

**EXISTENCE AND UNIQUENESS FOR BOUNDARY-VALUE  
PROBLEM WITH ADDITIONAL SINGLE POINT CONDITIONS  
OF THE STOKES-BITSADZE SYSTEM**

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ABSTRACT. This article shows the uniqueness of a solution to a Bitsadze system of equations, with a boundary-value problem that has four additional single point conditions. It also shows how to construct the solution.

1. INTRODUCTION

The planar Stokes flow based on stream function  $\psi(x, y)$  and stress function  $\phi(x, y)$ , is expressed as

$$\begin{aligned}\phi_{xx} - \phi_{yy} &= -4\eta\psi_{xy}, \\ -\phi_{xy} &= \eta(\psi_{yy} - \psi_{xx}),\end{aligned}\tag{1.1}$$

where  $\eta$  is a material constant, see for the details [4, 5, 9]. The re-scaling ( $2\eta\psi \rightarrow \psi$ ) reduces the system (1.1) to

$$\begin{aligned}\phi_{xx} - \phi_{yy} + 2\psi_{xy} &= 0, \\ \psi_{xx} - \psi_{yy} - 2\phi_{xy} &= 0,\end{aligned}\tag{1.2}$$

which is the famous second order elliptic system called the Bitsadze system of equations and is identified as Stokes-Bitsadze system [10]. In the literature Bitsadze appears to have been the first to question the uniqueness and existence or even the well-posedness of (1.2) subject to certain boundary conditions, see for reference [2, 3, 7]. Oshorov [8] finds well-posed problems for the Cauchy-Riemann system and extends those to the Bitsadze system (1.2). Vaitekhovich [12] discusses Dirichlet and Schwarz problems for the inhomogeneous Bitsadze equation for a circular ring domain. In the interior of unit disc a boundary value problem for the Bitsadze equation is considered by Babayan [1] and is proved to be Noetherian. In his paper Babayan also proposes solvability conditions for the inhomogeneous Bitsadze equation. The unique solvability in a unit disc for the inhomogeneous Bitsadze system is discussed in [6].

The Stokes-Bitsadze system (1.2) can be expressed in the matrix form as

$$A\mathbf{U}_{xx} + 2B\mathbf{U}_{xy} + C\mathbf{U}_{yy} = \mathbf{0},\tag{1.3}$$

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2000 *Mathematics Subject Classification.* 35J57.

*Key words and phrases.* Bitsadze system; boundary value problem; single point conditions.

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Submitted July 24, 2012. Published November 15, 2012.

where

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad C = -A, \quad \mathbf{U}(x, y) = \begin{pmatrix} \phi \\ \psi \end{pmatrix}.$$

In a domain  $\Omega \subset \mathbb{R}^2$  with boundary  $\Gamma$  a linear boundary value problem of Poincaré for the system (1.3) can be formulated as

$$p_1 \mathbf{U}_x + p_2 \mathbf{U}_y + q \mathbf{U} = \boldsymbol{\alpha}(x, y), \quad (x, y) \in \Gamma \quad (1.4)$$

where  $p_1, p_2, q$  are real  $2 \times 2$  matrices and  $\boldsymbol{\alpha}(x, y)$  a real vector given on the boundary  $\Gamma$ . The boundary-value problems of Poincaré for the Stokes-Bitsadze system will be discussed elsewhere. In this paper we are interested in a boundary value problem with four additional single point conditions.

## 2. A BOUNDARY VALUE PROBLEM WITH ADDITIONAL SINGLE POINT CONDITIONS

We consider the Stokes-Bitsadze system (1.2) in domain  $\Omega \subset \mathbb{R}^2$  with boundary  $\Gamma$  subject to the following boundary conditions.

$$\psi = f, \quad \psi_n = g \quad \text{on } \Gamma, \quad (2.1)$$

and

$$\phi = \phi^P, \quad \nabla \phi = (\nabla \phi)^P, \quad \Delta \phi = (\Delta \phi)^P, \quad \text{at a single point } P \in \bar{\Omega}. \quad (2.2)$$

**Theorem 2.1.** *For  $f, g \in C(\Gamma)$ , the boundary value problem (2.1)–(2.2) for the Stokes-Bitsadze system (1.2) has a unique solution  $(\phi, \psi) \in C^4(\Omega) \times C^4(\Omega)$ .*

*Proof.* Suppose  $\phi, \psi \in C^4(\Omega)$ . If  $(\phi, \psi)$  satisfies (1.2), then  $\phi$  and  $\psi$  are biharmonic in  $\Omega$ , and for  $f, g \in C(\Gamma)$  the problem

$$\begin{aligned} \Delta^2 \psi &= 0 && \text{in } \Omega \\ \psi &= f && \text{on } \Gamma \\ \psi_n &= g && \text{on } \Gamma \end{aligned} \quad (2.3)$$

has a unique solution  $\psi \in C^4(\Omega)$ , [11], that satisfies (1.2) and (2.1). Let the unique solution be denoted by  $\tilde{\psi}$ . Now we show that for the unique  $\tilde{\psi}$  if there exists  $\phi$  satisfying (1.2) and (2.1)–(2.2) then that  $\phi$  is unique. Assume that the pairs  $(\phi_1, \tilde{\psi})$  and  $(\phi_2, \tilde{\psi})$  with  $\phi_1 \neq \phi_2$  satisfy (1.2) and (2.1)–(2.2) and that  $\delta = \phi_1 - \phi_2$ . Then from (1.2) it immediately follows that

$$\delta_{xx} - \delta_{yy} = 0, \quad \delta_{xy} = 0 \quad \text{on } \Omega. \quad (2.4)$$

But (2.2) then yields

$$\delta = 0, \quad \nabla \delta = 0, \quad \Delta \delta = 0 \quad \text{at } P, \quad (2.5)$$

and the general solution of the system (2.4) becomes,

$$\delta = ax + by + c(x^2 + y^2) + d, \quad (2.6)$$

which on imposing the conditions (2.5) gives  $\delta \equiv 0$  in  $\bar{\Omega}$  and uniqueness of  $\phi$  thus follows. Hence there exists at most one pair  $(\phi, \psi) \in C^4(\Omega) \times C^4(\Omega)$  that can satisfy (1.2) and (2.1)–(2.2). We are now in a position to assume (without proof) that  $(\tilde{\phi}, \tilde{\psi})$  is a solution of (1.2) and (2.1)–(2.2).

Next, we suppose that  $P(x_P, y_P)$  and  $Q(x, y_P)$  are the points in  $\bar{\Omega}$ , refer to the Figure 1.



whence

$$\begin{aligned} \tilde{\phi}(x, y_P) &= \phi^P + (x - x_P)\phi_x^P + \frac{1}{2}(x - x_P)^2\phi_{yy}^P - 2 \int_{x_P}^x \int_{x_P}^{\mu} \tilde{\psi}_{xy}(\lambda, y_P) d\lambda d\mu \\ &+ \frac{1}{2} \int_{x_P}^x \int_{x_P}^{\nu} \int_{x_P}^{\mu} [\tilde{\psi}_{xxy}(\lambda, y_P) - \tilde{\psi}_{yyy}(\lambda, y_P)] d\lambda d\mu d\nu. \end{aligned} \quad (2.14)$$

Since all the terms on right hand sides of (2.11), (2.12), (2.13) are known therefore  $\tilde{\phi}_{xx}$ ,  $\tilde{\phi}_x$  and  $\tilde{\phi}$  are known along  $PQ$  and hence we know  $\tilde{\phi}$ ,  $\nabla\tilde{\phi}$  and  $\Delta\tilde{\phi}$  at  $Q(x, y_P)$ .

Now from the point  $Q$  we draw the line  $QR$  where  $R(x, y) \in \bar{\Omega}$  is an arbitrary point. Again, since  $(\tilde{\phi}, \tilde{\psi})$  satisfies (1.2)(b); therefore

$$\tilde{\phi}_{xxy} = \frac{1}{2}[\tilde{\psi}_{xxx} - \tilde{\psi}_{xyy}], \quad (2.15)$$

which on integration, along  $QR$ , gives

$$\tilde{\phi}_{xx}(x, y) = \tilde{\phi}_{xx}(x, y_P) + \frac{1}{2} \int_{y_P}^y [\tilde{\psi}_{xxx}(x, \lambda) - \tilde{\psi}_{xyy}(x, \lambda)] d\lambda, \quad (2.16)$$

$$\tilde{\phi}_x(x, y) = \tilde{\phi}_x(x, y_P) + \frac{1}{2} \int_{y_P}^y [\tilde{\psi}_{xx}(x, \lambda) - \tilde{\psi}_{yy}(x, \lambda)] d\lambda. \quad (2.17)$$

But the following expression from (1.2)(a)

$$\tilde{\phi}_{yy} = \tilde{\phi}_{xx} + 2\tilde{\psi}_{xy}, \quad (2.18)$$

on integration along  $QR$  gives

$$\tilde{\phi}_y(x, y) = \tilde{\phi}_y(x, y_P) + \int_{y_P}^y [\tilde{\phi}_{xx}(x, \lambda) + 2\tilde{\psi}_{xy}(x, \lambda)] d\lambda. \quad (2.19)$$

Using (2.10) and (2.16) the expression (2.19) takes the form

$$\begin{aligned} \tilde{\phi}_y(x, y) &= \phi_y^P + \frac{1}{2} \int_{x_P}^x [\tilde{\psi}_{xx}(\lambda, y_P) - \tilde{\psi}_{yy}(\lambda, y_P)] d\lambda + (y - y_P)\tilde{\phi}_{xx}(x, y_P) \\ &+ \frac{1}{2} \int_{y_P}^y \int_{y_P}^{\mu} [\tilde{\psi}_{xxx}(x, \lambda) - \tilde{\psi}_{xyy}(x, \lambda)] d\lambda d\mu + 2 \int_{y_P}^y \tilde{\psi}_{xy}(x, \lambda) d\lambda. \end{aligned} \quad (2.20)$$

Integrating along  $QR$  we obtain from (2.20) as follows.

$$\begin{aligned} \tilde{\phi}(x, y) &= \tilde{\phi}(x, y_P) + (y - y_P)\phi_y^P + \frac{1}{2}(y - y_P)^2\tilde{\phi}_{xx}(x, y_P) \\ &+ \frac{1}{2}(y - y_P) \int_{x_P}^x [\tilde{\psi}_{xx}(\lambda, y_P) - \tilde{\psi}_{yy}(\lambda, y_P)] d\lambda \\ &+ \frac{1}{2} \int_{y_P}^y \int_{y_P}^{\nu} \int_{y_P}^{\mu} [\tilde{\psi}_{xxx}(x, \lambda) - \tilde{\psi}_{xyy}(x, \lambda)] d\lambda d\mu d\nu \\ &+ 2 \int_{y_P}^y \int_{y_P}^{\mu} \tilde{\psi}_{xy}(x, \lambda) d\lambda d\mu. \end{aligned} \quad (2.21)$$

Using (2.12) and (2.14) we finally obtain the following expression for  $\tilde{\phi}(x, y)$  at an arbitrary point  $(x, y) \in \bar{\Omega}$ .

$$\begin{aligned}
& \tilde{\phi}(x, y) \\
&= \phi^P + (x - x_P)\phi_x^P + (y - y_P)\phi_y^P + \frac{1}{2}[(x - x_P)^2 + (y - y_P)^2]\phi_{yy}^P \\
&\quad - (y - y_P)^2\tilde{\psi}_{xy}(x, y_P) + \frac{1}{2}(y - y_P) \int_{x_P}^x [\tilde{\psi}_{xx}(\lambda, y_P) - \tilde{\psi}_{yy}(\lambda, y_P)] d\lambda \\
&\quad + \frac{1}{4}(y - y_P)^2 \int_{x_P}^x [\tilde{\psi}_{xxy}(\lambda, y_P) - \tilde{\psi}_{yyy}(\lambda, y_P)] d\lambda \\
&\quad - 2 \int_{x_P}^x \int_{x_P}^\mu \tilde{\psi}_{xy}(\lambda, y_P) d\lambda d\mu + 2 \int_{y_P}^y \int_{y_P}^\mu \tilde{\psi}_{xy}(x, \lambda) d\lambda d\mu \\
&\quad + \frac{1}{2} \int_{x_P}^x \int_{x_P}^\nu \int_{x_P}^\mu [\tilde{\psi}_{xxy}(\lambda, y_P) - \tilde{\psi}_{yyy}(\lambda, y_P)] d\lambda d\mu d\nu \\
&\quad + \frac{1}{2} \int_{y_P}^y \int_{y_P}^\nu \int_{y_P}^\mu [\tilde{\psi}_{xxx}(x, \lambda) - \tilde{\psi}_{xyy}(x, \lambda)] d\lambda d\mu d\nu.
\end{aligned} \tag{2.22}$$

Obviously we have obtained an explicit representation for  $\tilde{\phi}$  in terms of the point conditions and  $\tilde{\psi}$ , on the assumption that  $(\tilde{\phi}, \tilde{\psi})$  satisfies (1.2) and (2.1)–(2.2). Next we show that  $(\tilde{\phi}, \tilde{\psi})$  actually satisfies the Bitsadze system (1.2) and the conditions (2.2).

From expression (2.22) it is easy to verify that  $\tilde{\phi}(x_P, y_P) = \phi^P$ . We use (2.13) in (2.17) to obtain

$$\begin{aligned}
\tilde{\phi}_x(x, y) &= \phi_x^P + \int_{x_P}^x [\phi_{yy}^P + \frac{1}{2} \int_{x_P}^\mu [\tilde{\psi}_{xxy}(\lambda, y_P) - \tilde{\psi}_{yyy}(\lambda, y_P)] d\lambda] d\mu \\
&\quad - 2 \int_{x_P}^x \tilde{\psi}_{xy}(\lambda, y_P) d\lambda + \frac{1}{2} \int_{y_P}^y [\tilde{\psi}_{xx}(x, \lambda) - \tilde{\psi}_{yy}(x, \lambda)] d\lambda,
\end{aligned}$$

and it can be easily verified that  $\tilde{\phi}_x(x_P, y_P) = \phi_x^P$ . Similarly from (2.10) and (2.20) we have

$$\tilde{\phi}_y(x, y) = \phi_y^P + \frac{1}{2} \int_{x_P}^x [\tilde{\psi}_{xx}(\lambda, y_P) - \tilde{\psi}_{yy}(\lambda, y_P)] d\lambda + \int_{y_P}^y [\tilde{\phi}_{xx}(x, \lambda) + 2\tilde{\psi}_{xy}(x, \lambda)] d\lambda,$$

and it follows that  $\tilde{\phi}_y(x_P, y_P) = \phi_y^P$ . Again, from (2.12) and (2.16) we obtain

$$\begin{aligned}
\tilde{\phi}_{xx}(x, y) &= \phi_{yy}^P + \frac{1}{2} \int_{x_P}^x [\tilde{\psi}_{xxy}(\lambda, y_P) - \tilde{\psi}_{yyy}(\lambda, y_P)] d\lambda - 2\tilde{\psi}_{xy}(x, y_P) \\
&\quad + \frac{1}{2} \int_{y_P}^y [\tilde{\psi}_{xxx}(x, \lambda) - \tilde{\psi}_{xyy}(x, \lambda)] d\lambda,
\end{aligned}$$

which at  $P$  yields

$$\tilde{\phi}_{xx}(x_P, y_P) = \phi_{yy}^P - 2\tilde{\psi}_{xy}(x_P, y_P), \tag{2.23}$$

and from (2.7)(a) we obtain  $\tilde{\phi}_{xx}(x_P, y_P) = \phi_{xx}^P$ . Also from (2.18) it is obvious that

$$\tilde{\phi}_{yy}(x_P, y_P) = \tilde{\phi}_{xx}(x_P, y_P) + 2\tilde{\psi}_{xy}(x_P, y_P), \tag{2.24}$$

and (2.23)–(2.24) yield  $\tilde{\phi}_{yy}(x_P, y_P) = \phi_{yy}^P$ .

Now we verify that  $\tilde{\phi}(x, y)$  satisfies (1.2)(a). Using (2.10) in (2.20) and then differentiating with respect to  $x$  we obtain

$$\begin{aligned} \tilde{\phi}_{xy}(x, y) &= \frac{1}{2}[\tilde{\psi}_{xx}(x, y_P) - \tilde{\psi}_{yy}(x, y_P)] + \frac{1}{2}(y - y_P)[\tilde{\psi}_{xxy}(x, y_P) - \tilde{\psi}_{yyy}(x, y_P)] \\ &\quad - 2(y - y_P)\tilde{\psi}_{xxy}(x, y_P) + \frac{1}{2}\int_{y_P}^y \int_{y_P}^{\mu} [\tilde{\psi}_{xxxx}(x, \lambda) - \tilde{\psi}_{xxyy}(x, \lambda)] d\lambda d\mu \\ &\quad + 2\tilde{\psi}_{xx}(x, y) - 2\tilde{\psi}_{xx}(x, y_P), \end{aligned}$$

which, since  $\Delta^2\tilde{\psi} = 0$ , can be simplified as

$$\begin{aligned} &\tilde{\phi}_{xy}(x, y) \\ &= -\frac{1}{2}[3\tilde{\psi}_{xx}(x, y_P) + \tilde{\psi}_{yy}(x, y_P)] - \frac{1}{2}(y - y_P)[3\tilde{\psi}_{xxy}(x, y_P) + \tilde{\psi}_{yyy}(x, y_P)] \\ &\quad - \frac{1}{2}[3\tilde{\psi}_{xx}(x, y_P) + \tilde{\psi}_{yy}(x, y)] + \frac{1}{2}[3\tilde{\psi}_{xx}(x, y_P) + \tilde{\psi}_{yy}(x, y_P)] \\ &\quad + \frac{1}{2}(y - y_P)[3\tilde{\psi}_{xxy}(x, y_P) + \tilde{\psi}_{yyy}(x, y_P)] + 2\tilde{\psi}_{xx}(x, y), \end{aligned} \tag{2.25}$$

and we obtain

$$\tilde{\phi}_{xy}(x, y) = \frac{1}{2}[\tilde{\psi}_{xx}(x, y) - \tilde{\psi}_{yy}(x, y)]. \tag{2.26}$$

Then, to verify that  $\tilde{\phi}(x, y)$  satisfies (1.2)(b), we use (2.22) to obtain

$$\begin{aligned} &\tilde{\phi}_{xx}(x, y) - \tilde{\phi}_{yy}(x, y) \\ &= -(y - y_P)^2\tilde{\psi}_{xxyy}(x, y_P) + \frac{1}{2}(y - y_P)[\tilde{\psi}_{xxx}(x, y_P) - \tilde{\psi}_{xyy}(x, y_P)] \\ &\quad + \frac{1}{4}(y - y_P)^2[\tilde{\psi}_{xxyy}(x, y_P) - \tilde{\psi}_{xyyy}(x, y_P)] \\ &\quad + 2\int_{y_P}^y \int_{y_P}^{\mu} \tilde{\psi}_{xxyy}(x, \lambda) d\lambda d\mu + \frac{1}{2}\int_{x_P}^x [\tilde{\psi}_{xxy}(\lambda, y_P) - \tilde{\psi}_{yyy}(\lambda, y_P)] d\lambda \\ &\quad + \frac{1}{2}\int_{y_P}^y \int_{y_P}^{\nu} \int_{y_P}^{\mu} [\tilde{\psi}_{xxxx}(x, \lambda) - \tilde{\psi}_{xxyy}(x, \lambda)] d\lambda d\mu d\nu \\ &\quad - \frac{1}{2}\int_{x_P}^x [\tilde{\psi}_{xxy}(\lambda, y_P) - \tilde{\psi}_{yyy}(\lambda, y_P)] d\lambda - 2\tilde{\psi}_{xy}(x, y) \\ &\quad - \frac{1}{2}\int_{y_P}^y [\tilde{\psi}_{xxx}(x, \lambda) - \tilde{\psi}_{xyy}(x, \lambda)] d\lambda, \end{aligned}$$

which can further be simplified to obtain

$$\begin{aligned} &\tilde{\phi}_{xx}(x, y) - \tilde{\phi}_{yy}(x, y) \\ &= -\frac{1}{4}(y - y_P)^2[3\tilde{\psi}_{xxyy}(x, y_P) + \tilde{\psi}_{xyyy}(x, y_P)] \\ &\quad - \frac{1}{2}(y - y_P)[3\tilde{\psi}_{xxx}(x, y_P) + \tilde{\psi}_{xyy}(x, y_P)] \\ &\quad - \frac{1}{2}\int_{y_P}^y [3\tilde{\psi}_{xxx}(x, \lambda) + \tilde{\psi}_{xyy}(x, \lambda)] d\lambda + \frac{1}{2}(y - y_P)[3\tilde{\psi}_{xxx}(x, y_P) + \tilde{\psi}_{xyy}(x, y_P)] \\ &\quad + \frac{1}{4}(y - y_P)^2[3\tilde{\psi}_{xxyy}(x, y_P) + \tilde{\psi}_{xyyy}(x, y_P)] \end{aligned}$$

$$-2\tilde{\psi}_{xy}(x, y) + \frac{1}{2} \int_{y_P}^y [3\tilde{\psi}_{xxx}(x, \lambda) + \tilde{\psi}_{xyy}(x, \lambda)] d\lambda,$$

and finally we have

$$\tilde{\phi}_{xx}(x, y) - \tilde{\phi}_{yy}(x, y) = -2\tilde{\psi}_{xy}(x, y),$$

which completes the proof.  $\square$

**Conclusion.** It has been proved by construction that there exists a unique solution  $(\tilde{\phi}, \tilde{\psi})$  in  $C^4(\Omega) \times C^4(\Omega)$  to the Stokes-Bitsadze system (1.2) subject to the boundary conditions (2.1) along with additional single point conditions (2.2).

**Acknowledgements.** The author is grateful to Professor A. Russell Davies, Head School of Mathematics, Cardiff University, United Kingdom for his useful suggestions.

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