\Omega$  to its self. Let  $w \in \Omega$ . Since  $w + \alpha h \geq h_0$ , then from hypothesis (H4) we deduce that

$$V(qg(w + \alpha h)) \leq V(qg(h_0)). \tag{4.3}$$

Therefore, using (4.2) and (4.3) we obtain

$$\begin{aligned} v &:= \beta h + H_D\psi - V(qg(w + \alpha h)) \geq \beta h + H_D\psi - V(q_0 h_0) \\ &\geq \beta h + H_D\psi - \alpha_{q_0} h_0 \geq \beta h + (c - \alpha_{q_0})h_0. \end{aligned}$$

This yields

$$v \geq h_0 > 0. \tag{4.4}$$

So,  $Tw \leq H_D\varphi$ . On the other hand, by (4.4), the monotonicity of  $f$  and Proposition 2.4 (i), we obtain

$$V(pf(v)) \leq V(pf(h_0)) = V(p_0 h_0) \leq \alpha_{p_0} h_0. \tag{4.5}$$

Then, by (4.1) and (4.5), we have

$$Tw \geq H_D\varphi - \alpha_{p_0} h_0 \geq (1 + \alpha_{q_0})h_0 \geq h_0.$$

Hence  $T\Omega \subseteq \Omega$ . Next, let us prove that the set  $T\Omega$  is relatively compact in  $\mathcal{C}(\overline{D} \cup \{\infty\})$ . Let  $w \in \Omega$ , then by (H4), (H5) and using Proposition 2.4 (iii) it follows that the family of functions

$$\left\{ \int_D G(\cdot, y) p(y) f[\beta h + H_D \psi - V(qg(w + \alpha h))](y) dy : w \in \Omega \right\}$$

is relatively compact in  $\mathcal{C}(\overline{D} \cup \{\infty\})$ . Since  $H_D \varphi \in \mathcal{C}(\overline{D} \cup \{\infty\})$  we deduce that  $T\Omega$  is relatively compact in  $\mathcal{C}(\overline{D} \cup \{\infty\})$ .

Now we prove the continuity of the operator  $T$  in  $\Omega$  in the supremum norm. Let  $(w_k)$  be a sequence in  $\Omega$  which converges uniformly to a function  $w$  in  $\Omega$ . Then using (4.4) and the monotonicity of  $f$  we have, for each  $x$  in  $D$ ,

$$\begin{aligned} & p(x) |f(\beta h + H_D \psi - V(qg(w_k + \alpha h)))(x) - f(\beta h + H_D \psi - V(qg(w + \alpha h)))(x)| \\ & \leq 2f(h_0)p(x) \leq 2\|h_0\|_\infty p_0(x) \end{aligned}$$

Using the fact that  $Vp_0$  is bounded, we conclude by the continuity of  $f$  and the dominated convergence theorem that for all  $x \in D$ ,  $Tw_k(x) \rightarrow Tw(x)$  as  $k \rightarrow +\infty$ . Consequently, as  $T\Omega$  is relatively compact in  $\mathcal{C}(\overline{D} \cup \{\infty\})$ , we deduce that the pointwise convergence implies the uniform convergence; that is,

$$\|Tw_k - Tw\|_\infty \rightarrow 0 \quad \text{as } k \rightarrow +\infty$$

Therefore,  $T$  is a continuous mapping of  $\Omega$  to itself. So, since  $T\Omega$  is relatively compact in  $\mathcal{C}(\overline{D} \cup \{\infty\})$ , it follows that  $T$  is compact mapping on  $\Omega$ . Thus, the Schauder fixed-point theorem yields the existence of  $w \in \Omega$  such that

$$w = H_D \varphi - V(pf[\beta h + H_D \psi - V(qg(w + \alpha h))]).$$

Put  $u(x) = w(x) + \alpha h(x)$  and  $v(x) = \beta h(x) + H_D \psi(x) - V(qg(u))(x)$  for  $x \in D$ . Then  $(u, v)$  is a positive continuous solution of (1.7) with  $a = 1, b = 1$ , for the same arguments as in the proof of Theorem 1.1.  $\square$

**Example 4.1.** Let  $D = \overline{B(0, 1)}^c$  be the exterior of the unit closed disk,  $0 < \theta < 1$  and  $0 < \gamma < 1$ . Let  $p, q$  be two nonnegative functions such that the functions  $(\frac{|x|}{|x|-1})^{1+\theta} p(x)$  and  $(\frac{|x|}{|x|-1})^{1+\gamma} q(x)$  are in  $K(D)$ . Suppose that the functions  $\varphi$  and  $\psi$  are nonnegative continuous on  $\partial D$ . Then for a fixed nontrivial nonnegative continuous function  $\Phi$  in  $\partial D$ , there exists a constant  $c > 1$  such that if  $\varphi \geq c\Phi$  and  $\psi \geq c\Phi$  on  $\partial D$ , the problem

$$\begin{aligned} \Delta u &= p(x)v^{-\gamma}, & \text{in } D \\ \Delta v &= q(x)u^{-\theta}, & \text{in } D \\ u|_{\partial D} &= \varphi, \quad v|_{\partial D} = \psi, & \lim_{|x| \rightarrow +\infty} \frac{u(x)}{\ln|x|} = \alpha \geq 0, \quad \lim_{|x| \rightarrow +\infty} \frac{v(x)}{\ln|x|} = \beta \geq 0, \end{aligned}$$

has a positive continuous solution  $(u, v)$  satisfying

$$\begin{aligned} H_D \Phi(x) + \alpha h(x) &\leq u(x) \leq H_D \varphi(x) + \alpha h(x), \\ H_D \Phi(x) + \beta h(x) &\leq v(x) \leq H_D \psi(x) + \beta h(x), \end{aligned}$$

for each  $x \in D$ . Indeed, from [1] there exists  $c_0 > 0$  such that for each  $x \in D$ ,

$$c_0 \frac{|x| - 1}{|x|} \leq H_D \Phi(x).$$



It follows that  $p_0 := p \frac{(H_D \Phi(x))^{-\theta}}{H_D \Phi(x)} \in K(D)$ . In a similar way we have  $q_0 \in K(D)$ . Thus the hypothesis (H5) is satisfied.

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