

**EXISTENCES AND UPPER SEMI-CONTINUITY OF PULLBACK  
ATTRACTORS IN  $H^1(\mathbb{R}^N)$  FOR NON-AUTONOMOUS  
REACTION-DIFFUSION EQUATIONS PERTURBED BY  
MULTIPLICATIVE NOISE**

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**ABSTRACT.** In this article, we establish sufficient conditions on the existence and upper semi-continuity of pullback attractors in some *non-initial spaces* for non-autonomous random dynamical systems. As an application, we prove the existence and upper semi-continuity of pullback attractors in  $H^1(\mathbb{R}^N)$  are proved for stochastic non-autonomous reaction-diffusion equation driven by a Wiener type multiplicative noise as well as a non-autonomous forcing. The asymptotic compactness of solutions in  $H^1(\mathbb{R}^N)$  is proved by the well-known tail estimate technique and the estimate of the integral of  $L^{2p-2}$ -norm of truncation of solutions over a compact interval.

1. INTRODUCTION

In this paper, we consider the dynamics of solutions of the reaction-diffusion equation on  $\mathbb{R}^N$  driven by a random noise as well as a deterministic non-autonomous forcing,

$$du + (\lambda u - \Delta u)dt = f(x, u)dt + g(t, x)dt + \varepsilon u \circ d\omega(t), \quad (1.1)$$

with the initial value

$$u(\tau, x) = u_0(x), \quad x \in \mathbb{R}^N, \quad (1.2)$$

where  $u_0 \in L^2(\mathbb{R}^N)$ ,  $\lambda$  is a positive constant,  $\varepsilon$  is the intensity of noise, the unknown  $u = u(x, t)$  is a real valued function of  $x \in \mathbb{R}^N$  and  $t > \tau$ ,  $\omega(t)$  is a mutually independent two-sided real-valued Wiener process defined on a canonical Wiener probability space  $(\Omega, \mathcal{F}, P)$ .

The notion of random attractor of random dynamical system, which is introduced in [5, 6, 7, 15] and systematically developed in [1, 4], is an important tool to study the qualitative property of stochastic partial differential equations (SPDE) . We can find a large body of literature investigating the existence of random attractors in *an initial space* (the initial values located space) for some concrete SPDE, see [2, 9, 30, 18, 20, 22, 24, 25] and the references therein. In particular, [18, 19, 21] discussed the upper semi-continuity of a family of random attractors in the initial spaces.

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As we know, the solutions of SPDE may possess some regularities, for example, higher-order integrability or higher-order differentiability. In these cases, the solutions may escape (or leave) the initial space and enter into another space, which we call a *non-initial space*. Thus it is interesting for us to further investigate the existence and upper semi-continuity of random attractors in a non-initial space, usually a higher-regularity space, e.g.,  $L^p(p > 2)$  and  $H^1$ .

Recently in the case of bounded domain, Li *et al* [12, 10] discussed the existence of random attractor of stochastic reaction-diffusion equations in the non-initial spaces  $L^p$ , where  $p$  is the growth exponent of the nonlinearity. Zhao [28] investigated the existence of random attractor in  $H_0^1$  for stochastic two dimensional micropolar fluid flows with coupled additive noises. When the state space is unbounded, Zhao and Li [27] proved the existence of random attractors for reaction-diffusion equations with additive noises in  $L^p(\mathbb{R}^N)$ , and for the same equation Li *et al* [11] obtained the upper semi-continuity of random attractor in  $L^p(\mathbb{R}^N)$ . Most recently Zhao [26, 29] proved the existence of random attractors for semi-linear degenerate parabolic equations in  $L^{2p-2}(D) \cap H^1(D)$ , where  $D$  is a unbounded domain. By using the notion of omega-limit compactness, Li [13] obtained the existence of random attractors in  $L^q(\mathbb{R}^N)$  for semilinear Laplacian equations with multiplicative noise. Tang [16] considered the existence of random attractors for non-autonomous Fitzhugh-Nagumo system driven by additive noises in  $H^1(\mathbb{R}^N) \times L^2(\mathbb{R}^N)$ , and his work [17] investigated the random dynamics of stochastic reaction-diffusion equations with *additive noises* in  $H^1(\mathbb{R}^N)$ . However, it seems that the proofs in [16, 17] are essentially wrong, see Li and Yin [14] for the modified proof.

In this article, we study the existence and upper semi-continuity of pullback (random) attractors in  $H^1(\mathbb{R}^N)$  for stochastic reaction diffusion equations with *multiplicative noise* as well as a non-autonomous forcing. The nonlinearity  $f$  and the deterministic non-autonomous function  $g$  satisfy almost the same conditions as in [18], in which the author obtained the existence and upper-continuity of pullback attractors in the initial space  $L^2(\mathbb{R}^N)$ . Here, we develop their results and show that such attractors are also compact and attracting in  $H^1(\mathbb{R}^N)$ . Furthermore, we find that the upper continuity can also happen in  $H^1(\mathbb{R}^N)$ . We recall that the existence of pullback attractors in an initial space for a non-autonomous SPDE is established in [19, 20], where the measurability of such attractors is proved. The applications we may see [9, 18, 19, 20] and so forth. For the theory of the upper semi-continuity of attractors, we may refer to [18, 19, 21] for the stochastic case and to [3, 8] for the deterministic case.

To solve our problem, we establish a sufficient criteria for the existence and upper semi-continuity of pullback attractors in a non-initial space. It is showed that a family of such attractors obtained in an initial space are compact, attracting and upper semi-continuous in a non-initial space if some compactness conditions of the cocycle are satisfied, see Theorems 2.6–2.8. This implies that the continuity (or quasi-continuity [12], norm-weak continuity [32]) and absorption in the non-initial space are unnecessary things. This result is a meaningful and convenient tool for us to consider the existence and upper semi-continuity of pullback attractors in some related non-initial spaces for SPDE with a non-autonomous forcing term.

Considering that the stochastic equation (1.1) is defined on unbounded domains, the asymptotic compactness of solution in  $H^1(\mathbb{R}^N)$  can not be derived by the traditional technique. The reasons are as follows. On the one hand, the equation (1.1)

is stochastic and the Wiener process  $\omega$  is only continuous in  $t$  but not differentiable. This leads to some difficulties for us to estimate the norm of derivative  $u_t$  by the trick employed in [31, 32] in the deterministic case. Then the asymptotic compactness in  $H^1(\mathbb{R}^N)$  can not be proved by estimate of the difference of  $\nabla u$  as in [31]. On the other hand, the estimate of  $\Delta u$  is not available for our problem (To our knowledge, actually we do not know how to estimate the norm  $\Delta u$  of problem (1.1) and (1.2), although this can be achieved by estimate  $u_t$  in the deterministic case, see [32]). Hence the Sobolev compact embeddings of  $H^2 \hookrightarrow H^1$  on bounded domains is unavailable.

Here we give a new method to prove the asymptotical compactness of solutions in  $H^1(\mathbb{R}^N)$ . We first prove that the solutions vanish outside a ball centred at zero in the state space  $\mathbb{R}^N$  in the topology of  $H^1$  when both the time and the radius of ball are large enough, see Proposition 4.4. Second by a new developed estimate (where the minus or plus sign of nonlinearity is not required) we show that the integral of  $L^{2p-2}$ -norm of truncation of solutions over a compact interval is small for a large time, see Proposition 4.5. From these facts and along with some spectral arguments the asymptotic compactness of solutions on bounded domains is followed, and then the obstacles encountered in [16, 17] are overcome. The technique used here (without assumption that  $\psi_1 \in L^\infty$ , see (3.1)) is different from that in [14] and thus is optimal.

In the next section, we recall some notions and prove a sufficient standard for the existence and upper semi-continuity of pullback attractors of non-autonomous system in a non-initial space. In section 3, we give the assumptions on  $g$  and  $f$ , and define a continuous cocycle for problem (1.1) and (1.2). In section 4 and 5, we prove the existence and upper semi-continuity for this cocycle in  $H^1(\mathbb{R}^N)$ .

## 2. PRELIMINARIES AND ABSTRACT RESULTS

Let  $(X, \|\cdot\|_X)$  and  $(Y, \|\cdot\|_Y)$  be two completely separable Banach spaces with Borel sigma-algebras  $\mathcal{B}(X)$  and  $\mathcal{B}(Y)$ , respectively.  $X \cap Y \neq \emptyset$ . For convenience, we call  $X$  an *initial space* (which contains all initial values of a SPDE) and  $Y$  the associated *non-initial space* (usually the regular solutions located space).

In this section, we give a sufficient standard for the existence and upper semi-continuity of pullback attractors in the non-initial space  $Y$  for random dynamical system (RDS) over two parametric spaces. The readers may refer to [26, 27, 28, 10, 11, 12, 13, 23] for the existence and semi-continuity of such type attractors in the non-initial space  $Y$  for a RDS over one parametric space. The existence of random attractors in the initial space  $X$  for the RDS over one parametric space, the good references are [1, 2, 5, 15, 7, 6]. However, here we recall from [20] some basic notions for RDS over two parametric spaces, one of which is a real numbers space and the other of which is a measurable probability space.

**2.1. Preliminaries.** The basic notion in RDS is a metric dynamical system (MDS)  $\vartheta \equiv (\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$ , which is a probability space  $(\Omega, \mathcal{F}, P)$  incorporating a group  $\vartheta_t, t \in \mathbb{R}$ , of measure preserving transformations on  $(\Omega, \mathcal{F}, P)$ . Sometimes, we call  $\vartheta \equiv (\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$  a parametric dynamical system, see [18].

A MDS  $\vartheta$  is said to be ergodic under  $P$  if for any  $\vartheta$ -invariant set  $F \in \mathcal{F}$ , we have either  $P(F) = 0$  or  $P(F) = 1$ , where the  $\vartheta$ -invariant set is in the sense that  $\vartheta_t F = F$  for  $F \in \mathcal{F}$  and all  $t \in \mathbb{R}$ .

**Definition 2.1.** Let  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$  be a metric dynamical system. A family of measurable mappings  $\varphi : \mathbb{R}^+ \times \mathbb{R} \times \Omega \times X \rightarrow X$  is called a cocycle on  $X$  over  $\mathbb{R}$  and  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$  if for all  $\tau \in \mathbb{R}, \omega \in \Omega$  and  $t, s \in \mathbb{R}^+$ , the following conditions are satisfied:

$$\begin{aligned} \varphi(0, \tau, \omega, \cdot) & \text{ is the identity on } X, \\ \varphi(t+s, \tau, \omega, \cdot) & = \varphi(t, \tau+s, \vartheta_s \omega, \cdot) \circ \varphi(s, \tau, \omega, \cdot). \end{aligned}$$

In addition, if  $\varphi(t, \tau, \omega, \cdot) : X \rightarrow X$  is continuous for all  $t \in \mathbb{R}^+, \tau \in \mathbb{R}, \omega \in \Omega$ , then  $\varphi$  is called a continuous cocycle on  $X$  over  $\mathbb{R}$  and  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$ .

**Definition 2.2.** Let  $2^X$  be the collection of all subsets of  $X$ . A set-valued mapping  $K : \mathbb{R} \times \Omega \rightarrow 2^X$  is called measurable in  $X$  with respect to  $\mathcal{F}$  in  $\Omega$  if the mapping  $\omega \in \Omega \mapsto \text{dist}_X(x, K(\tau, \omega))$  is  $(\mathcal{F}, \mathcal{B}(\mathbb{R}))$ -measurable for every fixed  $x \in X$  and  $\tau \in \mathbb{R}$ , where  $\text{dist}_X$  is the Hausdorff semi-metric in  $X$ . In this case, we also say the family  $\{K(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\}$  is measurable in  $X$  with respect to  $\mathcal{F}$  in  $\Omega$ . Furthermore if the value  $K(\tau, \omega)$  is a closed nonempty subset of  $X$  for all  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ , then  $\{K(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\}$  is called a closed measurable set of  $X$  with respect to  $\mathcal{F}$  in  $\Omega$ .

In this article, the cocycle  $\varphi$  acting on  $X$  is further assumed to take its values into the non-initial space  $Y$  in the following sense:

(H1) For every fixed  $t > 0, \tau \in \mathbb{R}$  and  $\omega \in \Omega$ ,  $\varphi(t, \tau, \omega, \cdot) : X \rightarrow Y$ .

We use  $\mathfrak{D}$  to denote a collection of some families of nonempty subsets of  $X$  parametrized by  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$  such that

$$\begin{aligned} \mathfrak{D} = \{ & B = \{B(\tau, \omega) \in 2^X; B(\tau, \omega) \neq \emptyset, \tau \in \mathbb{R}, \omega \in \Omega\}; \\ & f_B \text{ satisfies certain conditions} \}. \end{aligned}$$

In particular, for  $B_1, B_2 \in \mathfrak{D}$  we say that  $B_1 = B_2$  if  $B_1(\tau, \omega) = B_2(\tau, \omega)$  for all  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ . The collection  $\mathfrak{D}$  is called inclusion closed if  $\tilde{B}(\tau, \omega) \subset B(\tau, \omega)$  and  $B \in \mathfrak{D}$  for every  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ , then  $\tilde{B} \in \mathfrak{D}$ .

**Definition 2.3.** Let  $\mathfrak{D}$  be a collection of some families of nonempty subsets of  $X$  and  $K = \{K(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$ . Then  $K$  is called a  $\mathfrak{D}$ -pullback absorbing set for a cocycle  $\varphi$  in  $X$  if for every  $\tau \in \mathbb{R}, \omega \in \Omega$  and  $B \in \mathfrak{D}$  there exists a absorbing time  $T = T(\tau, \omega, B) > 0$  such that

$$\varphi(t, \tau - t, \vartheta_{-t} \omega, B(\tau - t, \vartheta_{-t} \omega)) \subseteq K(\tau, \omega) \quad \text{for all } t \geq T.$$

If in addition  $K$  is measurable in  $X$  with respect to  $\mathcal{F}$  in  $\Omega$ , then  $K$  is said to a measurable pullback absorbing set for  $\varphi$ .

**Definition 2.4.** Let  $\mathfrak{D}$  be a collection of some families of nonempty subsets of  $X$ . A cocycle  $\varphi$  is said to be  $\mathfrak{D}$ -pullback asymptotically compact in  $X$  (resp. in  $Y$ ) if for each  $\tau \in \mathbb{R}, \omega \in \Omega$

$$\{\varphi(t_n, \tau - t_n, \vartheta_{-t_n} \omega, x_n)\} \text{ has a convergent subsequence in } X \text{ (resp. in } Y)$$

whenever  $t_n \rightarrow \infty$  and  $x_n \in B(\tau - t_n, \vartheta_{-t_n} \omega)$  with  $B = \{B(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$ .

**Definition 2.5.** Let  $\mathfrak{D}$  be a collection of some families of nonempty subsets of  $X$  and  $\mathcal{A} = \{\mathcal{A}(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$ .  $\mathcal{A}$  is called a  $\mathfrak{D}$ -pullback attractor for a cocycle  $\varphi$  in  $X$  (resp. in  $Y$ ) over  $\mathbb{R}$  and  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$  if

- (i)  $\mathcal{A}$  is measurable in  $X$  with respect to  $\mathcal{F}$ , and  $\mathcal{A}(\tau, \omega)$  is compact in  $X$  (resp. in  $Y$ ) for each  $\tau \in \mathbb{R}, \omega \in \Omega$ ;
- (ii)  $\mathcal{A}$  is invariant, that is, for each  $\tau \in \mathbb{R}, \omega \in \Omega$ ,

$$\varphi(t, \tau, \omega, \mathcal{A}(\tau, \omega)) = \mathcal{A}(\tau + t, \vartheta_t \omega), \quad \forall t \geq 0;$$

- (iii)  $\mathcal{A}$  attracts every element  $B = \{B(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$  in  $X$  (resp. in  $Y$ ), that is, for each  $\tau \in \mathbb{R}, \omega \in \Omega$ ,

$$\lim_{t \rightarrow +\infty} \text{dist}_X(\varphi(t, \tau - t, \vartheta_{-t} \omega, B(\tau - t, \vartheta_{-t} \omega)), \mathcal{A}(\tau, \omega)) = 0$$

$$\text{(resp. } \lim_{t \rightarrow +\infty} \text{dist}_Y(\varphi(t, \tau - t, \vartheta_{-t} \omega, B(\tau - t, \vartheta_{-t} \omega)), \mathcal{A}(\tau, \omega)) = 0).$$

**2.2. Existence of random attractors in a non-initial space.** This subsection is concerned with the existence of  $\mathfrak{D}$ -pullback attractor of the cocycle  $\varphi$  in the non-initial space  $Y$ . The continuity of  $\varphi$  in  $Y$  is not clear, and the embedding relation of  $X$  and  $Y$  is also unknown except that the following hypothesis (H2) holds:

- (H2) If  $\{x_n\}_n \subset X \cap Y$  such that  $x_n \rightarrow x$  in  $X$  and  $x_n \rightarrow y$  in  $Y$  respectively, then  $x = y$ .

**Theorem 2.6.** *Let  $\mathfrak{D}$  be a collection of some families of nonempty subsets of  $X$  which is inclusion closed. Let  $\varphi$  be a continuous cocycle on  $X$  over  $\mathbb{R}$  and  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$ . Assume that*

- (i)  $\varphi$  has a closed and measurable  $\mathfrak{D}$ -pullback bounded absorbing set  $K = \{K(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$  in  $X$ ;
- (ii)  $\varphi$  is  $\mathfrak{D}$ -pullback asymptotically compact in  $X$ .

Then the cocycle  $\varphi$  has a unique  $\mathfrak{D}$ -pullback attractor  $\mathcal{A}_X = \{\mathcal{A}_X(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$  in  $X$ , structured by

$$\mathcal{A}_X(\tau, \omega) = \overline{\bigcap_{s \geq 0} \bigcup_{t \geq s} \varphi(t, \tau - t, \vartheta_{-t} \omega, K(\tau - t, \vartheta_{-t} \omega))}^X, \quad \tau \in \mathbb{R}, \omega \in \Omega, \quad (2.1)$$

where the closure is taken in  $X$ .

If further (H1), (H2) hold and

- (iii)  $\varphi$  is  $\mathfrak{D}$ -pullback asymptotically compact in  $Y$ ,

Then the cocycle  $\varphi$  has a unique  $\mathfrak{D}$ -pullback attractor  $\mathcal{A}_Y = \{\mathcal{A}_Y(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\}$  in  $Y$ , given by

$$\mathcal{A}_Y(\tau, \omega) = \overline{\bigcap_{s > 0} \bigcup_{t \geq s} \varphi(t, \tau - t, \vartheta_{-t} \omega, K(\tau - t, \vartheta_{-t} \omega))}^Y, \quad \tau \in \mathbb{R}, \omega \in \Omega. \quad (2.2)$$

In addition, we have  $\mathcal{A}_Y = \mathcal{A}_X \subset X \cap Y$  in the sense of set inclusion, i.e., for each  $\tau \in \mathbb{R}, \omega \in \Omega$ ,  $\mathcal{A}_Y(\tau, \omega) = \mathcal{A}_X(\tau, \omega)$ .

*Proof.* The first result is well known and thus we are interested in the second result. Indeed, (2.2) makes sense by (H1) and  $\mathcal{A}_Y \neq \emptyset$  by the asymptotic compactness of the cocycle  $\varphi$  in  $Y$ . In the following, we show that  $\mathcal{A}_Y$  satisfies Definition 2.5 in the space  $Y$ .

**Step 1.** We claim that the set  $\mathcal{A}_Y$  is measurable in  $X$  (with respect to  $\mathcal{F}$  in  $\Omega$ ) and  $\mathcal{A}_Y \in \mathfrak{D}$  is invariant by proving that  $\mathcal{A}_Y = \mathcal{A}_X$  since  $\mathcal{A}_X$  is measurable (w.r.t  $\mathcal{F}$  in  $\Omega$ ) and  $\mathcal{A}_X \in \mathfrak{D}$  is invariant (the measurability of  $\mathcal{A}_X$  is proved by [19, Theorem 2.14]).

For each fixed  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ , taking  $x \in \mathcal{A}_X(\tau, \omega)$ , by (2.1), there exist two sequences  $t_n \rightarrow +\infty$  and  $x_n \in K(\tau - t_n, \vartheta_{-t_n}\omega)$  such that

$$\varphi(t_n, \tau - t_n, \vartheta_{-t_n}\omega, x_n) \xrightarrow[n \rightarrow \infty]{\|\cdot\|_X} x. \quad (2.3)$$

Since  $\varphi$  is  $\mathfrak{D}$ -asymptotically compact in  $Y$ , then there is a  $y \in Y$  such that up to a subsequence,

$$\varphi(t_n, \tau - t_n, \vartheta_{-t_n}\omega, x_n) \xrightarrow[n \rightarrow \infty]{\|\cdot\|_Y} y. \quad (2.4)$$

It implies from (2.2) that  $y \in \mathcal{A}_Y(\tau, \omega)$ . Then by (H2), along with (2.3) and (2.4), we have  $x = y \in \mathcal{A}_X(\tau, \omega)$  and thus  $\mathcal{A}_X(\tau, \omega) \subseteq \mathcal{A}_Y(\tau, \omega)$  for every fixed  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ . The inverse inclusion can be proved in the same way then we omit it here. Thus  $\mathcal{A}_X = \mathcal{A}_Y$  as required.

**noindentStep 2.** We prove the attraction of  $\mathcal{A}_Y$  in  $Y$  by a contradiction argument. Indeed, if there exist  $\delta > 0$ ,  $x_n \in B(\tau - t_n, \vartheta_{-t_n}\omega)$  with  $B \in \mathfrak{D}$  and  $t_n \rightarrow +\infty$  such that

$$\text{dist}_Y \left( \varphi(t_n, \tau - t_n, \vartheta_{-t_n}\omega, x_n), \mathcal{A}_Y(\tau, \omega) \right) \geq \delta. \quad (2.5)$$

By the asymptotic compactness of  $\varphi$  in  $Y$ , there exists  $y_0 \in Y$  such that up to a subsequence,

$$\varphi(t_n, \tau - t_n, \vartheta_{-t_n}\omega, x_n) \xrightarrow[n \rightarrow \infty]{\|\cdot\|_Y} y_0. \quad (2.6)$$

On the other hand, by condition (i), there exists a large time  $T > 0$  such that

$$\begin{aligned} y_n &= \varphi(T, \tau - t_n, \vartheta_{-t_n}\omega, x_n) \\ &= \varphi(T, (\tau - t_n + T) - T, \vartheta_{-T}\vartheta_{-(t_n-T)}\omega, x_n) \\ &\in K(\tau - t_n + T, \vartheta_{-(t_n-T)}\omega). \end{aligned} \quad (2.7)$$

Then by the cocycle property in Definition 2.1, with (2.6) and (2.7), we infer that as  $t_n \rightarrow \infty$ ,

$$\varphi(t_n, \tau - t_n, \vartheta_{-t_n}\omega, x_n) = \varphi(t_n - T, \tau - (t_n - T), \vartheta_{-(t_n-T)}\omega, y_n) \rightarrow y_0 \quad \text{in } Y.$$

Therefore by (2.2),  $y_0 \in \mathcal{A}_Y(\tau, \omega)$ . This implies

$$\text{dist}_Y \left( \varphi(t_n, \tau - t_n, \vartheta_{-t_n}\omega, x_n), \mathcal{A}_Y(\tau, \omega) \right) \rightarrow 0 \quad (2.8)$$

as  $t_n \rightarrow \infty$ , which is a contradiction to (2.5).

**Step 3.** It remains to prove the compactness of  $\mathcal{A}_Y$  in  $Y$ . Let  $\{y_n\}_{n=1}^\infty$  be a sequence in  $\mathcal{A}_Y(\tau, \omega)$ . By the invariance of  $\mathcal{A}_Y(\tau, \omega)$  which is proved in Step 1, we have

$$\varphi(t, \tau - t, \vartheta_{-t}\omega, \mathcal{A}_Y(\tau - t, \vartheta_{-t}\omega)) = \mathcal{A}_Y(\tau, \omega).$$

Then it follows that there is a sequence  $\{z_n\}_{n=1}^\infty$  with  $z_n \in \mathcal{A}_Y(\tau - t_n, \vartheta_{-t_n}\omega)$  such that for every  $n \in \mathbb{Z}^+$ ,

$$y_n = \varphi(t_n, \tau - t_n, \vartheta_{-t_n}\omega, z_n). \quad (2.9)$$

Note that  $\mathcal{A}_Y \in \mathfrak{D}$ . Then by the asymptotic compactness of  $\varphi$  in  $Y$ ,  $\{y_n\}$  has a convergence subsequence in  $Y$ , *i.e.*, there is a  $y_0 \in Y$  such that

$$\lim_{n \rightarrow \infty} y_n = y_0 \quad \text{in } Y.$$

But  $\mathcal{A}_Y(\tau, \omega)$  is closed in  $Y$ , so  $y_0 \in \mathcal{A}_Y(\tau, \omega)$ .

The uniqueness is easily followed by the attraction property of  $\varphi$  and  $\mathcal{A}_Y \in \mathfrak{D}$ . This completes the total proofs.  $\square$

**2.3. Upper semi-continuity of random attractors in a non-initial space.**

Assume that (H1) and (H2) hold. Given the indexed set  $I \subset \mathbb{R}$ , for every  $\varepsilon \in I$ , we use  $\mathfrak{D}_\varepsilon$  to denote a collection of some families of nonempty subsets of  $X$ . Let  $\varphi_\varepsilon (\varepsilon \in I)$  be a continuous cocycle on  $X$  over  $\mathbb{R}$  and  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$ . We now consider the upper semi-continuous of pullback attractors of a family of cocycle  $\varphi_\varepsilon$  in  $Y$ .

Suppose first that for every  $t \in \mathbb{R}^+, \tau \in \mathbb{R}, \omega \in \Omega, \varepsilon_n, \varepsilon_0 \in I$  with  $\varepsilon_n \rightarrow \varepsilon_0$ , and  $x_n, x \in X$  with  $x_n \rightarrow x$ , there holds

$$\lim_{n \rightarrow \infty} \varphi_{\varepsilon_n}(t, \tau, \omega, x_n) = \varphi_{\varepsilon_0}(t, \tau, \omega, x) \quad \text{in } X. \tag{2.10}$$

Suppose second that there exists a map  $R_{\varepsilon_0} : \mathbb{R} \times \Omega \rightarrow \mathbb{R}^+$  such that the family

$$B_0 = \{B_0(\tau, \omega) = \{x \in X; \|x\|_X \leq R_{\varepsilon_0}(\tau, \omega)\} : \tau \in \mathbb{R}, \omega \in \Omega\} \tag{2.11}$$

belongs to  $\mathfrak{D}_{\varepsilon_0}$ . And further for every  $\varepsilon \in I$ ,  $\varphi_\varepsilon$  has  $\mathfrak{D}_\varepsilon$ -pullback attractor  $\mathcal{A}_\varepsilon \in \mathfrak{D}_\varepsilon$  in  $X \cap Y$  and a closed and measurable  $\mathfrak{D}_\varepsilon$ -pullback absorbing set  $K_\varepsilon \in \mathfrak{D}_\varepsilon$  in  $X$  such that for every  $\tau \in \mathbb{R}, \omega \in \Omega$ ,

$$\limsup_{\varepsilon \rightarrow \varepsilon_0} \|K_\varepsilon(\tau, \omega)\| \leq R_{\varepsilon_0}(\tau, \omega), \tag{2.12}$$

where  $\|S\|_X = \sup_{x \in S} \|x\|_X$  for a set  $S$ . We finally assume that for every  $\tau \in \mathbb{R}, \omega \in \Omega$ ,

$$\cup_{\varepsilon \in I} \mathcal{A}_\varepsilon(\tau, \omega) \text{ is precompact in } X, \text{ and} \tag{2.13}$$

$$\cup_{\varepsilon \in I} \mathcal{A}_\varepsilon(\tau, \omega) \text{ is precompact in } Y. \tag{2.14}$$

Then we have the upper semi-continuity in  $Y$ .

**Theorem 2.7.** *If (2.10)–(2.13) hold, then for each  $\tau \in \mathbb{R}, \omega \in \Omega$ ,*

$$\lim_{\varepsilon \rightarrow \varepsilon_0} \text{dist}_X(\mathcal{A}_\varepsilon(\tau, \omega), \mathcal{A}_{\varepsilon_0}(\tau, \omega)) = 0.$$

*If further (H1)–(H2) hold and conditions (2.10)–(2.14) are satisfied. Then for each  $\tau \in \mathbb{R}, \omega \in \Omega$ ,*

$$\lim_{\varepsilon \rightarrow \varepsilon_0} \text{dist}_Y(\mathcal{A}_\varepsilon(\tau, \omega), \mathcal{A}_{\varepsilon_0}(\tau, \omega)) = 0.$$

*Proof.* If (2.10)–(2.13) hold, the upper-continuous in  $X$  is proved in [18]. We only need to prove the upper semi-continuity of  $\mathcal{A}_\varepsilon$  at  $\varepsilon = \varepsilon_0$  in  $Y$ .

Suppose that there exist  $\delta > 0, \varepsilon_n \rightarrow \varepsilon_0$  and a sequence  $\{y_n\}$  with  $y_n \in \mathcal{A}_{\varepsilon_n}(\tau, \omega)$  such that for all  $n \in \mathbb{N}$ ,

$$\lim_{\varepsilon \rightarrow \varepsilon_0} \text{dist}_Y(y_n, \mathcal{A}_{\varepsilon_0}(\tau, \omega)) \geq 2\delta. \tag{2.15}$$

Note that  $y_n \in \mathcal{A}_{\varepsilon_n}(\tau, \omega) \subset \mathbb{A}(\tau, \omega) = \cup_{\varepsilon \in I} \mathcal{A}_\varepsilon(\tau, \omega)$ . Then by (2.13) and (2.14) and using (H2), there exists a  $y_0 \in X \cap Y$  such that up to a subsequence,

$$\lim_{n \rightarrow \infty} y_n = y_0 \quad \text{in } X \cap Y. \tag{2.16}$$

It suffices to show that  $\text{dist}_Y(y_0, \mathcal{A}_{\varepsilon_0}(\tau, \omega)) < \delta$ . Given a positive sequence  $\{t_m\}$  with  $t_m \uparrow +\infty$  as  $m \rightarrow \infty$ . For  $m = 1$ , by the invariance of  $\mathcal{A}_{\varepsilon_n}$ , there exists a sequence  $\{y_{1,n}\}$  with  $y_{1,n} \in \mathcal{A}_{\varepsilon_n}(\tau - t_1, \vartheta_{-t_1}\omega)$  such that

$$y_n = \varphi_{\varepsilon_n}(t_1, \tau - t_1, \vartheta_{-t_1}\omega, y_{1,n}), \tag{2.17}$$

for each  $n \in \mathbb{N}$ . Since  $y_{1,n} \in \mathcal{A}_{\varepsilon_n}(\tau - t_1, \vartheta_{-t_1}\omega) \subset \mathbb{A}(\tau - t_1, \vartheta_{-t_1}\omega)$ , then by (2.13) and (2.14) and using (H2), there is a  $z_1 \in X \cap Y$  and a subsequence of  $\{y_{1,n}\}$  such that

$$\lim_{n \rightarrow \infty} y_{1,n} = z_1 \quad \text{in } X \cap Y. \quad (2.18)$$

Then (2.10) and (2.18) imply

$$\lim_{n \rightarrow \infty} \varphi_{\varepsilon_n}(t_1, \tau - t_1, \vartheta_{-t_1}\omega, y_{1,n}) = \varphi_{\varepsilon_0}(t_1, \tau - t_1, \vartheta_{-t_1}\omega, z_1) \quad \text{in } X. \quad (2.19)$$

Thus by combining (2.16), (2.17) and (2.19) we obtain

$$y_0 = \varphi_{\varepsilon_0}(t_1, \tau - t_1, \vartheta_{-t_1}\omega, z_1). \quad (2.20)$$

Note that  $K_{\varepsilon_n}$  as a  $\mathfrak{D}_{\varepsilon_n}$ -pullback absorbing set in  $X$  absorbs  $\mathcal{A}_{\varepsilon_n} \in \mathfrak{D}_{\varepsilon_n}$ , *i.e.*, there is a  $T = T(\tau, \omega, \mathcal{A}_{\varepsilon_n})$  such that for all  $t \geq T$ ,

$$\varphi(t, \tau - t, \vartheta_{-t}\omega, \mathcal{A}_{\varepsilon_n}(\tau - t, \vartheta_{-t}\omega)) \subseteq K_{\varepsilon_n}(\tau, \omega). \quad (2.21)$$

Then by the invariance of  $\mathcal{A}_{\varepsilon_n}(\tau, \omega)$ , it follows from (2.21) that

$$\mathcal{A}_{\varepsilon_n}(\tau, \omega) \subseteq K_{\varepsilon_n}(\tau, \omega). \quad (2.22)$$

Since  $y_{1,n} \in \mathcal{A}_{\varepsilon_n}(\tau - t_1, \vartheta_{-t_1}\omega) \subseteq K_{\varepsilon_n}(\tau - t_1, \vartheta_{-t_1}\omega)$ , then by (2.18) and (2.12), we obtain

$$\begin{aligned} \|z_1\|_X &= \limsup_{n \rightarrow \infty} \|y_{1,n}\|_X \\ &\leq \limsup_{n \rightarrow \infty} \|K_{\varepsilon_n}(\tau - t_1, \vartheta_{-t_1}\omega)\|_X \\ &\leq R_{\varepsilon_0}(\tau - t_1, \vartheta_{-t_1}\omega). \end{aligned} \quad (2.23)$$

By an induction argument, for each  $m \geq 1$ , there is  $z_m \in X \cap Y$  such that for all  $m \in \mathbb{N}$ ,

$$y_0 = \varphi_{\varepsilon_0}(t_m, \tau - t_m, \vartheta_{-t_m}\omega, z_m), \quad (2.24)$$

$$\|z_m\|_X \leq R_{\varepsilon_0}(\tau - t_m, \vartheta_{-t_m}\omega). \quad (2.25)$$

Thus from (2.11) and (2.25), for each  $m \in \mathbb{N}$ ,

$$z_m \in B_0(\tau - t_m, \vartheta_{-t_m}\omega). \quad (2.26)$$

We consider that the pullback attractor  $\mathcal{A}_{\varepsilon_0}$  attracts every element in  $\mathfrak{D}_{\varepsilon_0}$  in the topology of  $Y$  and connection with  $B_0 \in \mathfrak{D}_{\varepsilon_0}$ . Then  $\mathcal{A}_{\varepsilon_0}$  attracts  $B_0$  in the topology of  $Y$ . Therefore by (2.24) and (2.26) we have

$$\text{dist}_Y(y_0, \mathcal{A}_{\varepsilon_0}(\tau, \omega)) = \text{dist}_Y(\varphi_{\varepsilon_0}(t_m, \tau - t_m, \vartheta_{-t_m}\omega, z_m), \mathcal{A}_{\varepsilon_0}(\tau, \omega)) \rightarrow 0, \quad (2.27)$$

as  $m \rightarrow \infty$ . That is to say,  $\text{dist}_Y(y_0, \mathcal{A}_{\varepsilon_0}(\tau, \omega)) = \inf_{u \in \mathcal{A}_{\varepsilon_0}(\tau, \omega)} \|y_0 - u\|_Y = 0$  and thus we can choose a  $u_0 \in \mathcal{A}_{\varepsilon_0}(\tau, \omega)$  such that

$$\|y_0 - u_0\|_Y \leq \delta. \quad (2.28)$$

Therefore, by (2.16) and (2.28), as  $n \rightarrow \infty$ ,

$$\text{dist}_Y(y_n, \mathcal{A}_{\varepsilon_0}(\tau, \omega)) \leq \|y_n - u_0\|_Y \leq \|y_n - y_0\|_Y + \delta \rightarrow \delta,$$

which is a contradiction to (2.15). This concludes the proof.  $\square$

We next consider a special case of Theorem 2.7, in which case the limit cocycle  $\varphi_{\varepsilon_0}$  is independent of the parameter  $\omega \in \Omega$ . We call such  $\varphi_{\varepsilon_0}$  a deterministic non-autonomous cocycle on  $X$  over  $\mathbb{R}$ . That is to say,  $\varphi_{\varepsilon_0}$  satisfies the following two statements:

- (i)  $\varphi_0(0, \tau, \cdot)$  is the identity on  $X$ ;



(ii)  $\varphi_0(t + s, \tau, \cdot) = \varphi_0(t, \tau + s, \cdot) \circ \varphi_0(s, \tau, \cdot)$ .

If  $\varphi_0(t, \tau, \cdot) : X \rightarrow X$  is continuous for every  $t \in \mathbb{R}^+$  and  $\tau \in \mathbb{R}$ , then  $\varphi_{\varepsilon_0}$  is called a deterministic non-autonomous continuous cocycle on  $X$  over  $\mathbb{R}$ .

Let  $\mathfrak{D}_{\varepsilon_0}$  be a collection of some families of nonempty subsets of  $X$  denoted by

$$\mathfrak{D}_{\varepsilon_0} = \{B = \{B(\tau) \neq \emptyset; B(\tau) \in 2^X, \tau \in \mathbb{R}\}; f_B \text{ satisfies certain conditions}\}.$$

A family  $\mathcal{A}_{\varepsilon_0} \in \mathfrak{D}_{\varepsilon_0}$  is called a  $\mathfrak{D}_{\varepsilon_0}$ -pullback attractor of  $\varphi_{\varepsilon_0}$  in  $X$  (resp. in  $Y$ ) if

- (i) for each  $\tau \in \mathbb{R}$ ,  $\mathcal{A}_{\varepsilon_0}(\tau)$  is compact in  $X$  (resp. of  $Y$ );
- (ii)  $\varphi_{\varepsilon_0}(t, \tau, \mathcal{A}_{\varepsilon_0}(\tau)) = \mathcal{A}_{\varepsilon_0}(\tau + t)$  for all  $t \in \mathbb{R}^+$  and  $\tau \in \mathbb{R}$ ;
- (iii)  $\mathcal{A}_{\varepsilon_0}$  pullback attracts every element of  $\mathfrak{D}_{\varepsilon_0}$  under the Hausdorff semi-metric of  $X$  (resp. of  $Y$ ).

To obtain the convergence at  $\varepsilon = \varepsilon_0$  in  $Y$ , we make some modifications of the conditions used in random case. We assume that for every  $t \in \mathbb{R}^+, \tau \in \mathbb{R}, \omega \in \Omega, \varepsilon_n \in I$  with  $\varepsilon_n \rightarrow \varepsilon_0$ , and  $x_n, x \in X$  with  $x_n \rightarrow x$ , it holds

$$\lim_{n \rightarrow \infty} \varphi_{\varepsilon_n}(t, \tau, \omega, x_n) = \varphi_{\varepsilon_0}(t, \tau, x) \text{ in } X. \tag{2.29}$$

There exists a map  $R'_{\varepsilon_0} : \mathbb{R} \rightarrow \mathbb{R}$  such that the family

$$B'_0 = \{B'_0(\tau) = \{x \in X; \|x\|_X \leq R'_{\varepsilon_0}(\tau)\}; \tau \in \mathbb{R}\} \text{ belongs to } \mathfrak{D}_{\varepsilon_0}. \tag{2.30}$$

For every  $\varepsilon \in I$ ,  $\varphi_\varepsilon$  has a closed measurable  $\mathfrak{D}_\varepsilon$ -pullback absorbing set  $K_\varepsilon = \{K_\varepsilon(\tau, \omega); \omega \in \Omega\} \in \mathfrak{D}_\varepsilon$  in  $X$  such that for every  $\tau \in \mathbb{R}, \omega \in \Omega$ ,

$$\limsup_{\varepsilon \rightarrow \varepsilon_0} \|K_\varepsilon(\tau, \omega)\| \leq R'_{\varepsilon_0}(\tau). \tag{2.31}$$

Then we have the following, which can be proved by a similar argument as Theorem 2.7 and so the proof is omitted.

**Theorem 2.8.** *If (2.13) and (2.29)-(2.31) hold, then for each  $\tau \in \mathbb{R}, \omega \in \Omega$ ,*

$$\lim_{\varepsilon \rightarrow \varepsilon_0} \text{dist}_X(\mathcal{A}_\varepsilon(\tau, \omega), \mathcal{A}_{\varepsilon_0}(\tau)) = 0.$$

*If further (H1)-(H2) hold and conditions (2.14) and (2.29)-(2.31) are satisfied, then for each  $\tau \in \mathbb{R}, \omega \in \Omega$ ,*

$$\lim_{\varepsilon \rightarrow \varepsilon_0} \text{dist}_Y(\mathcal{A}_\varepsilon(\tau, \omega), \mathcal{A}_{\varepsilon_0}(\tau)) = 0. \tag{2.32}$$

### 3. NON-AUTONOMOUS REACTION-DIFFUSION EQUATION ON $\mathbb{R}^N$ WITH MULTIPLICATIVE NOISE

For the non-autonomous reaction-diffusion equations (1.1) and (1.2), the nonlinearity  $f(x, s)$  satisfies almost the same assumptions as in [18], i.e., for  $x \in \mathbb{R}^N$  and  $s \in \mathbb{R}$ ,

$$f(x, s)s \leq -\alpha_1 |s|^p + \psi_1(x), \tag{3.1}$$

$$|f(x, s)| \leq \alpha_2 |s|^{p-1} + \psi_2(x), \tag{3.2}$$

$$\frac{\partial f}{\partial s} f(x, s) \leq \alpha_3, \tag{3.3}$$

$$\left| \frac{\partial f}{\partial x} f(x, s) \right| \leq \psi_3(x), \tag{3.4}$$

where  $\alpha_i > 0$  ( $i = 1, 2, 3$ ) are determined constants,  $p \geq 2$ ,  $\psi_1 \in L^1(\mathbb{R}^N) \cap L^{p/2}(\mathbb{R}^N)$ ,  $\psi_2 \in L^2(\mathbb{R}^N)$  and  $\psi_3 \in L^2(\mathbb{R}^N)$ . And the non-autonomous term  $g$  satisfies that for every  $\tau \in \mathbb{R}$  and some  $\delta \in [0, \lambda)$ ,

$$\int_{-\infty}^{\tau} e^{\delta s} \|g(s, \cdot)\|_{L^2(\mathbb{R}^N)}^2 ds < +\infty, \quad (3.5)$$

where  $\lambda$  is as in (1.1), which implies that

$$\int_{-\infty}^0 e^{\delta s} \|g(s + \tau, \cdot)\|_{L^2(\mathbb{R}^N)}^2 ds < +\infty, \quad g \in L^2_{Loc}(\mathbb{R}, L^2(\mathbb{R}^N)). \quad (3.6)$$

For the probability space  $(\Omega, \mathcal{F}, P)$ , we write  $\Omega = \{\omega \in C(\mathbb{R}, \mathbb{R}); \omega(0) = 0\}$ . Let  $\mathcal{F}$  be the Borel  $\sigma$ -algebra induced by the compact-open topology of  $\Omega$  and  $P$  be the corresponding Wiener measure on  $(\Omega, \mathcal{F})$ . We define a shift operator  $\vartheta$  on  $\Omega$  by

$$\vartheta_t \omega(s) = \omega(s + t) - \omega(t), \quad \text{for every } \omega \in \Omega, t, s \in \mathbb{R}.$$

Then  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$  which is the model for random noise is called a metric dynamical system. Furthermore  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$  is ergodic with respect to  $\{\vartheta_t\}_{t \in \mathbb{R}}$  under  $P$ , which means that every  $\vartheta_t$ -invariant set has measure zero or one,  $t \in \mathbb{R}$ . By the law of the iterated logarithm (see [5]), we know that

$$\frac{\omega(t)}{t} \rightarrow 0, \quad \text{as } |t| \rightarrow +\infty. \quad (3.7)$$

For  $\omega \in \Omega$ , put  $z(t, \omega) = z_\varepsilon(t, \omega) = e^{-\varepsilon \omega(t)}$ . Then we have  $dz + \varepsilon z \circ d\omega(t) = 0$ . Put  $v(t, \tau, \omega, v_0) = z(t, \omega)u(t, \tau, \omega, u_0)$ , where  $u$  is a solution of problem (1.1) and (1.2) with the initial value  $u_0$ . Then  $v$  solves the non-autonomous equation

$$\frac{dv}{dt} + \lambda v - \Delta v = z(t, \omega)f(x, z^{-1}(t, \omega)v) + z(t, \omega)g(t, x), \quad (3.8)$$

with the initial value

$$v(\tau, x) = v_0(x) = z(\tau, \omega)u_0(x). \quad (3.9)$$

As pointed out in [18], for every  $v_0 \in L^2(\mathbb{R}^N)$  we may show that the problem (3.8)-(3.9) possesses a continuous solution  $v(\cdot)$  on  $L^2(\mathbb{R}^N)$  such that  $v(\cdot) \in C([\tau, +\infty), L^2(\mathbb{R}^N)) \cap L^2_{loc}((\tau, +\infty), H^1(\mathbb{R}^N)) \cap L^p_{loc}((\tau, +\infty), L^p(\mathbb{R}^N))$ . In addition, the solution  $v$  is  $(\mathcal{F}, \mathcal{B}(L^2(\mathbb{R}^N)))$ -measurable in  $\Omega$ . Then formally  $u(\cdot) = z^{-1}(\cdot, \omega)v(\cdot)$  is a  $(\mathcal{F}, \mathcal{B}(L^2(\mathbb{R}^N)))$ -measurable and continuous solution of problem (1.1) and (1.2) on  $L^2(\mathbb{R}^N)$  with  $u_0 = z^{-1}(\tau, \omega)v_0$ .

Define the mapping  $\varphi : \mathbb{R}^+ \times \mathbb{R} \times \Omega \times L^2(\mathbb{R}^N) \rightarrow L^2(\mathbb{R}^N)$  such that

$$\begin{aligned} \varphi(t, \tau, \omega, u_0) &= u(t + \tau, \tau, \vartheta_{-\tau} \omega, u_0) \\ &= z^{-1}(t + \tau, \vartheta_{-\tau} \omega)v(t + \tau, \tau, \vartheta_{-\tau} \omega, z(\tau, \vartheta_{-\tau} \omega)u_0), \end{aligned} \quad (3.10)$$

where  $u_0 = u_\tau \in L^2(\mathbb{R}^N)$  and  $t \in \mathbb{R}^+, \tau \in \mathbb{R}, \omega \in \Omega$ . Then by the measurability and continuity of  $v$  in  $v_0 \in L^2(\mathbb{R}^N)$  and  $t \in \mathbb{R}^+$ , we see that the mappings  $\varphi$  is  $(\mathcal{B}(\mathbb{R}^+) \times \mathcal{F} \times \mathcal{B}(L^2(\mathbb{R}^N))) \rightarrow \mathcal{B}(L^2(\mathbb{R}^N))$ -measurable. That is to say, the mappings  $\varphi$  defined by (3.10) is a continuous cocycle on  $L^2(\mathbb{R}^N)$  over  $\mathbb{R}$  and  $(\Omega, \mathcal{F}, P, \{\vartheta_t\}_{t \in \mathbb{R}})$ . Furthermore, from (3.10) we infer that

$$\begin{aligned} \varphi(t, \tau - t, \vartheta_{-t} \omega, u_0) &= u(\tau, \tau - t, \vartheta_{-\tau} \omega, u_0) \\ &= z(-\tau, \omega)v(\tau, \tau - t, \vartheta_{-\tau} \omega, z(\tau - t, \vartheta_{-\tau} \omega)u_0), \end{aligned} \quad (3.11)$$

where  $u_0 = u_{\tau-t}$ .

We define the collection  $\mathfrak{D}$  as

$$\mathfrak{D} = \{B = \{B(\tau, \omega) \subseteq L^2(\mathbb{R}^N); \tau \in \mathbb{R}, \omega \in \Omega\}; \lim_{t \rightarrow +\infty} e^{-\lambda t} z^2(-t, \omega) \|B(\tau - t, \vartheta_{-t}\omega)\|^2 = 0 \text{ for } \tau \in \mathbb{R}, \omega \in \Omega\} \tag{3.12}$$

where  $\|B\| = \sup_{v \in B} \|v\|_{L^2(\mathbb{R}^N)}$  and  $\lambda$  is in (3.8). Note that this collection  $\mathfrak{D}$  is much larger than the collection defined by [18]. That is to say, the collection  $\mathfrak{D}$  defined above includes all tempered families of bounded nonempty subsets of  $L^2(\mathbb{R}^N)$ .

We can show that all the results in [18] hold for the collection  $\mathfrak{D}$  defined by (3.12). Thus, the existence and upper semi-continuity of  $\mathfrak{D}$ -pullback attractors for the cocycle  $\varphi_\varepsilon$  in the initial space  $L^2(\mathbb{R}^N)$  have been proved by [18].

**Theorem 3.1** ([18]). *Assume that (3.1)-(3.5) hold. Then the cocycle  $\varphi_\varepsilon$  has a unique  $\mathfrak{D}$ -pullback attractor  $\mathcal{A}_\varepsilon = \{\mathcal{A}_\varepsilon(\tau, \omega), \tau \in \mathbb{R}, \omega \in \Omega\}$  in  $L^2(\mathbb{R}^N)$ , given by*

$$\mathcal{A}_\varepsilon(\tau, \omega) = \overline{\bigcap_{s \geq 0} \bigcup_{t \geq s} \varphi(t, \tau - t, \vartheta_{-t}\omega, K_\varepsilon(\tau - t, \vartheta_{-t}\omega))}^{L^2(\mathbb{R}^N)}, \tag{3.13}$$

for  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ , where  $K_\varepsilon$  is a closed and measurable  $\mathfrak{D}$ -pullback bounded absorbing set of  $\varphi_\varepsilon$  in  $L^2(\mathbb{R}^N)$ . Furthermore,  $\mathcal{A}_\varepsilon$  is upper semi-continuous in  $L^2(\mathbb{R}^N)$  at  $\varepsilon = 0$ .

Note that in most cases, we write  $v$  (resp.  $\varphi$  and  $z$ ) as the abbreviation of  $v_\varepsilon$  (resp.  $\varphi_\varepsilon$  and  $z_\varepsilon$ ). Next, we consider some applications of Theorems 2.6–2.8 to the non-autonomous stochastic reaction-diffusions (1.1) and (1.2). We emphasize that the result of Theorem 3.1 holds in the smooth functions space  $H^1(\mathbb{R}^N)$ . In particular, we prove the upper semi-continuity of the obtained attractors  $\mathcal{A}_\varepsilon$  in  $H^1(\mathbb{R}^N)$ .

#### 4. EXISTENCE OF PULLBACK ATTRACTOR IN $H^1(\mathbb{R}^N)$

In this section, we apply Theorem 2.6 to prove the existence of  $\mathfrak{D}$ -pullback attractors in  $H^1(\mathbb{R}^N)$  for the cocycle defined in (3.10). To this end, we need to prove the uniform smallness of solutions outside a large ball under  $H^1(\mathbb{R}^N)$  norm (see Proposition 4.4), and in the bounded ball of  $\mathbb{R}^N$  we will prove the asymptotic compactness of solutions by space-splitting and function-truncation techniques (see Proposition 4.5 and Lemma 4.6).

We consider that  $e^{-|\omega(s)|} \leq z(s, \omega) = e^{-\varepsilon\omega(s)} \leq e^{|\omega(s)|}$  for  $\varepsilon \in (0, 1]$ , and that  $\omega(s)$  is continuous function in  $s$ . Then there exist two positive random constants  $E = E(\omega)$  and  $F = F(\omega)$  depending only on  $\omega$  such that for all  $s \in [-2, 0]$  and  $\varepsilon \in (0, 1]$ .

$$0 < E \leq z(s, \omega) \leq F, \quad \omega \in \Omega. \tag{4.1}$$

Hereafter, we denote by  $\|\cdot\|, \|\cdot\|_p$  and  $\|\cdot\|_{H^1}$  the norms in  $L^2(\mathbb{R}^N), L^p(\mathbb{R}^N)$  and  $H^1(\mathbb{R}^N)$ , respectively. The numbers  $c$  and  $C(\tau, \omega)$  are two generic positive constants which may have different values in different places even in the same line. The first one depends only on  $p, \lambda$  and  $\alpha_i (i = 1, 2, 3)$ , and the second one depends on  $\tau, \omega, p, \lambda$  and  $\alpha_i (i = 1, 2, 3)$ . We always assume  $p > 2$  in the following discussions.

**4.1.  $H^1$ -tail estimate of solutions.** This can be achieved by a series of previously proved lemmas. First we stress that [18, Lemma 5.1] holds on the compact interval  $[\tau - 1, \tau]$ , which is necessary for us to estimate of the tail of solutions in  $H^1(\mathbb{R}^N)$ .

**Lemma 4.1.** *Assume that (3.1) and (3.3)-(3.5) hold. Let  $\tau \in \mathbb{R}, \omega \in \Omega$ ,  $B = \{B(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$  and  $u_0 \in B(\tau - t, \vartheta_{-t}\omega)$ . Then there exists a constant  $T = T(\tau, \omega, B) \geq 2$  such that for all  $t \geq T$ , the solution  $v$  of problem (3.8) and (3.9) satisfies that for every  $\zeta \in [\tau - 1, \tau]$ ,*

$$\|v(\zeta, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_{H^1(\mathbb{R}^N)}^2 \leq L_1(\tau, \omega, \varepsilon), \quad (4.2)$$

$$\int_{\tau-2}^{\tau} \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_p^p ds \leq L_1(\tau, \omega, \varepsilon), \quad (4.3)$$

where  $v_0 = z(\tau - t, \vartheta_{-\tau}\omega)u_0$  and  $L_1(\tau, \omega, \varepsilon) =: cz^{-2}(-\tau, \omega) \int_{-\infty}^0 e^{\lambda s} z^2(s, \omega) (\|g(s + \tau, \cdot)\|^2 + 1) ds$ .

The proof of the above lemma is similar to that of [18, Lemma 5.1], with a small modification, using  $\zeta \in [\tau - 1, \tau]$  instead of  $\tau$ .

**Lemma 4.2.** *Assume that (3.1) and (3.3)-(3.5) hold. Let  $\tau \in \mathbb{R}, \omega \in \Omega$  and  $B = \{B(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$ . Then for every  $\eta > 0$ , there exist two constants  $T = T(\tau, \omega, \eta, B) \geq 2$  and  $R = R(\tau, \omega, \eta) > 1$  such that the weak solution  $v$  of (3.8) and (3.9) satisfies that for all  $t \geq T$  and  $k \geq R$ ,*

$$\begin{aligned} & \int_{|x| \geq k} |v(\tau, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)|^2 dx \\ & + \int_{\tau-1}^{\tau} \int_{|x| \geq k} |\nabla v(s, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)|^2 dx ds \leq \eta, \end{aligned}$$

where  $u_0 \in B(\tau - t, \vartheta_{-t}\omega)$ ,  $R$  and  $T$  are independent of  $\varepsilon$ .

The proof of the above lemma is a simple modification of the proof of [18, Lemma 5.5].

**Lemma 4.3.** *Assume that (3.1) and (3.3)-(3.5) hold. Let  $\tau \in \mathbb{R}, \omega \in \Omega$  and  $B = \{B(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$ . Then there exists  $T = T(\tau, \omega, B) \geq 2$  such that the weak solution  $v$  of problem (3.8)-(3.9) satisfies that for all  $t \geq T$ ,*

$$\int_{\tau-1}^{\tau} \|v(s, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)\|_{2p-2}^{2p-2} ds \leq L_2(\tau, \omega, \varepsilon), \quad (4.4)$$

$$\int_{\tau-1}^{\tau} \|v_s(s, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)\|^2 ds \leq L_2(\tau, \omega, \varepsilon), \quad (4.5)$$

where  $v_s = \frac{\partial v}{\partial s}$ ,  $u_0 \in B(\tau - t, \vartheta_{-t}\omega)$  and

$$L_2(\tau, \omega, \varepsilon) =: C(\tau, \omega) \int_{-\infty}^0 e^{\lambda s} (z^2(s, \omega) + z^p(s, \omega)) (\|g(s + \tau, \cdot)\|^2 + 1) ds. \quad (4.6)$$

*Proof.* In the sequel, we always regard  $v$  as a solution at the time  $t$  with the initial value  $v_0 = v_{\tau-t}$  at the initial time  $\tau - t$ . We multiply (3.8) by  $|v|^{p-2}v$  and then integrate over  $\mathbb{R}^N$  to yield that

$$\begin{aligned} & \frac{1}{p} \frac{d}{dt} \|v\|_p^p + \lambda \|v\|_p^p \\ & \leq z(t, \omega) \int_{\mathbb{R}^N} f(x, z^{-1}v) |v|^{p-2}v dx + z(t, \omega) \int_{\mathbb{R}^N} |v|^{p-2}v g dx. \end{aligned} \quad (4.7)$$

By using (3.1), we see that

$$\begin{aligned} & z(t, \omega) \int_{\mathbb{R}^N} f(x, z^{-1}v) |v|^{p-2} v \, dx \\ & \leq -\alpha_1 z^{2-p}(t, \omega) \int_{\mathbb{R}^N} |v|^{2p-2} \, dx + z^2(t, \omega) \int_{\mathbb{R}^N} \psi_1(x) |v|^{p-2} \, dx \\ & \leq -\alpha_1 z^{2-p}(t, \omega) \int_{\mathbb{R}^N} |v|^{2p-2} \, dx + \frac{\lambda}{2} \|v\|_p^p + \left(\frac{2}{\lambda}\right)^{-\frac{p-2}{2}} z^p(t, \omega) \|\psi_1\|_{p/2}^{p/2}, \end{aligned} \quad (4.8)$$

where the  $\epsilon$ -Young's inequality are repeatedly used:

$$|ab| \leq \epsilon |a|^m + \epsilon^{-q/p} |b|^n, \quad \epsilon > 0, \quad m > 1, \quad n > 1, \quad \frac{1}{m} + \frac{1}{n} = 1. \quad (4.9)$$

At the same time, the last term on the right hand side of (4.7) is bounded as

$$\begin{aligned} & z(t, \omega) \int_{\mathbb{R}^N} |v|^{p-2} v g \, dx \\ & \leq \frac{1}{2} \alpha_1 z^{2-p}(t, \omega) \int_{\mathbb{R}^N} |v|^{2p-2} \, dx + \frac{1}{2\alpha_1} z^p(t, \omega) \|g(t, \cdot)\|^2. \end{aligned} \quad (4.10)$$

By a combination of (4.7)-(4.10), noticing that  $p > 2$ , we obtain that

$$\frac{d}{dt} \|v\|_p^p + \lambda \|v\|_p^p + \alpha_1 z^{2-p}(t, \omega) \|v\|_{\frac{2p-2}{2}}^{2p-2} \leq cz^p(t, \omega) (\|g(t, \cdot)\|^2 + 1), \quad (4.11)$$

where  $c$  only depends  $p, \lambda$  and  $\alpha_1$ . Applying [26, Lemma 5.1] (or [29]) over the interval  $[\tau - 2, \zeta]$ ,  $\zeta \in [\tau - 1, \tau]$ , along with  $\omega$  being replaced by  $\vartheta_{-\tau}\omega$ , we deduce that

$$\begin{aligned} & \|v(\zeta, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_p^p \\ & \leq \frac{e^\lambda}{\zeta - \tau + 2} \int_{\tau-2}^\tau e^{\lambda(s-\tau)} \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_p^p \, ds \\ & \quad + ce^\lambda z^{-p}(-\tau, \omega) \int_{-\infty}^0 e^{\lambda s} z^p(s, \omega) (\|g(s + \tau, \cdot)\|^2 + 1) \, ds. \end{aligned} \quad (4.12)$$

Since  $\frac{e^\lambda}{\zeta - \tau + 2} \leq 1$  for  $\zeta \in [\tau - 1, \tau]$ , then by (4.3) and (4.12) we find that there exists  $T > 2$  such that for all  $t \geq T$ ,

$$\begin{aligned} & \|v(\zeta, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_p^p \\ & \leq C(\tau, \omega) \int_{-\infty}^0 e^{\lambda s} (z^2(s, \omega) + z^p(s, \omega)) (\|g(s + \tau, \cdot)\|^2 + 1) \, ds. \end{aligned} \quad (4.13)$$

Integrating (4.11) over the interval  $[\tau - 1, \tau]$ , with  $\omega$  replaced by  $\vartheta_{-\tau}\omega$ , yields

$$\begin{aligned} & \alpha_1 \int_{\tau-1}^\tau z^{2-p}(s, \vartheta_{-\tau}\omega) \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_{\frac{2p-2}{2}}^{2p-2} \, ds \\ & \leq \|v(\tau - 1, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_p^p + c \int_{\tau-1}^\tau z^p(s, \vartheta_{-\tau}\omega) (\|g(s, \cdot)\|^2 + 1) \, ds \\ & \leq \|v(\tau - 1, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_p^p \\ & \quad + ce^{-\lambda} \int_{\tau-1}^\tau e^{\lambda(s-\tau)} z^p(s, \vartheta_{-\tau}\omega) (\|g(s, \cdot)\|^2 + 1) \, ds. \end{aligned} \quad (4.14)$$

Then from (4.1), (4.13) and (4.14) we deduce for all  $t \geq T$ ,

$$\begin{aligned} & \int_{\tau-1}^{\tau} \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_{2p-2}^{2p-2} ds \\ & \leq C(\tau, \omega) \int_{-\infty}^0 e^{\lambda s} (z^2(s, \omega) + z^p(s, \omega)) (\|g(s + \tau, \cdot)\|^2 + 1) ds, \end{aligned}$$

which proves (4.4).

To estimate the derivative  $v_t$  in  $L^2\text{loc}(\mathbb{R}, L^2(\mathbb{R}^N))$ , we multiply (3.8) by  $v_t$  and integrate over  $\mathbb{R}^N$  to produce

$$\begin{aligned} & \|v_t\|^2 + \frac{1}{2} \frac{d}{dt} (\lambda \|v\|^2 + \|\nabla v\|^2) \\ & = z(t, \omega) \int_{\mathbb{R}^N} f(x, z^{-1}v) v_t dx + z(t, \omega) \int_{\mathbb{R}^N} g v_t dx \\ & \leq \frac{1}{2} \|v_t\|^2 + c\alpha_2^2 z^{4-2p}(t, \omega) \|v\|_{2p-2}^{2p-2} + cz^2(t, \omega) \|\psi_2\|^2 + cz^2(t, \omega) \|g(t, \cdot)\|^2, \end{aligned}$$

i.e., we have

$$\begin{aligned} & \|v_t\|^2 + \frac{d}{dt} (\lambda \|v\|^2 + \|\nabla v\|^2) \\ & \leq cz^{4-2p}(t, \omega) \|v\|_{2p-2}^{2p-2} + cz^2(t, \omega) (\|g(t, \cdot)\|^2 + \|\psi_2\|^2). \end{aligned} \quad (4.15)$$

Integrate (4.15) over the interval  $[\tau - 1, \tau]$  to obtain

$$\begin{aligned} & \int_{\tau-1}^{\tau} \|v_s(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|^2 ds \\ & \leq c \int_{\tau-1}^{\tau} z^{4-2p}(s, \vartheta_{-\tau}\omega) \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_{2p-2}^{2p-2} ds \\ & \quad + c \int_{\tau-1}^{\tau} z^2(s, \vartheta_{-\tau}\omega) (\|g(s, \cdot)\|^2 + 1) ds + c \|v(\tau - 1, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_{H^1}^2. \end{aligned} \quad (4.16)$$

Then by (4.1), (4.2), (4.4) and (4.16) we get that for all  $t \geq T$ ,

$$\begin{aligned} & \int_{\tau-1}^{\tau} \|v_s(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|^2 ds \\ & \leq C(\tau, \omega) \int_{-\infty}^0 e^{\lambda s} (z^2(s, \omega) + z^p(s, \omega)) (\|g(s + \tau, \cdot)\|^2 + 1) ds, \end{aligned} \quad (4.17)$$

where  $T$  is as in Lemma 4.1. This completes the proof.  $\square$

We now can give the  $H^1$ -tail estimate of solutions of problem (3.8) and (3.9), which is one crucial condition for proving the asymptotic compactness in  $H^1(\mathbb{R}^N)$ .

**Proposition 4.4.** *Assume that (3.1)-(3.5) hold. Let  $\tau \in \mathbb{R}, \omega \in \Omega$  and  $B = \{B(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$ . Then for every  $\eta > 0$ , there exist two constants  $T = T(\tau, \omega, \eta, B) \geq 2$  and  $R = R(\tau, \omega, \eta) > 1$  such that the weak solution  $v$  of (3.8) and (3.9) satisfies that for all  $t \geq T$ ,*

$$\begin{aligned} & \int_{|x| \geq R} \left( |v(\tau, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)|^2 \right. \\ & \quad \left. + |\nabla v(\tau, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)|^2 \right) dx \leq \eta, \end{aligned}$$

where  $u_0 \in B(\tau - t, \vartheta_{-t}\omega)$  and  $R, T$  are independent of  $\varepsilon$ .

*Proof.* We first need to define a smooth function  $\xi(\cdot)$  on  $\mathbb{R}^+$  such that

$$\xi(s) = \begin{cases} 0, & \text{if } 0 \leq s \leq 1, \\ 0 \leq \xi(s) \leq 1, & \text{if } 1 \leq s \leq 2, \\ 1, & \text{if } s \geq 2, \end{cases}$$

which obviously implies that there is a positive constant  $C_1$  such that the  $|\xi'(s)| + |\xi''(s)| \leq C_1$  for all  $s \geq 0$ . For convenience, we write  $\xi = \xi(\frac{|x|^2}{k^2})$ .

We multiply (3.8) by  $-\xi\Delta v$  and integrate over  $\mathbb{R}^N$  to find that

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^N} \xi |\nabla v|^2 dx + \int_{\mathbb{R}^N} (\nabla \xi \cdot \nabla v) v_t dx + \lambda \int_{\mathbb{R}^N} \xi |\nabla v|^2 dx \\ & + \lambda \int_{\mathbb{R}^N} (\nabla \xi \cdot \nabla v) v dx + \int_{\mathbb{R}^N} \xi |\Delta v|^2 dx \\ & = -z(t, \omega) \int_{\mathbb{R}^N} f(x, z^{-1}v) \xi \Delta v dx - z(t, \omega) \int_{\mathbb{R}^N} g \xi \Delta v dx. \end{aligned} \tag{4.18}$$

Now, we estimate each term in (4.18) as follows. First we have

$$\begin{aligned} \left| \int_{\mathbb{R}^N} (\nabla \xi \cdot \nabla v) v_t dx + \lambda \int_{\mathbb{R}^N} (\nabla \xi \cdot \nabla v) v dx \right| &= \left| \int_{\mathbb{R}^N} (v_t + \lambda v) \left( \frac{2x}{k^2} \cdot \nabla v \right) \xi dx \right| \\ &\leq \frac{c}{k} (\|v_t\|^2 + \|v\|_{H^1}^2). \end{aligned} \tag{4.19}$$

For the nonlinearity in (4.18), we see that

$$\begin{aligned} & -z \int_{\mathbb{R}^N} f(x, z^{-1}v) \xi \Delta v dx \\ & = z \int_{\mathbb{R}^N} f(x, z^{-1}v) (\nabla \xi \cdot \nabla v) dx + z \int_{\mathbb{R}^N} \left( \frac{\partial}{\partial x} f(x, z^{-1}v) \cdot \nabla v \right) \xi dx \\ & \quad + \int_{\mathbb{R}^N} \frac{\partial}{\partial u} f(x, z^{-1}v) |\nabla v|^2 \xi dx. \end{aligned} \tag{4.20}$$

On the other hand, by using (3.2), (3.3) and (3.4), respectively, we calculate that

$$\begin{aligned} \left| z \int_{\mathbb{R}^N} f(x, z^{-1}v) (\nabla \xi \cdot \nabla v) dx \right| &\leq \frac{2z\sqrt{2}C_1}{k} \int_{k \leq |x| \leq \sqrt{2}k} |f(x, z^{-1}v)| |\nabla v| dx \\ &\leq \frac{c}{k} (z^{4-2p} \|v\|_{2p-2}^{2p-2} + z^2 \|\psi_2\|^2 + \|\nabla v\|^2), \end{aligned} \tag{4.21}$$

$$\int_{\mathbb{R}^N} \frac{\partial}{\partial u} f(x, z^{-1}v) |\nabla v|^2 \xi dx \leq \alpha_3 \int_{\mathbb{R}^N} \xi |\nabla v|^2 dx, \tag{4.22}$$

$$\begin{aligned} \left| z \int_{\mathbb{R}^N} \left( \frac{\partial}{\partial x} f(x, z^{-1}v) \cdot \nabla v \right) \xi dx \right| &\leq \left| z \int_{\mathbb{R}^N} |\psi_3| |\nabla v| \xi dx \right| \\ &\leq \frac{\lambda}{2} \int_{\mathbb{R}^N} \xi |\nabla v|^2 dx + cz^2 \int_{\mathbb{R}^N} \xi |\psi_3|^2 dx. \end{aligned} \tag{4.23}$$

Then from (4.20)-(4.23) it follows that

$$\begin{aligned} & -z \int_{\mathbb{R}^N} f(x, z^{-1}v) \xi \Delta v \, dx \\ & \leq \frac{c}{k} (z^{4-2p} \|v\|_{2p-2}^{2p-2} + z^2 \|\psi_2\|^2 + \|\nabla v\|^2) \\ & + \frac{\lambda}{2} \int_{\mathbb{R}^N} \xi |\nabla v|^2 \, dx + cz^2 \int_{\mathbb{R}^N} \xi |\psi_3|^2 \, dx + \alpha_3 \int_{\mathbb{R}^N} \xi |\nabla v|^2 \, dx. \end{aligned} \quad (4.24)$$

For the last term on the right-hand side of (4.18), we have

$$\left| z \int_{\mathbb{R}^N} g \xi \Delta v \, dx \right| \leq \frac{\lambda}{2} \int_{\mathbb{R}^N} \xi |\Delta v|^2 \, dx + \frac{1}{2\lambda} z^2 \int_{\mathbb{R}^N} \xi |g|^2 \, dx. \quad (4.25)$$

Then we use (4.19) and (4.24)-(4.25) in (4.18) to find that

$$\begin{aligned} & \frac{d}{dt} \int_{\mathbb{R}^N} \xi |\nabla v|^2 \, dx + \lambda \int_{\mathbb{R}^N} \xi |\nabla v|^2 \, dx \\ & \leq \frac{c}{k} (\|v_t\|^2 + \|v\|_{H^1}^2 + z^{4-2p} \|v\|_{2p-2}^{2p-2} + z^2 \|\psi_2\|^2) \\ & + 2\alpha_3 \int_{\mathbb{R}^N} \xi |\nabla v|^2 \, dx + cz^2 \int_{\mathbb{R}^N} \xi (|\psi_3|^2 + |g|^2) \, dx. \end{aligned} \quad (4.26)$$

Applying [26, Lemma 5.1] to (4.26) over the interval  $[\tau - 1, \tau]$ , along with  $\omega$  being replaced by  $\vartheta_{-\tau}\omega$ , we deduce that

$$\begin{aligned} & \int_{\mathbb{R}^N} \xi |\nabla v(\tau, \tau - t, \vartheta_{-\tau}\omega, v_0)|^2 \, dx \\ & \leq \frac{c}{k} \int_{\tau-1}^{\tau} e^{\lambda(s-\tau)} \left( \|v_s(s)\|^2 + \|v(s)\|_{H^1}^2 + z^{4-2p}(s, \vartheta_{-\tau}\omega) \|v(s)\|_{2p-2}^{2p-2} \right. \\ & \quad \left. + z^2(s, \vartheta_{-\tau}\omega) \|\psi_2\|^2 \right) ds + c \int_{\tau-1}^{\tau} e^{\lambda(s-\tau)} \int_{|x| \geq k} |\nabla v(s)|^2 \, dx \, ds \\ & \quad + cz^{-2}(\tau, \omega) \int_{-1}^0 e^{\lambda s} z^2(s, \omega) \int_{|x| \geq k} (|\psi_3|^2 + |g(s + \tau, x)|^2) \, dx \, ds, \end{aligned} \quad (4.27)$$

where  $v(s) = v(s, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)$ . Our task in the following is to show that each term on the right hand side of (4.27) vanishes when  $t$  and  $k$  are larger. First, by Lemma 4.2, there are two constants  $T_1 = T_1(\tau, \omega, B, \eta) \geq 2$  and  $R_1 = R_1(\tau, \omega, \eta) \geq 1$  such that for all  $t \geq T_1$  and  $k \geq R_1$ ,

$$\begin{aligned} & c \int_{\tau-1}^{\tau} e^{\lambda(s-\tau)} \int_{|x| \geq k} |\nabla v(s)|^2 \, dx \, ds \\ & \leq c \int_{\tau-1}^{\tau} \int_{|x| \geq k} |\nabla v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)|^2 \, dx \, ds \leq \frac{\eta}{6}. \end{aligned} \quad (4.28)$$

By (4.2) in Lemma 4.1, there exist  $T_2 = T_2(\tau, \omega, B) \geq 2$  and  $R_2 = R_2(\tau, \omega, \eta) \geq 1$  such that for all  $t \geq T_2$  and  $k \geq R_2$ ,

$$\begin{aligned} & \frac{c}{k} \int_{\tau-1}^{\tau} e^{\lambda(s-\tau)} \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_{H^1}^2 \, ds \\ & \leq \frac{c}{k} \int_{\tau-1}^{\tau} \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_{H^1}^2 \, ds \leq \frac{\eta}{6}. \end{aligned} \quad (4.29)$$



By Lemma 4.3, there exist  $T_3 = T_3(\tau, \omega, B) \geq 2$  and  $R_3 = R_3(\tau, \omega, \eta) \geq 1$  such that for all  $t \geq T_3$  and  $k \geq R_3$ ,

$$\begin{aligned} & \frac{c}{k} \int_{\tau-1}^{\tau} e^{\lambda(s-\tau)} z^{4-2p}(s, \vartheta_{-\tau}\omega) \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_{2^{p-2}}^{2p-2} ds \\ & \leq \frac{c}{k} z^{2p-4}(-\tau, \omega) E^{4-2p} L_2(\tau, \omega, \varepsilon) \leq \frac{\eta}{6}, \end{aligned} \tag{4.30}$$

and

$$\frac{c}{k} \int_{\tau-1}^{\tau} e^{\lambda(s-\tau)} \|v_s(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|^2 ds \leq \frac{c}{k} L_2(\tau, \omega, \varepsilon) \leq \frac{\eta}{6}. \tag{4.31}$$

By the assumptions on  $\psi_3$  and  $g$ , we deduce that there exist  $R_4 = R_4(\tau, \omega, \eta)$  such that for all  $k \geq R_4$ ,

$$cz^{-2}(\tau, \omega) \int_{-1}^0 e^{\lambda s} z^2(s, \omega) \int_{|x| \geq k} (|\psi_3|^2 + |g(s + \tau, x)|^2) dx ds \leq \frac{\eta}{6}. \tag{4.32}$$

Obviously, there exists  $R_5 = R_5(\tau, \omega, \eta)$  such that for all  $k \geq R_5$ ,

$$\begin{aligned} & \frac{c}{k} \int_{\tau-1}^{\tau} e^{\lambda(s-\tau)} z^2(s, \vartheta_{-\tau}\omega) \|\psi_2\|^2 ds \\ & \leq \frac{c}{k} \|\psi_2\|^2 z^{-2}(-\tau, \omega) \int_{-1}^0 z^2(s, \omega) ds \leq \frac{\eta}{6}, \end{aligned} \tag{4.33}$$

where  $\int_{-1}^0 z^2(s, \omega) ds < +\infty$ . Finally, take

$$T = \{T_1, T_2, T_3\}, \quad R = \max\{R_1, R_2, R_3, R_4, R_5\}.$$

It is obvious that  $R$  and  $T$  are independent of the intension  $\varepsilon$ . Then (4.28)-(4.33) are integrated into (4.27) to get that for all  $t \geq T$  and  $k \geq R$ ,

$$\int_{|x| \geq \sqrt{2}k} |\nabla v(\tau, \tau - t, \vartheta_{-\tau}\omega, v_0)|^2 dx \leq \eta. \tag{4.34}$$

Then in connection with Lemma 4.2, the desired result is achieved. □

**4.2. Estimate of the truncation of solutions in  $L^{2p-2}$ .** Given  $u$  the solution of problem (1.1) and (1.2), for each fixed  $\tau \in \mathbb{R}, \omega \in \Omega$ , we write  $M = M(\tau, \omega) > 1$  and

$$\mathbb{R}^N (|u(\tau, \tau - t, \vartheta_{-\tau}\omega, u_0)| \geq M) = \{x \in \mathbb{R}^N; |u(\tau, \tau - t, \vartheta_{-\tau}\omega, u_0)| \geq M\}. \tag{4.35}$$

We introduce the truncation version of solutions of problem (3.8)-(3.9). Let  $(v - M)_+$  be the positive part of  $v - M$ , i.e.,

$$(v - M)_+ = \begin{cases} v - M, & \text{if } v > M; \\ 0, & \text{if } v \leq M. \end{cases}$$

The next lemma shows that the integral of  $L^{2p-2}$ -norm of  $|u|$  over the interval  $[\tau - 1, \tau]$  vanishes on the state domain  $\mathbb{R}^N (|u(\tau, \tau - t, \vartheta_{-\tau}\omega), u_0| \geq M)$  for  $M$  large enough, which is the second crucial condition for proving the asymptotic compactness of solutions in  $H^1(\mathbb{R}^N)$ .

**Proposition 4.5.** *Assume that (3.1)-(3.5) hold. Let  $\tau \in \mathbb{R}, \omega \in \Omega$ ,*

$$B = \{B(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}$$

*and  $u_0 \in B(\tau - t, \vartheta_{-t}\omega)$ . Then for any  $\eta > 0$ , there exist constants  $\tilde{M} = \tilde{M}(\tau, \omega, \eta) > 1$  and  $T = T(\tau, \omega, B) \geq 2$  such that the solution  $u$  of problem (3.8) and (3.9) satisfies that for all  $t \geq T$  and all  $\varepsilon \in (0, 1]$ ,*

$$\int_{\tau-1}^{\tau} e^{\tilde{\varepsilon}(s-\tau)} \int_{\mathcal{O}} |v(s, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)|^{2p-2} dx ds \leq \eta,$$

*where  $p > 2$ ,  $\tilde{M}$  and  $T$  are independent of  $\varepsilon$ ,*

$$\mathcal{O} = \mathbb{R}^N (|v(s, \tau - t, \vartheta_{-\tau}\omega, z(\tau - t, \vartheta_{-\tau}\omega)u_0)| \geq \tilde{M})$$

*and*

$$\tilde{\varrho} = \tilde{\varrho}(\tau, \omega, \tilde{M}) = \alpha_1 F^{2-p} e^{-(p-2)|\omega(-\tau)|} \tilde{M}^{p-2}.$$

*Proof.* First, we replace  $\omega$  by  $\vartheta_{-\tau}\omega$  in (3.8) to see that

$$v = v(s) =: v(s, \tau - t, \vartheta_{-\tau}\omega, v_0), \quad s \in [\tau - 1, \tau],$$

is a solution of the SPDE

$$\frac{dv}{ds} + \lambda v - \Delta v = \frac{z(s - \tau, \omega)}{z(-\tau, \omega)} f(x, u) + \frac{z(s - \tau, \omega)}{z(-\tau, \omega)} g(s, x), \quad (4.36)$$

with the initial data  $v_0 = z(\tau - t, \vartheta_{-\tau}\omega)u_0$ , where we have used  $z(s, \vartheta_{-\tau}\omega) = \frac{z(s-\tau, \omega)}{z(-\tau, \omega)} > 0$ .

We multiply (4.36) by  $(v - M)_+^{p-1}$  and integrate over  $\mathbb{R}^N$  to obtain that for every  $s \in [\tau - 1, \tau]$ ,

$$\begin{aligned} & \frac{1}{p} \frac{d}{ds} \int_{\mathbb{R}^N} (v - M)_+^p dx + \lambda \int_{\mathbb{R}^N} v (v - M)_+^{p-1} dx - \int_{\mathbb{R}^N} \Delta v (v - M)_+^{p-1} dx \\ &= \frac{z(s - \tau, \omega)}{z(-\tau, \omega)} \int_{\mathbb{R}^N} f(x, u) (v - M)_+^{p-1} dx + \frac{z(s - \tau, \omega)}{z(-\tau, \omega)} \int_{\mathbb{R}^N} g(s, x) (v - M)_+^{p-1} dx. \end{aligned} \quad (4.37)$$

We now need to estimate every term in (4.37). First, it is obvious that

$$- \int_{\mathbb{R}^N} \Delta v (v - M)_+^{p-1} dx = (p - 1) \int_{\mathbb{R}^N} (v - M)_+^{p-2} |\nabla v|^2 dx \geq 0, \quad (4.38)$$

$$\lambda \int_{\mathbb{R}^N} v (v - M)_+^{p-1} dx \geq \lambda \int_{\mathbb{R}^N} (v - M)_+^p dx. \quad (4.39)$$

If  $v > M$ , then  $u = z^{-1}(s, \vartheta_{-\tau}\omega)v > 0$ . Therefore by assumption (3.1), we have

$$\begin{aligned} f(x, u) &\leq -\alpha_1 u^{p-1} + \frac{\psi_1(x)}{u} \\ &= -\alpha_1 \left( \frac{z(s - \tau, \omega)}{z(-\tau, \omega)} \right)^{1-p} v^{p-1} + \frac{z(s - \tau, \omega)}{z(-\tau, \omega)} \frac{\psi_1(x)}{v}. \end{aligned} \quad (4.40)$$

Since  $s \in [\tau - 1, \tau]$  and  $p > 2$ , then by (4.1) we have

$$F^{2-p} \leq z^{2-p}(s - \tau, \omega) \leq E^{2-p},$$

from which and (4.40) it follows that

$$\frac{z(s - \tau, \omega)}{z(-\tau, \omega)} f(x, u)$$

$$\begin{aligned}
&\leq -\alpha_1 \left( \frac{z(s-\tau, \omega)}{z(-\tau, \omega)} \right)^{2-p} v^{p-1} + \frac{z^2(s-\tau, \omega)}{z^2(-\tau, \omega)} \frac{\psi_1(x)}{v} \\
&= -\frac{\alpha_1}{2} \left( \frac{z(s-\tau, \omega)}{z(-\tau, \omega)} \right)^{2-p} v^{p-1} - \frac{\alpha_1}{2} \left( \frac{z(s-\tau, \omega)}{z(-\tau, \omega)} \right)^{2-p} v^{p-1} + \frac{z^2(s-\tau, \omega)}{z^2(-\tau, \omega)} \frac{\psi_1(x)}{v} \\
&\leq -\frac{\alpha_1}{2} \frac{F^{2-p}}{z^{2-p}(-\tau, \omega)} M^{p-2} (v-M) - \frac{\alpha_1}{2} \frac{F^{2-p}}{z^{2-p}(-\tau, \omega)} (v-M)^{p-1} \\
&\quad + \frac{F^2}{z^2(-\tau, \omega)} |\psi_1(x)| (v-M)^{-1},
\end{aligned}$$

which by the nonlinearity in (4.37) is estimated as

$$\begin{aligned}
&\frac{z(s-\tau, \omega)}{z(-\tau, \omega)} \int_{\mathbb{R}^N} f(x, u) (v-M)_+^{p-1} dx \\
&\leq -\frac{\alpha_1}{2} \frac{F^{2-p}}{z^{2-p}(-\tau, \omega)} M^{p-2} \int_{\mathbb{R}^N} (v-M)_+^p dx - \frac{\alpha_1}{2} \frac{F^{2-p}}{z^{2-p}(-\tau, \omega)} \\
&\quad \times \int_{\mathbb{R}^N} (v-M)_+^{2p-2} dx + \frac{F^2}{z^2(-\tau, \omega)} \int_{\mathbb{R}^N} |\psi_1(x)| (v-M)_+^{p-2} dx \\
&\leq -\frac{\alpha_1}{2} \frac{F^{2-p}}{z^{2-p}(-\tau, \omega)} M^{p-2} \int_{\mathbb{R}^N} (v-M)_+^p dx - \frac{\alpha_1}{2} \frac{F^{2-p}}{z^{2-p}(-\tau, \omega)} \\
&\quad \times \int_{\mathbb{R}^N} (v-M)_+^{2p-2} dx + \frac{1}{2} \lambda \int_{\mathbb{R}^N} (v-M)_+^p dx \\
&\quad + \frac{cF^p}{z^p(-\tau, \omega)} \int_{\mathbb{R}^N(v \geq M)} |\psi_1(x)|^{p/2} dx,
\end{aligned} \tag{4.41}$$

where the last term the  $\epsilon$ -Young's inequality (4.9) is used. The second term on the right-hand side of (4.37) is bounded as

$$\begin{aligned}
&\frac{F}{z(-\tau, \omega)} \left| \int_{\mathbb{R}^N} g(s, x) (v(s) - M)_+^{p-1} dx \right| \\
&\leq \frac{\alpha_1}{4} \frac{F^{2-p}}{z^{2-p}(-\tau, \omega)} \int_{\mathbb{R}^N} (v-M)_+^{2p-2} dx \\
&\quad + \frac{1}{\alpha_1} \frac{F^p}{z^p(-\tau, \omega)} \int_{\mathbb{R}^N(v(s) \geq M)} g^2(s, x) dx.
\end{aligned} \tag{4.42}$$

By a combination of (4.37)–(4.42), we obtain

$$\begin{aligned}
&\frac{d}{ds} \int_{\mathbb{R}^N} (v(s) - M)_+^p dx + \frac{\alpha_1 F^{2-p}}{z^{2-p}(-\tau, \omega)} M^{p-2} \int_{\mathbb{R}^N} (v(s) - M)_+^p dx \\
&\quad + \frac{\alpha_1 F^{2-p}}{z^{2-p}(-\tau, \omega)} \int_{\mathbb{R}^N} (v-M)_+^{2p-2} dx \\
&\leq \frac{cF^p}{z^p(-\tau, \omega)} \left( \|g(s, \cdot)\|^2 + \|\psi_1\|_{p/2}^{p/2} \right),
\end{aligned} \tag{4.43}$$

where the positive constant  $c$  is independent of  $\varepsilon, \tau, \omega$  and  $M$ . Note that for each  $\tau \in \mathbb{R}$  and  $\varepsilon \in (0, 1]$ ,

$$e^{-|\omega(-\tau)|} \leq z(-\tau, \omega) = e^{-\varepsilon\omega(-\tau)} \leq e^{|\omega(-\tau)|}. \tag{4.44}$$

Here for convenience, we put

$$\varrho = \varrho(\tau, \omega, M) = \alpha_1 F^{2-p} e^{-(p-2)|\omega(-\tau)|} M^{p-2} > 0,$$

$$d = d(\tau, \omega) = \alpha_1 F^{2-p} e^{-(p-2)|\omega(-\tau)|} > 0,$$

where  $d$  is unchanged and  $\varrho \rightarrow +\infty$  as  $M \rightarrow +\infty$ . Then from (4.43) and (4.44) we infer that

$$\begin{aligned} & \frac{d}{ds} \int_{\mathbb{R}^N} (v(s) - M)_+^p dx + \varrho \int_{\mathbb{R}^N} (v(s) - M)_+^p dx + d \int_{\mathbb{R}^N} (v - M)_+^{2p-2} dx \\ & \leq cF^p e^{p|\omega(-\tau)|} \left( \|g(s, \cdot)\|^2 + 1 \right), \end{aligned} \quad (4.45)$$

where  $s \in [\tau - 1, \tau]$  and  $\varrho, E, F$  are independent of  $\varepsilon$  and  $t$ . By using [26, Lemma 5.1] to (4.45) over the interval  $[\tau - 1, \tau]$ , we find that

$$\begin{aligned} & \int_{\tau-1}^{\tau} e^{\varrho(s-\tau)} \int_{\mathbb{R}^N} (v(s) - M)_+^{2p-2} dx ds \\ & \leq \frac{1}{d} \int_{\tau-1}^{\tau} e^{\varrho(s-\tau)} \int_{\mathbb{R}^N} \left( v(s, \tau - t, \vartheta_{-\tau}\omega, v_0) - M \right)_+^p dx ds \\ & \quad + \frac{cF^p e^{p|\omega(-\tau)|}}{d} \int_{\tau-1}^{\tau} e^{\varrho(s-\tau)} \left( \|g(s, \cdot)\|^2 + 1 \right) ds. \end{aligned} \quad (4.46)$$

First by (4.13), there exists  $T_1 = T_1(\tau, \omega, B) \geq 2$  such that for all  $t \geq T_1$ ,

$$\begin{aligned} & \frac{1}{d} \int_{\tau-1}^{\tau} e^{\varrho(s-\tau)} \int_{\mathbb{R}^N} \left( v(s, \tau - t, \vartheta_{-\tau}\omega, v_0) - M \right)_+^p dx ds \\ & \leq \frac{1}{d} \int_{\tau-1}^{\tau} e^{\varrho(s-\tau)} \|v(s, \tau - t, \vartheta_{-\tau}\omega, v_0)\|_p^p ds \\ & \leq N(\tau, \omega) \frac{1}{d\varrho} \rightarrow 0, \end{aligned} \quad (4.47)$$

as  $\varrho \rightarrow +\infty$ , where  $N(\tau, \omega)$  is the bound of the right hand side of (4.13). We then show that the second term on the right hand side of (4.46) is also small as  $\varrho \rightarrow +\infty$ . Indeed, choosing  $\varrho > \delta$  (where  $\delta \in (0, \lambda)$  is in (3.5)) and taking  $\varsigma \in (0, 1)$ , we have

$$\begin{aligned} & \int_{\tau-1}^{\tau} e^{\varrho(s-\tau)} \left( \|g(s, \cdot)\|^2 + 1 \right) ds \\ & = \int_{\tau-1}^{\tau-\varsigma} e^{\varrho(s-\tau)} \left( \|g(s, \cdot)\|^2 + 1 \right) ds + \int_{\tau-\varsigma}^{\tau} e^{\varrho(s-\tau)} \left( \|g(s, \cdot)\|^2 + 1 \right) ds \\ & = e^{-\varrho\tau} \int_{\tau-1}^{\tau-\varsigma} e^{(\varrho-\delta)s} e^{\delta s} \left( \|g(s, \cdot)\|^2 + 1 \right) ds + e^{-\varrho\tau} \int_{\tau-\varsigma}^{\tau} e^{\varrho s} \left( \|g(s, \cdot)\|^2 + 1 \right) ds \\ & \leq e^{-\varrho\varsigma} e^{\delta(\varsigma-\tau)} \int_{-\infty}^{\tau} e^{\delta s} \left( \|g(s, \cdot)\|^2 + 1 \right) ds + \int_{\tau-\varsigma}^{\tau} \left( \|g(s, \cdot)\|^2 + 1 \right) ds. \end{aligned}$$

By (3.5), the first term above vanishes as  $\varrho \rightarrow +\infty$ , and by  $g \in L^2 \text{loc}(\mathbb{R}, L^2(\mathbb{R}^N))$  we can choose  $\varsigma$  small enough such that the second term is small. Hence when  $\varrho \rightarrow +\infty$ , we have

$$\frac{cF^p e^{p|\omega(-\tau)|}}{d} \int_{\tau-1}^{\tau} e^{\varrho 2(s-\tau)} \left( \|g(s, \cdot)\|^2 + 1 \right) ds \rightarrow 0. \quad (4.48)$$

Then by (4.46)–(4.48), there exist two large positive constants  $M_1 = M_1(\tau, \omega)$  and  $T_1 = T_1(\tau, \omega, B) \geq 2$  such that all  $t \geq T_1$ ,

$$\int_{\tau-1}^{\tau} e^{\varrho_1(s-\tau)} \int_{\mathbb{R}^N} (v(s) - M_1)_+^{2p-2} dx ds \leq \eta, \quad (4.49)$$

where  $\varrho_1 = \alpha_1 F^{2-p} e^{-(p-2)|\omega(-\tau)|} M_1$ . Note that  $v - M_1 \geq \frac{v}{2}$  for  $v \geq 2M_1$ . Then (4.49) gives that for all  $t \geq T_1$ ,

$$\begin{aligned} & \int_{\tau-1}^{\tau} e^{\varrho_1(s-\tau)} \int_{\mathbb{R}^N(v(s) \geq 2M_1)} |v(s)|^{2p-2} dx ds \\ & \leq 2^{2p-2} \int_{\tau-1}^{\tau} e^{\varrho_1(s-\tau)} \int_{\mathbb{R}^N} (v(s) - M_1)_+^{2p-2} dx ds \leq 2^{2p-2} \eta. \end{aligned} \tag{4.50}$$

By a similar argument, we can show that there exist two large positive constants  $M_2 = M_2(\tau, \omega)$  and  $T_2 = T_2(\tau, \omega, B) \geq 2$  such that for all  $t \geq T_2$ ,

$$\int_{\tau-1}^{\tau} e^{\varrho_2(s-\tau)} \int_{\mathbb{R}^N(v(s) \leq -2M_2)} |v(s)|^{2p-2} dx ds \leq 2^{2p-2} \eta, \tag{4.51}$$

where  $\varrho_2 = \alpha_1 F^{2-p} e^{-(p-2)|\omega(-\tau)|} M_2$ . Put  $\tilde{M} = 2 \times \max\{M_1, M_2\}$  and  $T = \max\{T_1, T_2\}$ . Then (4.50) and (4.51) together imply the desired.  $\square$

**4.3. Asymptotic compactness on bounded domains.** In this subsection, by using Proposition 4.5, we prove the asymptotic compactness of the cocycle  $\varphi$  defined by (3.10) in  $H_0^1(\mathcal{O}_R)$  for any  $R > 0$ , where  $\mathcal{O}_R = \{x \in \mathbb{R}^N; |x| \leq R\}$ . For this purpose, we define  $\phi(\cdot) = 1 - \xi(\cdot)$ , where  $\xi$  is the cut-off function as in (4.16). Then we know that  $0 \leq \phi(s) \leq 1$ , and  $\phi(s) = 1$  if  $s \in [0, 1]$  and  $\phi(s) = 0$  if  $s \geq 2$ . Fix a positive constant  $k$ , we define

$$\tilde{v}(t, \tau, \omega, v_0) = \phi\left(\frac{x^2}{k^2}\right)v(t, \tau, \omega, v_0), \quad \tilde{u}(t, \tau, \omega, u_0) = \phi\left(\frac{x^2}{k^2}\right)u(t, \tau, \omega, u_0), \tag{4.52}$$

where  $v$  is the solution of problem (3.8)-(3.9) and  $u$  is the solution of problem (1.1)-(1.2) with  $v = z(t, \omega)u$ . Then we have

$$\tilde{u}(t, \tau, \omega, u_0) = z^{-1}(t, \omega)\tilde{v}(t, \tau, \omega, v_0). \tag{4.53}$$

It is obvious that  $\tilde{v}$  solves the following equations:

$$\begin{aligned} \tilde{v}_t + \lambda \tilde{v} - \Delta \tilde{v} &= \phi z f(x, z^{-1}v) + \phi z g - v \Delta \phi - 2 \nabla \phi \cdot \nabla v, \\ \tilde{v}|_{\partial \mathcal{O}_{k\sqrt{2}}} &= 0, \\ \tilde{v}(\tau, x) &= \tilde{v}_0(x) = \phi v_0(x), \end{aligned} \tag{4.54}$$

where  $\phi = \phi(x^2/k^2)$ .

It is well-known that the eigenvalue problem on bounded domains  $\mathcal{O}_{k\sqrt{2}}$  with Dirichlet boundary condition:

$$\begin{aligned} -\Delta \tilde{v} &= \lambda \tilde{v}, \\ \tilde{v}|_{\partial \mathcal{O}_{k\sqrt{2}}} &= 0 \end{aligned}$$

has a family of orthogonal eigenfunctions  $\{e_j\}_{j=1}^{+\infty}$  in both  $L^2(\mathcal{O}_{k\sqrt{2}})$  and  $H_0^1(\mathcal{O}_{k\sqrt{2}})$  such that the corresponding eigenvalue  $\{\lambda_j\}_{j=1}^{+\infty}$  is non-decreasing in  $j$ .

Let  $H_m = \text{Span}\{e_1, e_2, \dots, e_m\} \subset H_0^1(\mathcal{O}_{k\sqrt{2}})$  and  $P_m : H_0^1(\mathcal{O}_{k\sqrt{2}}) \rightarrow H_m$  be the canonical projector and  $I$  be the identity. Then for every  $\tilde{u} \in H_0^1(\mathcal{O}_{k\sqrt{2}})$ ,  $\tilde{u}$  has a unique decomposition:  $\tilde{u} = \tilde{u}_1 + \tilde{u}_2$ , where  $\tilde{u}_1 = P_m \tilde{u} \in H_m$  and  $\tilde{u}_2 = (I - P_m)\tilde{u} \in H_m^\perp$ , i.e.,  $H_0^1(\mathcal{O}_{k\sqrt{2}}) = H_m \oplus H_m^\perp$ .

**Lemma 4.6.** *Assume that (3.1)-(3.5) hold. Let  $\tau \in \mathbb{R}$ ,  $\omega \in \Omega$  and*

$$B = \{B(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\} \in \mathfrak{D}.$$

Then for every  $\eta > 0$ , there are  $N_0 = N_0(\tau, \omega, k, \eta) \in Z^+$  and  $T = T(\tau, \omega, B, \eta) \geq 2$  such that for all  $t \geq T$  and  $m > N_0$ ,

$$\|(I - P_m)\tilde{u}(\tau, \tau - t, \vartheta_{-\tau}\omega, \tilde{u}_0)\|_{H_0^1(\mathcal{O}_{k\sqrt{2}})} \leq \eta,$$

where  $\tilde{u}_0 = \phi u_0$  with  $u_0 \in B(\tau - t, \vartheta_{-\tau}\omega)$ . Here  $\tilde{u}$  is as in (4.53) and  $N, T$  are independent of  $\varepsilon$ .

*Proof.* By (4.53), we start at the estimate of  $\tilde{v}$ . For  $\tilde{v} \in H_0^1(\mathcal{O}_{k\sqrt{2}})$ , we write  $\tilde{v} = \tilde{v}_1 + \tilde{v}_2$  where  $\tilde{v}_1 = P_m\tilde{v}$  and  $\tilde{v}_2 = (I - P_m)\tilde{v}$ . Then naturally, we have a splitting about  $\tilde{u} = \tilde{u}_1 + \tilde{u}_2$  where  $\tilde{u}_1 = P_m\tilde{u}$  and  $\tilde{u}_2 = (I - P_m)\tilde{u}$ . Multiplying (4.47) by  $\Delta\tilde{v}_2$  we get that

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|\nabla\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 + \lambda \|\nabla\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 + \|\Delta\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 \\ &= -z \int_{\mathcal{O}_{k\sqrt{2}}} \phi f(x, z^{-1}v) \Delta\tilde{v}_2 dx + \int_{\mathcal{O}_{k\sqrt{2}}} (\phi z g - v \Delta\phi - 2\nabla\phi \cdot \nabla v) \Delta\tilde{v}_2 dx, \end{aligned} \tag{4.55}$$

where  $z$  is the abbreviation of  $z(t, \omega)$ . By (3.2), we deduce that

$$z \int_{\mathcal{O}_{k\sqrt{2}}} \phi f(x, z^{-1}v) \Delta\tilde{v}_2 dx \leq \frac{1}{4} \|\Delta\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 + cz^{4-2p} \|v\|_{L^{2p-2}(\mathcal{O}_{k\sqrt{2}})}^{2p-2} + z^2 \|\psi_2\|^2. \tag{4.56}$$

On the other hand,

$$\begin{aligned} & \int_{\mathcal{O}_{k\sqrt{2}}} (\phi z g - v \Delta\phi - 2\nabla\phi \cdot \nabla v) \Delta\tilde{v}_2 dx \\ & \leq \frac{1}{4} \|\Delta\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 + c(z^2 \|g\|^2 + \|v\|^2 + \|\nabla v\|^2). \end{aligned} \tag{4.57}$$

Then by (4.55)–(4.57) we find that

$$\begin{aligned} & \frac{d}{dt} \|\nabla\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 + \|\Delta\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 \\ & \leq c(z^{4-2p} \|v\|_{L^{2p-2}(\mathcal{O}_{k\sqrt{2}})}^{2p-2} + z^2 \|\psi_2\|^2 + z^2 \|g\|^2 + \|v\|_{H^1}^2). \end{aligned}$$

from which and Poincaré’s inequality

$$\|\Delta\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 \geq \lambda_{m+1} \|\nabla\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2,$$

it follows that

$$\begin{aligned} & \frac{d}{dt} \|\nabla\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 + \lambda_{m+1} \|\nabla\tilde{v}_2\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 \\ & \leq c(z^{4-2p} \|v\|_{L^{2p-2}(\mathcal{O}_{k\sqrt{2}})}^{2p-2} + z^2 \|\psi_2\|^2 + z^2 \|g\|^2 + \|v\|_{H^1}^2). \end{aligned} \tag{4.58}$$

Applying [26, Lemma 5.1] to (4.58) over the interval  $[\tau - 1, \tau]$ , along with  $\omega$  being replaced by  $\vartheta_{-\tau}\omega$ , we find that

$$\begin{aligned} & \|\nabla\tilde{v}_2(\tau, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 \\ & \leq \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} \|\nabla\tilde{v}_2(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{L^2(\mathcal{O}_{k\sqrt{2}})}^2 ds \\ & \quad + c \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} z^{4-2p}(s, \vartheta_{-\tau}\omega) \|v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{L^{2p-2}(\mathcal{O}_{k\sqrt{2}})}^{2p-2} ds \\ & \quad + c \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} z^2(s, \vartheta_{-\tau}\omega) (\|\psi_2\|^2 + \|g(s, \cdot)\|^2) ds \end{aligned}$$

$$\begin{aligned}
& + c \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} \|v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{H^1}^2 ds \\
\leq & c \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} z^{4-2p}(s, \vartheta_{-\tau}\omega) \|v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{L^{2p-2}(\mathcal{O}_{k\sqrt{2}})}^{2p-2} ds \\
& + c \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} \|v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{H^1}^2 ds \\
& + c \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} z^2(s, \vartheta_{-\tau}\omega) \left( \|g(s, \cdot)\|^2 + 1 \right) ds \\
= & I_1 + I_2 + I_3. \tag{4.59}
\end{aligned}$$

We next to show that  $I_1, I_2$  and  $I_3$  converge to zero as  $m$  increases to infinite. First since by (4.1),  $z^{4-2p}(s - \tau, \omega) \leq E^{4-2p}$  for  $s \in [-1, 0]$ , then we have

$$\begin{aligned}
I_1 & = z^{2p-4}(-\tau, \omega) \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} z^{4-2p}(s - \tau, \omega) \\
& \quad \times \|v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{L^{2p-2}(\mathcal{O}_{k\sqrt{2}})}^{2p-2} ds \\
\leq & z^{2p-4}(-\tau, \omega) E^{4-2p} \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} \|v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{L^{2p-2}(\mathcal{O}_{k\sqrt{2}})}^{2p-2} ds \\
\leq & z^{2p-4}(-\tau, \omega) E^{4-2p} \left( \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} \right. \\
& \quad \times \int_{\mathcal{O}_{k\sqrt{2}}(|v(s)| \geq M)} |v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)|^{2p-2} dx ds \\
& \quad \left. + \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} \int_{\mathcal{O}_{k\sqrt{2}}(|v(s)| \leq M)} |v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)|^{2p-2} dx ds \right). \tag{4.60}
\end{aligned}$$

By Proposition 4.5, there exist  $T_1 = T_1(\tau, \omega, B, \eta) \geq 2$ ,  $\tilde{M} = \tilde{M}(\tau, \omega, \eta)$  such that for all  $t \geq T_1$ ,

$$\begin{aligned}
& z^{2p-4}(-\tau, \omega) E^{4-2p} \int_{\tau-1}^{\tau} e^{\tilde{\varrho}(s-\tau)} \\
& \quad \times \int_{\mathcal{O}_{k\sqrt{2}}(|v(s)| \geq \tilde{M})} |v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)|^{2p-2} dx ds \leq \eta. \tag{4.61}
\end{aligned}$$

But  $\lambda_{m+1} \rightarrow +\infty$ , then there exists  $N' = N'(\tau, \omega, \eta) > 0$  such that for all  $m > N'$ ,  $\lambda_{m+1} > \tilde{\varrho}$ . Hence by (4.61) it gives us that for all  $t \geq T_1$  and  $m > N'$  there holds

$$\begin{aligned}
& z^{2p-4}(-\tau, \omega) E^{4-2p} \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} \\
& \quad \times \int_{\mathcal{O}_{k\sqrt{2}}(|v(s)| \geq \tilde{M})} |v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)|^{2p-2} dx ds \leq \eta. \tag{4.62}
\end{aligned}$$

For the second term on the right hand side of (4.60), since  $\mathcal{O}_{k\sqrt{2}}(|v(s)| \leq \tilde{M})$  is a bounded domain, then there exists  $N'' = N''(\tau, \omega, \eta) > 0$  such that for all  $m > N''$ ,

$$\begin{aligned}
 & z^{2p-4}(-\tau, \omega) E^{4-2p} \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} \\
 & \times \int_{\mathcal{O}_{k\sqrt{2}}(|v(s)| \leq \tilde{M})} |v(s, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)|^{2p-2} dx ds \tag{4.63} \\
 & \leq z^{2p-4}(-\tau, \omega) E^{4-2p} \frac{\tilde{M}^{2p-2}}{\lambda_{m+1}} |(\mathcal{O}_{k\sqrt{2}}(|v(s)| \leq \tilde{M}))| \leq \eta,
 \end{aligned}$$

where  $|(\mathcal{O}_{k\sqrt{2}}(|v(s)| \leq \tilde{M}))|$  is the finite measure of the bounded domain  $\mathcal{O}_{k\sqrt{2}}(|v(s)| \leq \tilde{M})$ . Put  $N_1 = \max\{N', N''\}$ . It follows from (4.60)-(4.63) that for all  $m > N_1$  and  $t \geq T_1$ ,

$$I_1 \leq 2\eta. \tag{4.64}$$

By Lemma 4.1, there exists  $T_2 = T_2(\tau, \omega, B)$  and  $N_2 = N_2(\tau, \omega, \eta) > 0$  such that for all  $m > N_2$  and  $t \geq T_2$ ,

$$I_2 \leq \frac{L_1(\tau, \omega, \varepsilon)}{\lambda_{m+1}} \leq \eta. \tag{4.65}$$

By a same technique as (4.48), we can show that there exists  $N_3 = N_3(\tau, \omega, \eta) > 0$  such that for all  $m > N_3$ ,

$$I_3 = c \int_{\tau-1}^{\tau} e^{\lambda_{m+1}(s-\tau)} z^2(s, \vartheta_{-\tau}\omega) (\|g(s, \cdot)\|^2 + 1) ds \leq \eta. \tag{4.66}$$

Let  $N_0 = \max\{N_1, N_2, N_3\}$  and  $T = \max\{T_1, T_2\}$ . Then (4.64)-(4.66) are integrated into (4.59) to get that for all  $m > N_0$  and  $t \geq T$ ,

$$\|\nabla \tilde{v}_2(\tau, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{L^2(\mathcal{O}_{k\sqrt{2}})} \leq 4\eta. \tag{4.67}$$

Then by (3.11) and (4.67), we have

$$\begin{aligned}
 \|\nabla \tilde{u}_2(\tau, \tau - t, \vartheta_{-\tau}\omega, \tilde{u}_0)\|_{L^2(\mathcal{O}_{k\sqrt{2}})} \\
 & = z(-\tau, \omega) \|\nabla \tilde{v}_2(\tau, \tau - t, \vartheta_{-\tau}\omega, \tilde{v}_0)\|_{L^2(\mathcal{O}_{k\sqrt{2}})} \\
 & \leq C(\tau, \omega)\eta,
 \end{aligned}$$

for all  $m > N_0$  and  $t \geq T$ , which completes the proof. □

**Lemma 4.7.** *Assume that (3.1)–(3.5) hold. Let  $\tau \in \mathbb{R}, \omega \in \Omega$ . Then for every  $k > 0$ , the sequence  $\{\tilde{u}(\tau, \tau - t_n, \vartheta_{-\tau}\omega, \phi(\frac{x^2}{k^2})u_{0,n})\}_{n=1}^{\infty}$  has a convergent subsequence in  $H_0^1(\mathcal{O}_{k\sqrt{2}})$  whenever  $t_n \rightarrow +\infty$  and  $u_{0,n} \in B(\tau - t_n, \vartheta_{-t_n}\omega)$ .*

*Proof.* Given  $\eta > 0$ , by Lemma 4.6, there exists  $N_0 \in \mathbb{Z}^+$  such that as  $t_n \rightarrow +\infty$ ,

$$\|(I - P_{N_0})\tilde{u}(\tau, \tau - t_n, \vartheta_{-\tau}\omega, \phi(\frac{x^2}{k^2})u_{0,n})\|_{H^1(\mathcal{O}_{k\sqrt{2}})} \leq \eta. \tag{4.68}$$

By Lemma 4.1, we deduce that for  $t_n$  large enough,

$$\|P_{N_0}\tilde{u}(\tau, \tau - t_n, \vartheta_{-\tau}\omega, \phi(\frac{x^2}{k^2})u_{0,n})\|_{H^1(\mathcal{O}_{k\sqrt{2}})} \leq L_1(\tau, \omega, \varepsilon). \tag{4.69}$$

Note that

$$H^1(\mathcal{O}_{k\sqrt{2}}) = P_{N_0}H^1(\mathcal{O}_{k\sqrt{2}}) + (I - P_{N_0})H^1(\mathcal{O}_{k\sqrt{2}}),$$



but  $P_{N_0}H^1(\mathcal{O}_{k\sqrt{2}})$  is a finite dimensional space, which is compact. Then by (4.69), if  $n, m$  large enough,

$$\begin{aligned} & \left\| P_{N_0}\tilde{u}(\tau, \tau - t_n, \vartheta_{-\tau}\omega, \phi\left(\frac{x^2}{k^2}\right)u_{0,n}) \right. \\ & \left. - P_{N_0}\tilde{u}(\tau, \tau - t_m, \vartheta_{-\tau}\omega, \phi\left(\frac{x^2}{k^2}\right)u_{0,m}) \right\|_{H^1(\mathcal{O}_{k\sqrt{2}})} \leq \eta. \end{aligned} \quad (4.70)$$

Then it is easy to complete the proof using (4.68) and (4.70) and a standard argument.  $\square$

**4.4. Existence of pullback attractor in  $H^1(\mathbb{R}^N)$ .** In this subsection, we prove the existences of pullback attractors in  $H^1(\mathbb{R}^N)$  for problem (1.1) and (1.2) for every  $\varepsilon \in (0, 1]$ .

**Proposition 4.8.** *Assume that (3.1)-(3.5) hold. Then the cocycle  $\varphi$  defined by (3.10) is asymptotically compact in  $H^1(\mathbb{R}^N)$ ; i.e., for every  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ , the sequence  $\{\varphi(t, \tau - t_n, \vartheta_{-t}\omega, u_{0,n})\}_{n=1}^\infty$  has a convergent subsequence in  $H^1(\mathbb{R}^N)$  whenever  $t_n \rightarrow +\infty$  and  $u_{0,n} \in B = B(\tau - t_n, \vartheta_{-t_n}\omega)$  with  $B \in \mathfrak{D}$ .*

*Proof.* Given  $R > 0$ , we denote  $\mathcal{O}_R^c = \mathbb{R}^N - \mathcal{O}_R$ , where  $\mathcal{O}_R = \{x \in \mathbb{R}^N; |x| \leq R\}$ . By Proposition 4.4, for any  $\eta > 0$ , there exist  $R = R(\tau, \omega, \eta) > 0$  and  $N_1 = N_1(\tau, \omega, B, \eta) \in \mathbb{Z}^+$  such that for all  $n \geq N_1$ ,

$$\|v(\tau, \tau - t_n, \vartheta_{-\tau}\omega, z(\tau - t_n, \vartheta_{-\tau}\omega)u_{0,n})\|_{H^1(\mathcal{O}_R^c)} \leq \frac{\eta}{8}e^{-|\omega(-\tau)|}, \quad (4.71)$$

for every  $u_{0,n} \in B = B(\tau - t_n, \vartheta_{-t_n}\omega)$ . By (3.11) and (4.71), we have

$$\|u(\tau, \tau - t_n, \vartheta_{-\tau}\omega, z(\tau - t_n, \vartheta_{-\tau}\omega)u_{0,n})\|_{H^1(\mathcal{O}_R^c)} \leq \frac{\eta}{8}. \quad (4.72)$$

On the other hand, for this  $R$ , by Lemma 4.7, there exists  $N_2 = N_2(\tau, \omega, B, \eta) \geq N_1$  such that for all  $m, n \geq N_2$ ,

$$\begin{aligned} & \left\| u(\tau, \tau - t_n, \vartheta_{-\tau}\omega, \phi\left(\frac{x^2}{R^2}\right)u_{0,n}) \right. \\ & \left. - u(\tau, \tau - t_m, \vartheta_{-\tau}\omega, \phi\left(\frac{x^2}{R^2}\right)u_{0,m}) \right\|_{H_0^1(\mathcal{O}_{R\sqrt{2}})} \\ & \leq \frac{\eta}{8}. \end{aligned} \quad (4.73)$$

Then the desired result follows from (4.72) and (4.73) by a standard argument.  $\square$

Given  $\varepsilon \in (0, 1]$ , by Lemma 4.1, we deduce that the  $\mathfrak{D}$ -pullback absorbing set  $K_\varepsilon$  of  $\varphi_\varepsilon$  in  $L^2(\mathbb{R}^N)$  is defined by

$$K_\varepsilon = \{K_\varepsilon(\tau, \omega) = \{u \in L^2(\mathbb{R}^N); \|u\| \leq L_\varepsilon(\tau, \omega)\}; \tau \in \mathbb{R}, \omega \in \Omega\}, \quad (4.74)$$

where

$$L_\varepsilon(\tau, \omega) = \left( c \int_{-\infty}^0 e^{\lambda s} e^{-2\varepsilon\omega(s)} (\|g(s + \tau, \cdot)\|^2 + 1) \right)^{1/2}.$$

By Proposition 4.8 and Theorem 2.6, we have the following result.

**Theorem 4.9.** *Assume that (3.1)-(3.5) hold. Then for every fixed  $\varepsilon \in (0, 1]$ , the cocycle  $\varphi_\varepsilon$  defined by (3.10) possesses a unique  $\mathfrak{D}$ -pullback attractor  $\mathcal{A}_{\varepsilon, H^1}$  =  $\{\mathcal{A}_{\varepsilon, H^1}(\tau, \omega); \tau \in \mathbb{R}, \omega \in \Omega\}$  in  $H^1(\mathbb{R}^N)$ , given by*

$$\mathcal{A}_{\varepsilon, H^1}(\tau, \omega) = \overline{\bigcup_{t \geq s} \varphi_\varepsilon(t, \tau - t, \vartheta_{-t}\omega, K_\varepsilon(\tau - t, \vartheta_{-t}\omega))}^{H^1(\mathbb{R}^N)}, \quad \tau \in \mathbb{R}, \omega \in \Omega.$$

Furthermore,  $\mathcal{A}_{\varepsilon, H^1}$  is consistent with the  $\mathfrak{D}$ -pullback random attractor  $\mathcal{A}_\varepsilon$  in the space  $L^2(\mathbb{R}^N)$ , which is defined as in (3.13).

5. UPPER SEMI-CONTINUITY OF PULLBACK ATTRACTOR IN  $H^1(\mathbb{R}^N)$

From Theorem 4.9, for every  $\varepsilon \in (0, 1]$ , the cocycle  $\varphi_\varepsilon$  admits a common  $\mathfrak{D}$ -pullback attractor  $\mathcal{A}_\varepsilon$  in both  $L^2(\mathbb{R}^N)$  and  $H^1(\mathbb{R}^N)$ , where  $\mathfrak{D}$  is defined by (3.11). Then we may investigate the upper semi-continuity of  $\mathcal{A}_\varepsilon$  in both  $L^2(\mathbb{R}^N)$  and  $H^1(\mathbb{R}^N)$ . Note that [18] only proved the upper semi-continuity in  $L^2(\mathbb{R}^N)$  at  $\varepsilon = 0$ . In this section, we strengthen this study and prove that the upper semi-continuity of  $\mathcal{A}_\varepsilon$  may happen in the topology of  $H^1(\mathbb{R}^N)$  at  $\varepsilon = 0$ .

For the upper semi-continuity, we also give a further assumption as in [18], that is,  $f$  satisfies that for all  $x \in \mathbb{R}^N$  and  $s \in \mathbb{R}$ ,

$$\left| \frac{\partial}{\partial s} f(x, s) \right| \leq \alpha_4 |s|^{p-2} + \psi_4(x), \tag{5.1}$$

where  $\alpha_4 > 0$ ,  $\psi_4 \in L^\infty(\mathbb{R}^N)$  if  $p = 2$  and  $\psi_4 \in L^{\frac{p}{p-2}}(\mathbb{R}^N)$  if  $p > 2$ .

Let  $\varphi_0$  be the continuous cocycle associated with the problem (1.1) and (1.2) for  $\varepsilon = 0$ . That is to say,  $\varphi_0$  is a deterministic non-autonomous cocycle over  $\mathbb{R}$ . Denote by  $\mathfrak{D}_0$  the collection of some families of deterministic nonempty subsets of  $L^2(\mathbb{R}^N)$ :

$$\mathfrak{D}_0 = \{B = \{B(\tau) \subseteq L^2(\mathbb{R}^N); \tau \in \mathbb{R}\}; \lim_{t \rightarrow +\infty} e^{-\delta t} \|B(\tau - t)\| = 0, \tau \in \mathbb{R}, \delta < \lambda\},$$

where  $\lambda$  is as in (3.8). As a special case of Theorem 4.9, under the assumptions (3.1)-(3.5),  $\varphi_0$  has a common  $\mathfrak{D}_0$ -pullback attractor  $\mathcal{A}_0 = \{\mathcal{A}_0(\tau); \tau \in \mathbb{R}\}$  in both  $L^2(\mathbb{R}^N)$  and  $H^1(\mathbb{R}^N)$ .

To prove the upper semi-continuity of  $\mathcal{A}_\varepsilon$  at  $\varepsilon = 0$ , we have to check that the conditions (2.10)-(2.14) in Theorem 2.8 hold in  $L^2(\mathbb{R}^N)$  and  $H^1(\mathbb{R}^N)$  point by point. But (2.10)-(2.13) have been achieved, see [18, Corollary 7.2, Lemma 7.5 and equality (7.31)]. We only need to prove the condition (2.14) holds in  $H^1(\mathbb{R}^N)$ .

**Lemma 5.1.** *Assume that (3.1)-(3.5) hold. Then for every  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ , the union  $\cup_{\varepsilon \in (0,1]} \mathcal{A}_\varepsilon(\tau, \omega)$  is precompact in  $H^1(\mathbb{R}^N)$ .*

*Proof.* For any  $\eta > 0$ , it suffices to show that for every fixed  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ , the set  $\cup_{\varepsilon \in (0,1]} \mathcal{A}_\varepsilon(\tau, \omega)$  has finite  $\eta$ -nets in  $H^1(\mathbb{R}^N)$ . Let  $\chi = \chi(\tau, \omega) \in \cup_{\varepsilon \in (0,1]} \mathcal{A}_\varepsilon(\tau, \omega)$ . Then there exists a  $\varepsilon \in (0, 1]$  such that  $\chi(\tau, \omega) \in \mathcal{A}_\varepsilon(\tau, \omega)$ . By the invariance of  $\mathcal{A}_\varepsilon(\tau, \omega)$ , it follows that there is a  $u_0 \in \mathcal{A}_\varepsilon(\tau - t, \vartheta_{-t}\omega)$  such that (by (3.11))

$$\chi(\tau, \omega) = \varphi_\varepsilon(t, \tau - t, \vartheta_{-t}\omega, u_0) = u_\varepsilon(\tau, \tau - t, \vartheta_{-\tau}\omega, u_0) \quad \forall t \geq 0. \tag{5.2}$$

Given  $R > 0$ , denote  $\mathcal{O}_R^c = \mathbb{R}^N - \mathcal{O}_R$ , where  $\mathcal{O}_R = \{x \in \mathbb{R}^N; |x| \leq R\}$ . Note that  $\mathcal{A}_\varepsilon(\tau, \omega) \in \mathfrak{D}$ . Then by Proposition 4.4, for every  $\eta > 0$ , there exist  $T = T(\tau, \omega, \eta) \geq 2$  and  $R = R(\tau, \omega, \eta) > 1$  such that the solution  $u$  of problem (1.1) and (1.2) satisfies

$$\|u_\varepsilon(\tau, \tau - t, \vartheta_{-\tau}\omega, u_0)\|_{H^1(\mathcal{O}_R^c)} \leq \eta, \quad \forall t \geq T. \tag{5.3}$$

Then by (5.2)-(5.3), we have

$$\|\chi(\tau, \omega)\|_{H^1(\mathcal{O}_R^c)} \leq \eta, \quad \text{for all } \chi \in \cup_{\varepsilon \in (0,1]} \mathcal{A}_\varepsilon(\tau, \omega). \tag{5.4}$$

On the other hand, by Lemma 4.6, there exist a projector  $P_{N_0}$  and  $T = T(\tau, \omega, \eta) \geq 2$  such that for all  $t \geq T$ ,

$$\|(I - P_{N_0})\tilde{u}_\varepsilon(\tau, \tau - t, \vartheta_{-\tau}\omega, \tilde{u}_0)\|_{H_0^1(\mathcal{O}_{R\sqrt{2}})} \leq \eta, \tag{5.5}$$

where  $\tilde{u}_\varepsilon$  is the cut-off of  $u_\varepsilon$  on the domain  $\mathcal{O}_{R\sqrt{2}}$ , by (4.52). Because  $P_{N_0}\tilde{u}_\varepsilon \in H_{N_0}$ , where  $H_{N_0} = \text{span}\{e_{1,2}, \dots, e_{N_0}\}$  is a finite dimension space and  $P_{N_0}\tilde{u}_\varepsilon(\tau, \tau - t, \vartheta_{-\tau}\omega, \tilde{u}_0)$  is bounded in  $H_{N_0}$  which is compact. Therefore there exist finite points  $v_1, v_2, \dots, v_s \in H_{N_0}$  such that

$$\|P_{N_0}\tilde{u}_\varepsilon(\tau, \tau - t, \vartheta_{-\tau}\omega, \tilde{u}_0) - v_i\|_{H_0^1(\mathcal{O}_{R\sqrt{2}})} \leq \eta. \quad (5.6)$$

Thus by (5.2), the inequalities (5.5) and (5.6) are rewritten as

$$\|(I - P_{N_0})\chi(\tau, \omega)\|_{H_0^1(\mathcal{O}_{R\sqrt{2}})} \leq \eta, \quad \|P_{N_0}\chi(\tau, \omega) - v_i\|_{H_0^1(\mathcal{O}_{R\sqrt{2}})} \leq \eta, \quad (5.7)$$

for all  $\chi \in \cup_{\varepsilon \in (0,1]} \mathcal{A}_\varepsilon(\tau, \omega)$ . We now define  $\tilde{v}_i = \tilde{v}_i(x) = 0$  if  $x \in \mathcal{O}_{R\sqrt{2}}^c$  and  $\tilde{v}_i = v_i$  if  $x \in \mathcal{O}_{R\sqrt{2}}$ . Then for every  $i = 1, 2, \dots, s$ ,  $\tilde{v}_i \in H^1(\mathbb{R}^N)$ . Furthermore, by (5.4) and (5.7), we have

$$\begin{aligned} \|\chi(\tau, \omega) - \tilde{v}_i\|_{H^1(\mathbb{R}^N)} &\leq \|\chi(\tau, \omega) - \tilde{v}_i\|_{H^1(\mathcal{O}_{R\sqrt{2}}^c)} + \|\chi(\tau, \omega) - \tilde{v}_i\|_{H_0^1(\mathcal{O}_{R\sqrt{2}})} \\ &\leq \|\chi(\tau, \omega)\|_{H^1(\mathcal{O}_{R\sqrt{2}}^c)} + \|P_{N_0}\chi(\tau, \omega) - \tilde{v}_i\|_{H_0^1(\mathcal{O}_{R\sqrt{2}})} \\ &\quad + \|(I - P_{N_0})\chi(\tau, \omega)\|_{H_0^1(\mathcal{O}_{R\sqrt{2}})} \leq 3\eta, \end{aligned}$$

for all  $\chi \in \cup_{\varepsilon \in (0,1]} \mathcal{A}_\varepsilon(\tau, \omega)$ . Thus  $\cup_{\varepsilon \in (0,1]} \mathcal{A}_\varepsilon(\tau, \omega)$  has finite  $\eta$ -nets in  $H^1(\mathbb{R}^N)$ , which implies that the union  $\cup_{\varepsilon \in (0,1]} \mathcal{A}_\varepsilon(\tau, \omega)$  is precompact in  $H^1(\mathbb{R}^N)$ .  $\square$

Then we obtain that the family of random attractors  $\mathcal{A}_\varepsilon$  indexed by  $\varepsilon$  converges to the deterministic  $\mathcal{A}_0$  in  $H^1(\mathbb{R}^N)$  in the following sense.

**Theorem 5.2.** *Assume that (3.1)-(3.5) and (5.1) hold. Then for each  $\tau \in \mathbb{R}$  and  $\omega \in \Omega$ ,*

$$\lim_{\varepsilon \downarrow 0} \text{dist}_{H^1}(\mathcal{A}_\varepsilon(\tau, \omega), \mathcal{A}_0(\tau)) = 0,$$

where  $\text{dist}_{H^1}$  is the Hausdorff semi-metric in  $H^1(\mathbb{R}^N)$ .

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