

## OSCILLATION CRITERIA FOR FIRST-ORDER NONLINEAR NEUTRAL DELAY DIFFERENTIAL EQUATIONS

ELMETWALLY M. ELABBASY, TAHER S. HASSAN, SAMIR H. SAKER

ABSTRACT. Oscillation criteria are obtained for all solutions of first-order nonlinear neutral delay differential equations. Our results extend and improve some results well known in the literature. Some examples are considered to illustrate our main results.

### 1. INTRODUCTION

In recent years, the literature on the oscillation of neutral delay differential equations has grown very rapidly. It is a relatively new field with interesting applications in real world life problems. In fact, neutral delay differential equations appear in modelling of the networks containing lossless transmission lines (as in high-speed computers where the lossless transmission lines are used to interconnect switching circuits), in the study of vibrating masses attached to an elastic bar, as the Euler equation in some variational problems, in the theory of automatic control and in neuro-mechanical systems in which inertia plays an important role. See Hale [17], Driver [8], Brayton and Willoughby [6], Popove [32], and Boe and Chang [5], and the references cited therein. Also this is evident by the number of references in the recent books by Ladde et al. [14] and by Ladas [16].

We consider a general first-order nonlinear neutral delay differential equation

$$(x(t) - q(t)x(t - r))' + f(t, x(\tau(t))) = 0, \quad (1.1)$$

where for  $t \geq t_0$

$$q, \tau \in C([t_0, \infty), \mathbb{R}^+), \quad q(t) \neq 1, \quad r \in (0, \infty), \quad \tau(t) < t, \quad \lim_{t \rightarrow \infty} \tau(t) = \infty, \quad (1.2)$$

$$f \in C([t_0, \infty) \times \mathbb{R}, \mathbb{R}), \quad uf(t, u) \geq 0, \quad (1.3)$$

$$\sum_{i=1}^n \prod_{j=1}^i \frac{1}{q(t_j)} \rightarrow \infty \quad \text{as } n \rightarrow \infty. \quad (1.4)$$

we assume that the nonlinear function  $f(t, u)$  in (1.1) satisfies the following conditions:

- (H) There are a piecewise continuous function  $p : [t_0, \infty) \rightarrow \mathbb{R}^+ = [0, \infty)$ , a function  $g \in C(\mathbb{R}, \mathbb{R}^+)$ , and a number  $\varepsilon_0 > 0$  such that

---

2000 *Mathematics Subject Classification.* 34K15, 34C10.

*Key words and phrases.* Oscillation; non-oscillation; neutral delay of differential equations.

©2005 Texas State University - San Marcos.

Submitted August 2, 2005. Published November 30, 2005.

- (i)  $g$  is nondecreasing on  $\mathbb{R}^+$
- (ii)  $g(-u) = g(u)$ ,  $\lim_{u \rightarrow 0} g(u) = 0$ ,
- (iii)  $\int_0^\infty g(e^{-u}) du < \infty$ ,
- (iv)  $\frac{1}{|u|} |f(t, u) - p(t)u| \leq p(t)g(u)$  for  $t \geq t_0$  and  $0 < |u| < \varepsilon_0$ ,
- (v) For each  $\varphi \in C([t_0, \infty), \mathbb{R})$  with  $\lim_{t \rightarrow \infty} \varphi(t) > 0$ ,

$$\int_{t_0}^\infty \int f(t, \varphi(\tau(t))) dt = \infty, \quad \int_{t_0}^\infty \int f(t, -\varphi(\tau(t))) dt = -\infty.$$

As usual a solution  $x(t)$  of equation (1.1) is said to be oscillatory if it has arbitrarily large zeros in  $[t_0, \infty)$ . Otherwise it is nonoscillatory and the equation (1.1) is called oscillatory if every solution of this equation is oscillatory.

When  $q(t) = 0$ , (1.1) reduces to

$$x'(t) + f(t, x(\tau(t))) = 0,$$

which was studied by Tang and Shen [36]. They obtained some infinite integral sufficient conditions for oscillations.

The oscillatory behavior of other neutral delay differential equations have been investigated by many authors, see [1, 2, 3, 4, 9, 10, 12, 13, 14, 15, 16, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 33, 37, 38, 39, 40] and references therein.

In recent papers Elabbasy and Saker [10], Kubiacyk and Saker [22] obtained an infinite integral conditions for oscillation of the linear neutral delay differential equation

$$(x(t) - q(t)x(t - r))' + p(t)x(t - \tau) = 0.$$

Let  $\delta(t) = \max\{\tau(t) : t_0 \leq s \leq t\}$  and  $\delta^{-1}(t) = \min\{s \geq t_0 : \delta(s) = t\}$ . Clearly,  $\delta$  and  $\delta^{-1}$  are non-decreasing and satisfy

- (A)  $\delta(t) < t$  and  $\delta^{-1}(t) > t$
- (B)  $\delta(\delta^{-1}(t)) = t$  and  $\delta^{-1}(\delta(t)) \leq t$ .

Let  $\delta^{-k}(t)$  be defined on  $[t_0, \infty)$  by

$$\delta^{-(k+1)}(t) = \delta^{-1}(\delta^{-k}(t)), \quad k = 1, 2, \dots \quad (1.5)$$

Throughout this paper, we use the sequence  $\{p_k\}$ , of functions defined by

$$p_1(t) = \int_t^{\delta^{-1}(t)} p(s) ds, \quad t \geq t_0,$$

$$p_{k+1}(t) = \int_t^{\delta^{-1}(t)} p(s) p_k(s) ds, \quad t \geq t_0, \quad k = 1, 2, \dots$$

Our main results are the following.

**Theorem 1.1.** *Assume that (1.2), (1.4), (1.3), and (H) hold, and there exist a bounded positive function  $\sigma(t)$  such that*

$$\int_{\tau(t)}^t B(s) ds > \frac{1}{e}, \quad (1.6)$$

and

$$\int_{t_0}^\infty p(t) \sigma(t) \left[ \exp \left( \int_{\tau(t)}^t p(s) ds - \frac{\sigma(t)}{e} \right) - 1 \right] dt = \infty, \quad (1.7)$$

where  $B(t) = p(t)/\sigma(t)$ . Then every solution of (1.1) oscillates.

**Theorem 1.2.** Assume that (1.2), (1.4), (1.3) and (H) hold, and that

$$\liminf_{t \rightarrow \infty} \int_{\tau(t)}^t p(s) ds \geq 0. \quad (1.8)$$

and suppose that there exists a positive integer  $n$  such that

$$\int_{t_0}^{\infty} p(t) \ln(e^{n-1} p_n(t) + 1) dt = \infty. \quad (1.9)$$

Then every solution of (1.1) oscillates.

**Corollary 1.3.** Assume that (1.2) (1.3), (1.4), (1.8) and (H) hold, and that

$$\int_{t_0}^{\infty} p(t) \left[ \exp \left( \int_{\tau(t)}^t p(s) ds \right) - 1 \right] dt = \infty. \quad (1.10)$$

Then every solution of (1.1) oscillates.

**Corollary 1.4.** Assume that (1.2), (1.3), (1.4), (1.8) and (H) hold, and that

$$\int_{t_0}^{\infty} p(t) \ln \left( \int_t^{\delta^{-1}(t)} p(s) ds + 1 \right) dt = \infty.$$

Then every solution of (1.1) oscillates.

**Corollary 1.5.** Assume that (1.2), (1.3), (1.4), (1.8) and (H) hold, and suppose that there exists a positive integer  $n$  such that

$$\int_{t_0}^{\infty} p(t) \ln(e^n p_n(t)) dt = \infty.$$

Then every solution of (1.1) oscillates.

Note that if

$$\limsup_{t \rightarrow \infty} \int_{\tau(t)}^t p(s) ds > 2,$$

then by Lemma 2.4 every solution of (1.1) oscillates. Thus, we will consider the case

$$\limsup_{t \rightarrow \infty} \int_{\tau(t)}^t p(s) ds \leq 2.$$

This implies that for some  $\epsilon > 0$  and large  $t$ ,

$$\int_{\tau(t)}^t p(s) ds \leq 2 + \epsilon.$$

Thus we have

$$\liminf_{t \rightarrow \infty} p_k(t) \leq (2 + \epsilon)^{k-1} \liminf_{t \rightarrow \infty} \int_t^{\delta^{-1}(t)} p(s) ds \leq (2 + \epsilon)^{k-1} \liminf_{t \rightarrow \infty} \int_{\tau(t)}^t p(s) ds.$$

As a result, by Theorem 1.2 we have

**Corollary 1.6.** Assume that (1.2), (1.3), (1.4) and (H) hold, and that there exists a positive integer  $n$  such that

$$\liminf_{t \rightarrow \infty} p_n(t) > 0.$$

Then every solution of (1.1) oscillates.

The proofs of the above Theorems and also some Lemmas to be used in these proofs will be given in the next two sections. Some examples which illustrate and the advantage of our results will be given in section 4.

## 2. PRELIMINARY LEMMAS

**Lemma 2.1.** *Assume that (1.2), (1.4) and (1.3) hold. Let  $x(t)$  be an eventually positive solution of 1.1 and set*

$$z(t) = x(t) - q(t)x(t-r). \quad (2.1)$$

*Then  $z(t)$  is eventually nonincreasing and positive function.*

*Proof.* From (1.1), (1.3), we have  $z'(t) = -f(t, x(\tau(t))) \leq 0$  eventually. We prove that  $z(t)$  is a positive function. If not, then there exist  $T \geq t_0$  and  $\alpha < 0$  such that  $z(t) < \alpha$  for  $t \geq T$ . Then from (2.1), we have  $x(t) < \alpha + q(t)x(t-r)$  which implies

$$x(t+r) < \alpha + q(t+r)x(t).$$

Now we choose  $k$  such that  $t_k = t^* + kr > T$ . Then  $x(t_{k+1}) < \alpha + q(t_{k+1})x(t_k)$ . Applying this inequality by induction, it gives

$$x(t_n) < \alpha \left[ 1 + \sum_{i=k+2}^n \prod_{j=0}^{n-i} q(t_{n-j}) \right] + \prod_{i=k+1}^n q(t_i)x(t_k).$$

Now define  $q_n$  and  $d_n$  by

$$q_n = 1 + \sum_{i=k+2}^n \prod_{j=0}^{n-i} q(t_{n-j}), \quad d_n = \prod_{i=k+1}^n q(t_i),$$

and let

$$s_n = \sum_{i=1}^n \prod_{j=1}^i \frac{1}{q(t_j)}.$$

Then

$$s_n^* = \frac{q_n}{d_n} = \left( s_n - \sum_{i=1}^{k+1} \prod_{j=1}^i \frac{1}{q(t_j)} \right) q(t_{k+1}) \dots q(t_1) \rightarrow \infty \quad \text{as } n \rightarrow \infty,$$

by condition (1.4). Using the above inequality,

$$x(t_n) < \left[ s_n^* + \frac{x(t_k)}{\alpha} \right] \alpha d_n \rightarrow -\infty \quad \text{as } n \rightarrow \infty,$$

and this contradicts the assumption that  $x(t) > 0$ . Then  $z(t)$  must be positive function. The proof is complete.  $\square$

Note that the proof of Lemma 2.1 is similar to that in [7, Lemma 1]; we state it here for the sake of completeness.

**Lemma 2.2.** *Assume that (1.2), (1.3), (1.4) and (H) hold. Then every non-oscillatory solution of (1.1) converges to zero monotonically for large  $t$  as  $t \rightarrow \infty$ .*

*Proof.* Suppose that  $x(t)$  is a non-oscillatory solution of equation (1.1) which we shall assume to be eventually positive [If  $x(t)$  is eventually negative the proof is similar]. From Lemma 2.1, we have  $z(t)$  is eventually non-increasing and positive function.

Choose a  $t_1 \geq t_0$  such that  $x(t) > 0$ ,  $z(t) > 0$  for  $t \geq t_1$ . It follows from equations (1.1)-(1.3) and (H) that there exists  $t_2 > t_1$  such that  $\tau(t) \geq t_1$  and  $z'(t) \leq 0$  for  $t > t_2$ . Hence the following limits exist and

$$\lim_{t \rightarrow \infty} x(t) \geq \lim_{t \rightarrow \infty} z(t) = \alpha \geq 0.$$

If  $\alpha > 0$ , then from (1.1) we have

$$z(t) - z(t_0) = - \int_{t_0}^t f(t, x(\tau(s))) ds.$$

It follows from assumption (H)(v) that  $\lim_{t \rightarrow \infty} z(t) = -\infty$ , which contradicts that  $z(t)$  being positive function, then  $\alpha = 0$ , from (1.2), we have  $\lim_{t \rightarrow \infty} x(t) = 0$ . The proof of Lemma 2.2 is complete.  $\square$

**Lemma 2.3.** *Assume that (1.2), 1.3, (1.4) and (H) hold. If  $x(t)$  is a nonoscillatory solution of (1.1), then there exist  $A > 0$ ,  $\varepsilon > 0$  and  $T \in (0, \infty)$  such that for  $t \geq T$ ,*

$$|x(t)| \leq A \exp \left( - \frac{1}{2} \int_T^t p(s) ds \right) + \varepsilon, \quad (2.2)$$

*Proof.* We shall assume  $x(t)$  to be eventually positive [If  $x(t)$  is eventually negative the proof is similar]. By Lemma 2.2, there exists  $t_1 > 0$  such that

$$0 < x(t) \leq x(\tau(t)) < \varepsilon \quad \text{for } t \geq t_1.$$

From (H), we find that for  $t \geq t_1$

$$f(t, x(\tau(t))) \geq p(t)[1 - g(x(\tau(t)))]x(\tau(t)),$$

and  $\lim_{t \rightarrow \infty} x(t) = 0$ . By assumption (H), there exists  $T > t_1$  such that for  $t \geq T$ ,

$$f(t, x(\tau(t))) \geq \frac{1}{2}p(t)x(\tau(t)) \geq \frac{1}{2}p(t)x(t),$$

and it follows from (1.1) that for  $t \geq T$ ,

$$(x(t) - q(t)x(t-r))' + \frac{1}{2}p(t)x(t) \leq 0, \quad z'(t) + \frac{1}{2}p(t)z(t) \leq 0,$$

where  $z(t) = x(t) - q(t)x(t-r)$ . This yields, for  $t \geq T$ ,

$$\begin{aligned} z(t) &\leq A \exp \left[ - \frac{1}{2} \int_T^t p(s) ds \right], \\ |x(t)| &\leq A \exp \left( - \frac{1}{2} \int_T^t p(s) ds \right) + \varepsilon, \end{aligned}$$

where  $A = x(T) - q(T)x(T-r)$ .  $\square$

**Lemma 2.4.** *Assume that (1.2), 1.3, (1.4) and (H) hold. If equation (1.1) has a nonoscillatory solution, then*

$$\int_{\tau(t)}^t p(s) ds \leq 2 \quad \text{and} \quad p_k(t) \leq 2^k, \quad k = 1, 2, \dots \quad (2.3)$$

*eventually.*

*Proof.* Suppose that  $x(t)$  is a nonoscillatory solution of equation (1.1) which we shall assume to be eventually positive [if  $x(t)$  is eventually negative the proof is similar]. By Lemma 2.2, there exists  $T \geq 0$  such that

$$\begin{aligned} x(\tau(t)) &\geq x(t) > 0 \quad \text{for } t \geq T, \\ (x(t) - q(t)x(t-r))' + \frac{1}{2}p(t)x(\tau(t)) &\leq 0, \\ z'(t) + \frac{1}{2}p(t)z(\tau(t)) &\leq 0 \quad \text{for } t \geq T. \end{aligned} \quad (2.4)$$

Integrating both sides from  $\tau(t)$  to  $t$  yields

$$z(t) - z(\tau(t)) + \frac{1}{2} \int_{\tau(t)}^t p(s)z(\tau(s))ds \leq 0 \quad \text{for } t \geq T.$$

By the decreasing nature of  $z(t)$  for large  $t$  and the increasing nature of  $\tau(t)$ , there exists  $T_1 \geq T$  such that

$$z(t) - z(\tau(t)) + \frac{1}{2}z(\tau(t)) \int_{\tau(t)}^t p(s)ds \leq 0 \quad \text{for } t \geq T_1.$$

Then,  $\int_{\tau(t)}^t p(s)ds \leq 2$ .

Also, integrating both sides of equation (2.4) from  $t$  to  $\delta^{-1}(t)$  yields

$$z(\delta^{-1}(t)) - z(t) + \frac{1}{2} \int_t^{\delta^{-1}(t)} \delta^{-1}(t)p(s)z(\tau(s))ds \leq 0 \quad \text{for } t \geq T.$$

By the decreasing nature of  $z(t)$  for large  $t$  and the increasing nature of  $\tau(t)$ , there exists  $T_1 \geq T$  such that

$$z(\delta^{-1}(t)) - z(t) + \frac{1}{2} \left( \int_t^{\delta^{-1}(t)} p(s)ds \right) z(\tau(\delta^{-1}(t))) \leq 0 \quad \text{for } t \geq T_1.$$

or

$$z(\delta^{-1}(t)) - z(t) + \frac{1}{2} \left( \int_t^{\delta^{-1}(t)} p(s)ds \right) z(t) \leq 0 \quad \text{for } t \geq T_1.$$

Then, we have

$$p_1(t) = \int_t^{\delta^{-1}(t)} p(s)ds \leq 2.$$

By iteration we deduce, from this, that  $p_k(t) \leq 2^k$  which shows that (2.3) holds for  $t \geq T_1$ . The proof of Lemma 2.4 is complete.  $\square$

**Lemma 2.5.** *Assume that (1.2), (1.3), (1.8), (1.4) and (H) hold. If  $x(t)$  is a nonoscillatory solution of equation (1.1), then  $\frac{z(\tau(t))}{z(t)}$  is well defined for large  $t$  and is bounded.*

*Proof.* Suppose that  $x(t)$  is a nonoscillatory solution of equation (1.1) which we shall assume to be eventually positive [if  $x(t)$  is eventually negative the proof is similar]. By the same argument as in the proof of Lemma 2.3, there exists  $T > 0$ , such that

$$\begin{aligned} x(\tau(t)) &\geq x(t) > 0 \quad \text{for } t \geq T, \\ (x(t) - q(t)x(t-\sigma))' + \frac{1}{2}p(t)x(\tau(t)) &\leq 0, \end{aligned}$$

$$z'(t) + \frac{1}{2}p(t)z(\tau(t)) \leq 0 \quad \text{for } t \geq T.$$

The rest of the proof is similar to in [28, Lemma 5], and thus it is omitted.  $\square$

### 3. PROOFS OF THEOREMS

**Proof of Theorem 1.1.** Assume that (1.1) has a nonoscillatory solution  $x(t)$  which will be assumed to be eventually positive (if  $x(t)$  is eventually negative the proof is similar). By Lemma 2.2, there exists  $t_1 \geq t_0$  such that

$$0 < x(t) \leq x(\tau(t)) < \varepsilon_0, \quad g(x(\tau(t))) < 1, \quad t \geq t_1, \quad (3.1)$$

where  $\varepsilon_0$  is given by assumption (H). From (3.1) and (H), we have

$$f(t, x(\tau(t))) \geq p(t)[1 - g(x(\tau(t)))]x(\tau(t)), \quad t \geq t_1. \quad (3.2)$$

Set

$$\omega(t) = \frac{\sigma(t)z(\tau(t))}{z(t)} \quad \text{for } t \geq t_1.$$

From Lemmas 2.1 and 2.2,  $\omega(t) \geq \sigma(t)$  for  $t \geq t_1$ . From (1.1) and (3.2), we have

$$\frac{z'(t)}{z(t)} + B(t)\omega(t)[1 - g(x(\tau(t)))] \leq 0, \quad t \geq t_1. \quad (3.3)$$

Let  $t_2 > t_1$  be such that  $\tau(t) \geq t_1$  for  $t \geq t_2$ . Integrating both sides of (3.3) from  $\tau(t)$  to  $t$ , we obtain

$$\omega(t) \geq \sigma(t) \exp\left(\int_{\tau(t)}^t B(s)\omega(s)[1 - g(x(\tau(s)))]ds\right), \quad t \geq t_2. \quad (3.4)$$

By (1.6), for  $t \geq t_2$ , we have

$$\int_{\delta(t)}^t p(s)ds = \int_{\tau(t^*)}^t p(s)ds \geq \int_{\tau(t^*)}^{t^*} p(s)ds \geq e^{-1}, \quad (3.5)$$

where  $t^* \in [t_0, t]$  with  $\tau(t^*) = \delta(t)$ . From (1.6) and (3.4), we find that for  $t \geq t_2$ ,

$$\begin{aligned} \omega(t) &\geq \sigma(t) \exp\left(\int_{\tau(t)}^t B(s)(\omega(s) - \sigma(t))ds + \frac{\sigma(t)}{e}\right) \\ &\quad \times \exp\left(\int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e}\right) \exp\exp\left(-\int_{\tau(t)}^t B(s)\omega(s)g(x(\tau(s)))ds\right) \\ &\geq \sigma(t)\left(e \int_{\delta(t)}^t B(s)(\omega(s) - \sigma(t))ds + \sigma(t)\right) \exp\left(\int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e}\right) \\ &\quad \times \exp\left(-\int_{\tau(t)}^t B(s)\omega(s)g(x(\tau(s)))ds\right). \end{aligned}$$

Let  $v(t) = \omega(t) - \sigma(t)$  for  $t \geq t_1$ . Then  $v(t) \geq 0$  for  $t \geq t_1$ , and so for  $t \geq t_2$ ,

$$\begin{aligned} v(t) - e \int_{\delta(t)}^t B(s)v(s)ds \\ &\geq \left(e \int_{\delta(t)}^t B(s)v(s)ds + \sigma(t)\right) \left[\sigma(t) \exp\left(\int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e}\right)\right. \\ &\quad \left. \times \exp\left(-\int_{\tau(t)}^t B(s)\omega(s)g(x(\tau(s)))ds\right) - 1\right], \end{aligned}$$

that is, for  $t \geq t_2$ ,

$$\begin{aligned} & B(t)v(t) - B(t)e \int_{\delta(t)}^t B(s)v(s)ds \\ & \geq B(t) \left( e \int_{\delta(t)}^t B(s)v(s)ds + \sigma(t) \right) \left[ \sigma(t) \exp \left( \int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e} \right) \right. \\ & \quad \left. \times \exp \left( - \int_{\tau(t)}^t B(s)\omega(s)g(x(\tau(s)))ds \right) - 1 \right]. \end{aligned} \quad (3.6)$$

By Lemmas 2.1-2.5, there exist  $T > t_2$ ,  $A > 0$ ,  $\varepsilon > 0$  and  $M > 0$  such that for  $t \geq T$ ,

$$x(\tau(t)) \leq A \exp \left( - \frac{1}{2} \int_T^{\tau(t)} p(s)ds \right) + \varepsilon, \quad (3.7)$$

$$\int_{\tau(t)}^t p(s)ds \leq 2, \quad (3.8)$$

$$\omega(t) \leq \sigma(t)M, \quad \sigma(t) \leq \eta. \quad (3.9)$$

Let

$$\alpha(t) = \frac{1}{2} \int_T^t p(s)ds, \quad t \geq T.$$

Clearly, (1.6) implies that  $\alpha(t) \rightarrow \infty$  as  $t \rightarrow \infty$ . For  $t \geq t_2$ , set

$$\begin{aligned} D(t) &= p(t) \left( e \int_{\delta(t)}^t B(s)v(s)ds + \sigma(t) \right) \exp \left( \int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e} \right) \\ & \quad \times \left[ 1 - \exp \left( - \int_{\tau(t)}^t B(s)\omega(s)g(x(\tau(s)))ds \right) \right]. \end{aligned} \quad (3.10)$$

One can easily see that

$$0 \leq 1 - e^{-c} \leq c \quad \text{for } c \geq 0. \quad (3.11)$$

It follows from (3.10) that for  $t \geq t_2$ ,

$$\begin{aligned} D(t) &\leq p(t) \left( e \int_{\delta(t)}^t B(s)v(s)ds + \sigma(t) \right) \exp \left( \int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e} \right) \\ & \quad \times \int_{\tau(t)}^t B(s)\omega(s)g(x(\tau(s)))ds. \end{aligned} \quad (3.12)$$

Therefore,

$$\begin{aligned} & D(t) \\ & \leq p(t) \left( e \int_{\delta(t)}^t B(s)v(s)ds + \sigma(t) \right) \exp \left( \int_{\tau(t)}^t p(s)ds \right) \int_{\tau(t)}^t B(s)\omega(s)g(x(\tau(s)))ds. \end{aligned}$$

Let  $T^* > T$  be such that  $\tau(\tau(t)) \geq T$  for  $t \geq T^*$  and  $\alpha(T^*) > 2 + \ln A$ . Set  $M_1 = e^2\eta M[2e(M-1) + \eta]$  and  $A_1 = eA$ . Noting that

$$e \int_{\delta(t)}^t B(s)v(s)ds + \sigma(t) \leq 2e(M-1) + \eta \quad \text{for } t \geq T.$$



from (3.7)–(3.9), (3.12), and assumption (H), we obtain  $N \geq T^*$ ,

$$\begin{aligned}
& \int_{T^{\alpha_{st}}}^N D(t) dt \\
& \leq M_1 \int_{T^{\alpha_{st}}}^N p(t) \int_{\tau(t)}^t p(s) g\left(A \exp\left(\frac{1}{2} \int_T^{\tau(t)} p(s) ds\right) + \varepsilon\right) ds dt \\
& = M_1 \int_{T^{\alpha_{st}}}^N p(t) \int_{\tau(t)}^t p(s) g\left(A \exp\left(-\frac{1}{2} \int_T^s p(\mu) d\mu + \frac{1}{2} \int_{\tau(s)}^s p(\mu) d\mu\right) + \varepsilon\right) ds dt \\
& \leq M_1 \int_{T^{\alpha_{st}}}^N p(t) \int_{\tau(t)}^t p(s) g\left(A_1 e^{-\alpha(s)} + \varepsilon\right) ds dt \\
& = 2M_1 \int_{T^{\alpha_{st}}}^N p(t) \int_{\alpha(\tau(t))}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du dt \\
& = 2M_1 \int_{T^{\alpha_{st}}}^N p(t) \int_{\alpha(t) - \beta(t)}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du dt, \quad \beta(t) = \frac{1}{2} \int_{\tau(t)}^t p(s) ds \\
& \leq 4M_1 \int_{\alpha(T^*)}^{\alpha(N)} p(t) \int_{v-1}^v g(A_1 e^{-u} + \varepsilon) du dv \\
& \leq 4M_1 \int_{\alpha(T^*)-1}^{\alpha(N)} g(A_1 e^{-u} + \varepsilon) du \\
& = 4M_1 \int_{\ln(A_1 e^{1-\alpha(T^*)} + \varepsilon)^{-1}}^{\ln(A_1 e^{-\alpha(N)} + \varepsilon)^{-1}} g(e^{-u}) \frac{e^{-u}}{e^{-u} - \varepsilon} du \\
& \leq 4M_1 \int_0^{\alpha(N)} g(e^{-u}) \frac{e^{-u}}{e^{-u} - \varepsilon} du \\
& \leq 4M_1 \int_0^\infty g(e^{-u}) du < \infty.
\end{aligned}$$

and

$$\int_T^\infty D(t) dt < \infty. \tag{3.13}$$

Substituting (3.10) into (3.6), for  $t \geq t_2$ , we obtain

$$\begin{aligned}
& B(t)v(t) - eB(t) \int_{\delta(t)}^t B(s)v(s) ds \\
& \geq p(t) \left( e \int_{\delta(t)}^t B(s)v(s) ds + \sigma(t) \right) \left[ \exp\left(\int_{\tau(t)}^t p(s) ds - \frac{\sigma(t)}{e}\right) - 1 \right] - D(t),
\end{aligned}$$

$$\begin{aligned}
& B(t)v(t) - eB(t) \int_{\delta(t)}^t B(s)v(s) ds \\
& \geq p(t)\sigma(t) \left[ \exp\left(\int_{\tau(t)}^t p(s) ds - \frac{\sigma(t)}{e}\right) - 1 \right] - D(t).
\end{aligned}$$

Integrating both sides from  $T^*$  to  $N > \tau^{-1}(T^*)$ , we have

$$\begin{aligned} & \int_{T^*}^N B(t)v(t)dt - e \int_{T^*}^N B(t) \int_{\delta(t)}^t B(s)v(s) ds dt \\ & \geq \int_{T^*}^N p(t)\sigma(t) \left[ \exp \left( \int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e} \right) - 1 \right] dt - \int_{T^*}^N D(t)dt. \end{aligned} \quad (3.14)$$

By interchanging the order of integrations and by (3.5), we have

$$\begin{aligned} e \int_{T^*}^N B(t) \int_{\delta(t)}^t B(s)v(s) ds dt & \geq e \int_{T^*}^{\delta(N)} B(t)v(t) \int_t^{\delta^{-1}(t)} B(s) ds dt \\ & \geq \int_{T^*}^{\delta(N)} B(t)v(t)dt. \end{aligned} \quad (3.15)$$

From this and (3.14), it follows that

$$\int_{\delta(N)}^N B(t)v(t)dt \geq \int_{T^*}^N p(t)\sigma(t) \left[ \exp \left( \int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e} \right) - 1 \right] dt - \int_{T^*}^N D(t)dt. \quad (3.16)$$

By (3.8) and (3.9),

$$\int_{\delta(N)}^N B(t)v(t)dt \leq (M-1) \int_{\delta(N)}^N p(t)dt \leq (M-1) \int_{\tau(N)}^N p(t)dt \leq 2(M-1),$$

and so by (3.16),

$$2(M-1) \geq \int_{T^*}^N p(t)\sigma(t) \left[ \exp \left( \int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e} \right) - 1 \right] dt - \int_{T^*}^N D(t)dt.$$

This implies that

$$2(M-1) \geq \int_{T^*}^{\infty} p(t)\sigma(t) \left[ \exp \left( \int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e} \right) - 1 \right] dt - \int_{T^*}^{\infty} D(t)dt,$$

which together with (3.13) yields

$$\int_{T^*}^{\infty} p(t)\sigma(t) \left[ \exp \left( \int_{\tau(t)}^t p(s)ds - \frac{\sigma(t)}{e} \right) - 1 \right] dt < \infty.$$

This contradicts (1.7) and so the proof is complete.

**Proof of Theorem 1.2.** Assume that (1.1) has a nonoscillatory solution  $x(t)$  which will be assumed to be eventually positive (if  $x(t)$  is eventually negative the proof is similar). By Lemma 2.1 and assumption (H), there exists  $t_0^* \geq t_0$  such that

$$0 < x(t) \leq x(\delta(t)) \leq x(\tau(t)) < \varepsilon_0, \quad g(x(\tau(t))) < 1, \quad t \geq t_0^*, \quad (3.17)$$

where  $\varepsilon_0$  is given by assumption (H). (3.17) and (H) yield that for  $t \geq t_0^*$ ,

$$\begin{aligned} f(t, x(\tau(t))) & \geq p(t)[1 - g(x(\tau(t)))]x(\tau(t)) \\ & \geq p(t)[1 - g(x(\tau(t)))]z(\delta(t)), \end{aligned} \quad (3.18)$$

and it follows from (1.1) that

$$\frac{z'(t)}{z(t)} + p(t) \frac{z(\delta(t))}{z(t)} [1 - g(x(\tau(t)))] \leq 0, \quad t \geq t_0^*. \quad (3.19)$$

By Lemmas 2.1–2.5, there exist  $T > t_2$ ,  $A > 0$ ,  $\varepsilon > 0$  and  $M > 0$  such that for  $t \geq T$ ,

$$x(\tau(t)) \leq A \exp\left(-\frac{1}{2} \int_T^{\tau(t)} p(s) ds\right) + \varepsilon, \quad (3.20)$$

$$\int_{\delta(t)}^t p(s) ds \leq \int_{\tau(t)}^t p(s) ds \leq 2, \quad p_k(t) \leq 2^k, \quad k = 1, 2, \dots, \quad (3.21)$$

$$\frac{z(\delta(t))}{z(t)} \leq \frac{z(\tau(t))}{z(t)} \leq M. \quad (3.22)$$

Let  $t_k = \delta^{-k}(T)$ ,  $k = 1, 2, \dots$ . Clearly  $t_k \rightarrow \infty$  as  $k \rightarrow \infty$ . Set  $\lambda(t) = -z'(t)/z(t)$ , for  $t \geq T$ . Then

$$\frac{z(\delta(t))}{z(t)} = \exp \int_{\delta(t)}^t \lambda(s) ds, \quad t \geq t_1,$$

and from (3.19), for  $t \geq t_1$ , we have

$$\lambda(t) \geq p(t) \exp \int_{\delta(t)}^t \lambda(s) ds - p(t)g(x(\tau(t))) \frac{z(\delta(t))}{z(t)}. \quad (3.23)$$

It follows from (3.20)–(3.23) that for  $t \geq t_1$ ,

$$\begin{aligned} \lambda(t) &\geq p(t) \exp \int_{\delta(t)}^t \lambda(s) ds - Mp(t)g\left(A \exp\left(-\frac{1}{2} \int_T^{\tau(t)} p(s) ds\right) + \varepsilon\right) \\ &\geq p(t) \exp \int_{\delta(t)}^t \lambda(s) ds - Mp(t)g\left(A_1 \exp\left(-\frac{1}{2} \int_T^t p(s) ds\right) + \varepsilon\right), \end{aligned} \quad (3.24)$$

where  $A_1 = eA$ . By the inequality  $e^c \geq ec$  for  $c \geq 0$ , we have for  $t \geq t_1$ ,

$$\lambda(t) \geq ep(t) \int_{\delta(t)}^t \lambda(s) ds - Mp(t)g\left(A_1 \exp\left(-\frac{1}{2} \int_T^t p(s) ds\right) + \varepsilon\right). \quad (3.25)$$

Set

$$\alpha(t) = \frac{1}{2} \int_T^t p(s) ds, \quad t \geq T, \quad (3.26)$$

and

$$\begin{aligned} \lambda_0(t) &= \lambda(t), \quad t \geq T, \\ \lambda_k(t) &= p(t) \int_{\delta(t)}^t \lambda_{k-1}(s) ds, \quad t \geq t_k, \quad k = 1, 2, \dots, n, \end{aligned} \quad (3.27)$$

and

$$\begin{aligned} G_0(t) &= 0, \quad t \geq T, \\ G_k(t) &= ep(t) \int_{\delta(t)}^t G_{k-1}(s) ds + Mp(t)g(A_1 \exp(-\alpha(t)) + \varepsilon), \end{aligned} \quad (3.28)$$

for  $t \geq t_k$ ,  $k = 1, 2, \dots, n$ . Clearly (1.8) implies that  $\alpha(t)$  is nondecreasing on  $[T, \infty)$  and  $\alpha(t) \rightarrow \infty$  as  $t \rightarrow \infty$ . By iteration we deduce from (3.25) that

$$\lambda(t) \geq e^k \lambda_k(t) - G_k(t), \quad t \geq t_k, \quad k = 1, 2, \dots, n-1, \quad (3.29)$$

and so by (3.24),

$$\lambda(t) \geq p(t) \exp\left(e^{n-1} \int_{\delta(t)}^t \lambda_{n-1}(s) ds\right) \exp\left(- \int_{\delta(t)}^t G_{n-1}(s) ds\right) - G_1(t), \quad (3.30)$$

for  $t \geq t_n$ . From (3.28), one can easily obtain

$$G_{k+1}(t) - G_k(t) = ep(t) \int_{\delta(t)}^t [G_k(s) - G_{k-1}(s)] ds, \quad (3.31)$$

for  $t \geq t_{k+1}$ ,  $k = 1, 2, \dots, n-1$ . By (3.21), (3.26) and (3.28), for  $t \geq t_2$ , we have

$$\begin{aligned} \int_{\delta(t)}^t G_1(s) ds &= M \int_{\delta(t)}^t p(s) g(A_1 \exp(-\alpha(s)) + \varepsilon) ds \\ &= 2M \int_{\alpha(\delta(t))}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du \\ &\leq 2M \int_{\alpha(t)-1}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du. \end{aligned} \quad (3.32)$$

Thus, from (3.31), we get

$$[G_2(t) - G_1(t)] = ep(t) \int_{\delta(t)}^t G_1(s) ds \leq 2eMp(t) \int_{\alpha(t)-1}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du, \quad t \geq t_2,$$

$$\begin{aligned} G_3(t) - G_2(t) &= ep(t) \int_{\delta(t)}^t [G_2(s) - G_1(s)] ds \\ &\leq 2e^2Mp(t) \int_{\delta(t)}^t p(s) \int_{\alpha(s)-1}^{\alpha(s)} g(A_1 e^{-u} + \varepsilon) du ds \\ &= 4e^2Mp(t) \int_{\alpha(\delta(t))}^{\alpha(t)} \int_{v-1}^v g(A_1 e^{-u} + \varepsilon) du dv \\ &\leq 4e^2Mp(t) \int_{\alpha(t)-1}^{\alpha(t)} \int_{v-1}^v g(A_1 e^{-u} + \varepsilon) du dv \\ &\leq 4e^2Mp(t) \int_{\alpha(t)-2}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du, \quad t \geq t_3. \end{aligned}$$

By induction, one can prove in general that for  $k = 2, 3, \dots, n-1$ ,

$$G_k(t) - G_{k-1}(t) \leq (2e)^{k-1} (k-2)! Mp(t) \int_{\alpha(t)-(k-1)}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du, \quad t \geq t_k,$$

and so

$$\begin{aligned} G_{n-1}(t) &= \sum_{k=1}^{n-1} [G_k(t) - G_{k-1}(t)] \\ &\leq G_1(t) + Mp(t) \sum_{k=2}^{n-1} (2e)^{k-1} (k-2)! \int_{\alpha(t)-(k-1)}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du, \end{aligned} \quad (3.33)$$

for  $t \geq t_{n-1}$ . By (3.21), (3.22) and (3.27), we obtain

$$\begin{aligned} \lambda_1(t) &= p(t) \int_{\delta(t)}^t \lambda(s) ds = p(t) \ln \left[ \frac{z(\delta(t))}{z(t)} \right] \\ &\leq p(t) \ln M, \quad t \geq t_1, \\ \lambda_2(t) &= p(t) \int_{\delta(t)}^t \lambda_1(s) ds \leq p(t) \ln M \int_{\delta(t)}^t p(s) ds \\ &\leq 2p(t) \ln M, \quad t \geq t_2, \\ &\dots \\ \lambda_{n-1}(t) &\leq 2^{n-2} p(t) \ln M, \quad t \geq t_{n-1}. \end{aligned} \tag{3.34}$$

For  $t \geq t_n$ , set

$$D(t) = p(t) \exp \left( e^{n-1} \int_{\delta(t)}^t \lambda_{n-1}(s) ds \right) \left[ 1 - \exp \left( - \int_{\delta(t)}^t G_{n-1}(s) ds \right) \right] + G_1(t).$$

From (3.11), (3.21), (3.32), (3.33) and (3.34), we have

$$\begin{aligned} D(t) &\leq p(t) \exp \left( e^{n-1} \int_{\delta(t)}^t \lambda_{n-1}(s) ds \right) \int_{\delta(t)}^t G_{n-1}(s) ds + G_1(t) \\ &\leq G_1(t) + p(t) \exp \left( 2^{n-2} e^{n-1} \ln M \int_{\delta(t)}^t p(s) ds \right) \\ &\quad \times \int_{\delta(t)}^t \left[ G_1(s) + Mp(s) \sum_{k=2}^{n-1} (2e)^{k-1} (k-2)! \int_{\alpha(s)-(k-1)}^{\alpha(s)} g(A_1 e^{-u} + \varepsilon) du \right] ds \\ &\leq G_1(t) + 2Mp(t) \exp((2e)^{n-1} \ln M) \int_{\alpha(t)-1}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du \\ &\quad + Mp(t) \exp((2e)^{n-1} \ln M) \\ &\quad \times \sum_{k=2}^{n-1} (2e)^{k-1} (k-2)! \int_{\delta(t)}^t p(s) \int_{\alpha(s)-(k-1)}^{\alpha(s)} g(A_1 e^{-u} + \varepsilon) du ds \\ &\leq G_1(t) + M_1 p(t) \sum_{k=1}^{n-1} (2e)^{k-1} (k-1)! \int_{\alpha(t)-k}^{\alpha(t)} g(A_1 e^{-u} + \varepsilon) du, \quad t \geq t_n, \end{aligned} \tag{3.35}$$

where  $M_1 = 2M \exp((2e)^{n-1} \ln M)$ . Let  $T^* > t_n$  be such that  $\alpha(T^*) > n + \ln A_1$ . It follows from (3.35) and (H) that

$$\begin{aligned} &\int_{T^*}^{\infty} D(t) dt \\ &\leq \int_{T^*}^{\infty} G_1(t) dt + M_1 \sum_{k=1}^{n-1} (2e)^{k-1} (k-1)! \int_{T^*}^{\infty} p(t) \int_{\alpha(t)-k}^{\alpha(t)} g(A_1 e^{-u}) du dt \\ &\leq 2M \int_{\alpha(T^*)}^{\infty} g(A_1 e^{-u}) du + 2M_1 \sum_{k=1}^{n-1} (2e)^{k-1} (k-1)! \int_{\alpha(T^*)}^{\infty} \int_{v-k}^v g(A_1 e^{-u}) du dv \\ &\leq 2M \int_{\alpha(T^*)}^{\infty} g(A_1 e^{-u}) du + 2M_1 \sum_{k=1}^{n-1} (2e)^{k-1} k! \int_{\alpha(T^*)-(k+1)}^{\infty} g(A_1 e^{-u}) du \end{aligned}$$

$$\int_{T^*}^{\infty} D(t) dt \leq 2M \int_0^{\infty} g(e^{-u}) du + 2M_1 \sum_{k=1}^{n-1} (2e)^{k-1} k! \int_0^{\infty} g(e^{-u}) du < \infty.$$

Since

$$\begin{aligned} & p(t) \exp\left(e^{n-1} \int_{\delta(t)}^t \lambda_{n-1}(s) ds\right) \exp\left(-\int_{\delta(t)}^t G_{n-1}(s) ds\right) - G_1(t) \\ &= p(t) \exp\left(e^{n-1} \int_{\delta(t)}^t \lambda_{n-1}(s) ds\right) - D(t), \quad t \geq t_n, \end{aligned}$$

it follows from (3.30) that

$$\lambda(t) \geq p(t) \exp\left(e^{n-1} \int_{\delta(t)}^t \lambda_{n-1}(s) ds\right) - D(t), \quad t \geq t_n. \quad (3.36)$$

One can easily show that  $\gamma e^x \geq x + \ln(\gamma + 1)$  for  $\gamma > 0$ , and so for  $t \geq t_n$ ,

$$\begin{aligned} p_n(t) \lambda(t) &\geq p(t) e^{1-n} (e^{n-1} p_n(t)) \exp\left(e^{n-1} \int_{\delta(t)}^t \lambda_{n-1}(s) ds\right) - p_n(t) D(t) \\ &\geq p(t) \int_{\delta(t)}^t \lambda_{n-1}(s) ds + e^{1-n} p(t) \ln(e^{n-1} p_n(t) + 1) - p_n(t) D(t), \end{aligned}$$

that is, for  $t \geq t_n$ ,

$$p_n(t) \lambda(t) - p(t) \int_{\delta(t)}^t \lambda_{n-1}(s) ds \geq e^{1-n} p(t) \ln(e^{n-1} p_n(t) + 1) - p_n(t) D(t). \quad (3.37)$$

For  $N > \delta^{-n}(T^*)$ , we have

$$\begin{aligned} & \int_{T^*}^N p_n(t) \lambda(t) dt - \int_{T^*}^N p(t) \int_{\delta(t)}^t \lambda_{n-1}(s) ds dt \\ & \geq e^{1-n} \int_{T^*}^N p(t) \ln(e^{n-1} p_n(t) + 1) dt - \int_{T^*}^N p_n(t) D(t) dt. \end{aligned} \quad (3.38)$$

Let  $\delta^1(t) = \delta(t)$ ,  $\delta^{k+1}(t) = \delta(\delta^k(t))$ ,  $k = 1, 2, \dots, n$ . Then by interchanging the order of integration, we have

$$\begin{aligned} \int_{T^*}^N p(t) \int_{\delta(t)}^t \lambda_{n-1}(s) ds dt &\geq \int_{T^*}^{\delta(N)} \lambda_{n-1}(t) \int_t^{\delta^{-1}(t)} p(s) ds dt \\ &= \int_{T^*}^{\delta(N)} p(t) p_1(t) \int_{\delta(t)}^t \lambda_{n-2}(s) ds dt \\ &\geq \int_{T^*}^{\delta^2(N)} \lambda_{n-2}(t) \int_t^{\delta^{-1}(t)} p(s) p_1(s) ds dt \\ &= \int_{T^*}^{\delta^2(N)} p(t) p_2(t) \int_{\delta(t)}^t \lambda_{n-3}(s) ds dt \\ &\dots \\ &\geq \int_{T^*}^{\delta^n(N)} \lambda(t) p_n(t) dt. \end{aligned}$$

From this and (3.38), we have

$$\int_{\delta^n(N)}^N p_n(t)\lambda(t)dt \geq e^{1-n} \int_{T^*}^N p(t) \ln(e^{n-1}p_n(t) + 1)dt - \int_{T^*}^N p_n(t)D(t)dt, \quad (3.39)$$

which together with (3.21) yields

$$2^n \int_{\delta^n(N)}^N \lambda(t)dt \geq e^{1-n} \int_{T^*}^N p(t) \ln(e^{n-1}p_n(t) + 1)dt - 2^n \int_{T^*}^N D(t)dt,$$

or

$$\ln \frac{x(\delta^n(N))}{x(N)} \geq 2^{-n} e^{1-n} \int_{T^*}^N p(t) \ln(e^{n-1}p_n(t) + 1)dt - \int_{T^*}^N D(t)dt. \quad (3.40)$$

In view of (1.9) and (3), we have

$$\lim_{N \rightarrow \infty} \frac{x(\delta^n(N))}{x(N)} = \infty. \quad (3.41)$$

On the other hand, (3.22) implies that

$$\frac{x(\delta^n(N))}{x(N)} = \frac{x(\delta^1(N))}{x(N)} \cdot \frac{x(\delta^2(N))}{x(\delta^1(N))} \cdots \frac{x(\delta^n(N))}{x(\delta^{n-1}(N))} \leq M^n.$$

This contradicts (3.41) and completes the proof.

#### 4. EXAMPLES

In this section we introduce some examples to illustrate our main results.

**Example 4.1.** Consider the neutral delay differential equation

$$(x(t) - (\frac{5}{2} + \sin t)x(t - \pi))' + f(t, x(\tau(t))) = 0, \quad t \geq 3. \quad (4.1)$$

For  $f(t, u) = p(t)f(u)$ , with

$$f(u) = \begin{cases} u[1 + (1 + \ln^2 |u|)^{-1}], & u \neq 0, \\ 0, & u = 0, \end{cases} \quad (4.2)$$

$$g(u) = \begin{cases} 1, & |u| > 1, \\ (1 + \ln^2 |u|)^{-1}, & 0 < |u| \leq 1, \\ 0, & u = 0, \end{cases} \quad (4.3)$$

$$p(t) = \frac{1}{et \ln 2} + \frac{1}{t \ln t}, \quad \tau(t) = \frac{t}{2}, \quad (4.4)$$

with  $\int_3^\infty p(t)dt = \infty$ . It is easily seen that condition (H) holds. We check that the conditions (1.8) and (1.10) in Corollary 1.3 hold. In fact, for  $t \geq 3$ ,

$$\int_{\frac{t}{2}}^t p(s)ds = \int_{\frac{t}{2}}^t [\frac{1}{es \ln 2} + \frac{1}{s \ln s}]ds = \frac{1}{e} - \ln [1 - \frac{\ln 2}{\ln t}] \geq \frac{1}{e},$$

$\liminf_{t \rightarrow \infty} \int_{t/2}^t p(s)ds = 1/e$ , and

$$\begin{aligned} \int_3^\infty p(t) [\exp [\int_{t/2}^t p(s)ds - \frac{1}{e}] - 1]dt &\geq \int_3^\infty p(t) [\int_{t/2}^t p(s)ds - \frac{1}{e}]dt \\ &\geq -\frac{1}{e \ln 2} \int_3^\infty \frac{1}{t} \ln [1 - \frac{\ln 2}{\ln t}]dt = \infty, \end{aligned}$$

because

$$\int_3^\infty \frac{1}{t \ln t} dt = \infty \quad \text{and} \quad \lim_{t \rightarrow \infty} (\ln t) \ln \left[ 1 - \frac{\ln 2}{\ln t} \right] = -\ln 2.$$

By Theorem 1.1 every solution of (4.1) oscillates.

**Example 4.2.** Consider the neutral delay differential equation

$$\left( x(t) - \left( \frac{5}{2} + \sin t \right) x\left(t - \frac{\pi}{2}\right) \right)' + f(t, x(\tau(t))) = 0, \quad t \geq 3, \quad (4.5)$$

For

$$p(t) = \frac{\delta}{t}, \quad \tau(t) = \frac{t}{\lambda}, \quad \delta < \frac{1}{e \ln \lambda}, \quad \lambda > 1, \quad f(t, u) = p(t)f(u),$$

where  $f(u)$  and  $g(u)$  are defined by (4.2) and (4.3) and with  $\int_3^\infty p(t) dt = \infty$ , and

$$\int_{t/\lambda}^t p(s) ds = \int_{t/\lambda}^t \frac{\delta}{s} ds = \delta (\ln t - \ln \frac{t}{\lambda}) = \delta \ln \lambda < \frac{1}{e}$$

It is easily seen that condition (H) holds. We check that the conditions (1.6) and (1.10) in Theorem 1.2 hold. In fact, for  $t \geq 3$ ,

$$\liminf_{t \rightarrow \infty} \int_{t/\lambda}^t p(s) ds = \liminf_{t \rightarrow \infty} \int_{t/\lambda}^t \frac{\delta}{s} ds = \delta (\ln t - \ln \frac{t}{\lambda}) = \delta \ln \lambda > 0$$

and

$$\begin{aligned} \int_3^\infty p(t) \left[ \exp \left( \int_{t/\lambda}^t p(s) ds \right) - 1 \right] dt &\geq \int_3^\infty p(t) \left( \int_{t/\lambda}^t p(s) ds \right) dt \\ &\geq \int_3^\infty \frac{\delta^2 \ln \lambda}{t} dt = \delta^2 \ln \lambda (\infty) = \infty \end{aligned}$$

By Corollary 1.3 every solution of (4.5) oscillates.

**Example 4.3.** Consider the neutral delay differential equation

$$\left( x(t) - \left( \frac{5}{2} + \sin t \right) x(t - \pi) \right)' + f(t, x(\tau(t))) = 0, \quad t \geq 3, \quad (4.6)$$

where

$$\tau(t) = t - 1 \quad \text{and} \quad f(t, u) = [\exp 3(\sin t - 1) + |u|]^{1/3} u.$$

Let  $p(t) = \exp(\sin t) - 0.1$  and  $g(u) = e^2 |u|^{1/3}$ . It is easy to see that assumption (H) holds. Clearly

$$\begin{aligned} \liminf_{t \rightarrow \infty} \int_{t-1}^t p(s) ds &< \frac{1}{e}, \\ \int_0^\infty p(t) \ln \left( \int_t^{t+1} p(s) ds + 1 \right) dt &\geq \int_0^\infty \exp(\sin t - 1) \ln \left( \int_t^{t+1} \exp(\sin s) ds \right) dt \end{aligned}$$

By Jensen's inequality,

$$\begin{aligned} \int_0^\infty p(t) \ln \left( \int_t^{t+1} p(s) ds + 1 \right) dt &\geq \int_0^\infty \exp(\sin t - 1) \int_t^{t+1} \sin s ds dt \\ &= \frac{2 \sin 2^{-1}}{e} \int_0^\infty \exp(\sin t) \sin \left( t + \frac{1}{2} \right) dt. \end{aligned}$$



On the other hand, it is easy to see that  $\int_0^t \exp(\sin s) \cos s \, ds$  is bounded and

$$\int_0^{2\pi} \exp(\sin t) \sin t \, dt > 0.$$

Thus

$$\int_0^\infty p(t) \ln \left( \int_t^{t+1} p(s) \, ds + 1 \right) dt = \infty.$$

By Corollary 1.4, every solution of (4.6) oscillates.

#### REFERENCES

- [1] R. P. Agarwal, S. R. Grace and D. O'Regan; *Oscillation theory for difference and Functional differential equations*, Kluwer, Dordrecht (2000).
- [2] R. P. Agarwal, S. R. Grace and D. O'Regan; *Oscillation theory for second order dynamic equations* To appear.
- [3] R. P. Agarwal, X. H. Tang and Z. C. Wang; *The existence of positive solutions to neutral differential equations*, J. Math. Anal. Appl., 240 (1999), 446-467.
- [4] D. D. Bainov and D. P. Mishev; *Oscillation theory for neutral differential with delay*, Adam Hilger, NewYork (1991) .
- [5] E. Boe and H.C. Chang; *Dynamics of delayed systems under feedback control*, Chem. Engg. Sci., 44 (1989), 1281-1294.
- [6] R. K. Brayton and R. A. Willoughby; *On the numerical integration of a symmetric system of difference-differential equations of neutral type*, J. Math. Anal. Appl., 18 (1976), 182-189.
- [7] K. Dib, R.M. Mathsen; *Oscillation of solutions of neutral delay differential equations*, Math. Comp. Model. 32 (2000), 609-619.
- [8] R. D. Driver; *A mixed neutral system*, *Nonlinear Analysis*, 8 (1976), 182-189.
- [9] El. M. Elabbasy and S. H. Saker; *Oscillation of nonlinear delay differential equations with several positive and negative coefficients*, Kyungpook. Math. J., 39 (1999), 367-377.
- [10] El. M. Elabbasy and S. H. Saker; *Oscillation of first order neutral delay differential equations*, Kyungpook. Math. J., 41 (2001), 311-321.
- [11] A. Elbert and I. P. Stavroulakis; *Oscillation and non-oscillation criteria for delay differential equations*, Proc. Amer. Math. Soc. 124 (1995), 1503-1511.
- [12] M. K. Grammatikopoulos, E. A. Grove and G. Ladas; *Oscillation of first order neutral delay differential equations*, J. Math. Anal. Appl., 120 (1986), 510-520.
- [13] M. K. Grammatikopoulos, Y. G. Sficas and G. Ladas; *Oscillation and asymptotic behavior of neutral equations with variable coefficients*, Radovi Mathematicki, 2 (1986), 279-303.
- [14] G. S. Ladde, V. Lakshmikantham and B. G. Zhang; *Oscillation Theory of Differential Equations with Deviating Arguments*, Marcel Dekker, New York, 1987.
- [15] Z. Luo and J. Shen; *Oscillation and nonoscillation of neutral differential equations with positive and negative coefficients*, Czechoslovak Math. J., 129 (2004), 79-93.
- [16] I. Gyori and G. Ladas; *Oscillation Theory of Delay Differential Equations with Applications*, Oxford Mathematical Monographs (1991).
- [17] J. K. Hale; *Theory of functional differential equations*, Springer-Verlag, New York (1977).
- [18] J. Jaros and I. P. Stavroulakis; *Oscillation tests for delay equations*, Rocky Mountain J. Math. 28 (1999), 197-207.
- [19] M. Kon, Y. G. Sficas and I. P. Stavroulakis; *Oscillation criteria for delay equations*, Proc. Amer. Math. Soc., 128 (2000), 2989-2997.
- [20] M. R. S. Kulenovic, G. Ladas and A. Meimaridou; *Necessary and sufficient condition for oscillations of neutral differential equations*, J. Austral. Math., Soc. Ser. B., 28 (1987), 362-375.
- [21] I. Kubiacyk, S. H. Saker, J. Morchalo; *New oscillation criteria for first order nonlinear neutral delay differential equations*, Applied Mathematics and Computation 142 (2003), 225-242.
- [22] I. Kubiacyk and S. H. Saker; *Oscillation of solutions of neutral delay differential equations*, Math. Slovaca, to appear.
- [23] M. K. Kwong; *Oscillation of first order delay equations*, J. Math. Anal. Appl., 159 (1991), 469-484.

- [24] G. Ladas and Y. G. Sficas; *Oscillation of neutral delay differential equations*, Canad. Math. Bull., 29 (1986), 438-445.
- [25] B. S. Lalli and B. G. Zhang; *Oscillation of first order neutral differential equations*, Applicable Analysis, 39 (1990), 265-274.
- [26] B. Li; *Oscillations of delay differential equations with variable coefficients*, J. Math. Anal. Appl., 192 (1995), 312-321.
- [27] B. Li, *Oscillations of first order delay differential equations*, Proc. Amer. Math. Soc., 124 (1996), 3729-3737.
- [28] B. Li and Y. Kuang; *Sharp conditions for oscillations in some nonlinear nonautonomous delay differential equations*, Nonlinear Anal. Appl., 29 (1997), 1265-1276.
- [29] W. T. Li, H. Quan and J. Wu; *Oscillation of first order neutral differential equations with variable coefficients*, Commun. Appl. Anal., 3 (1999), 1-13.
- [30] W. T. Li and J. Yan; *Oscillation of first order neutral differential equations with positive and negative coefficients*, Collect. Math., 50 (1999), 199-209.
- [31] Z. Luo and J. Shen; *Oscillation and nonoscillation of neutral differential equations with positive and negative coefficients*, Czechoslovak Math. J., 129 (2004), 79-93.
- [32] E. P. Popove; *Automatic Regulation and Control*, Nauka, Moscow (1966), In Russian.
- [33] C. Qian, M. R. S. Kulenovic and G. Ladas; *Oscillation of neutral equations with variable coefficients*, Radovi Matematicki, 5 (1989), 321-331.
- [34] Y. G. Sficas and I. P. Stavroulakis; *Oscillation criteria for first order delay equations*, Bull. London Math. Soc., 35 (2003), 239-246.
- [35] X. Tang and J. Shen; *Oscillations of delay differential equations with variable coefficients*, J. Math. Anal. Appl., 217(1998), 32-42.
- [36] X. Tang and J. Shen, *New oscillation criteria for first order nonlinear delay differential equations*, Colloquium Mathematicum, 83 (2000), 21-41.
- [37] J. S. Yu; *Neutral differential equations with positive and negative coefficients*, Acta Math. Sinica, 34 (1992), 517-523.
- [38] J. S. Yu and Z. C. Wang, *Some further results on oscillation of neutral equations*, Bull. Austral. Math. Soc., 46 (1992), 149-157.
- [39] B. G. Zhang; *Oscillation of first order neutral functional differential equations*, J. Math. Anal. Appl., 139 (1989), 311-318.
- [40] B. G. Zhang, *On the positive solution of kind of neutral equations*, Acta Math. Appl. Sinica, 19 (1996), 222-230.

ELMETWALLY M. ELABBASY

DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE, MANSOURA UNIVERSITY, MANSOURA, 35516, EGYPT

*E-mail address:* emelabbasy@mans.edu.eg

TAHER S. HASSAN

DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE, MANSOURA UNIVERSITY, MANSOURA, 35516, EGYPT

*E-mail address:* tshassan@mans.edu.eg

SAMIR H. SAKER

DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE, MANSOURA UNIVERSITY, MANSOURA, 35516, EGYPT

*E-mail address:* shsaker@mans.edu.eg