

**WEAK SOLUTION BY THE SUB-SUPERSOLUTION METHOD
FOR A NONLOCAL SYSTEM INVOLVING LEBESGUE
GENERALIZED SPACES**

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ABSTRACT. We consider a system of nonlocal elliptic equations

$$\begin{aligned} & -\mathcal{A}(x, |v|_{L^{r_1(x)}}) \operatorname{div}(a_1(|\nabla u|^{p_1(x)})|\nabla u|^{p_1(x)-2}\nabla u) \\ & = f_1(x, u, v)|\nabla v|_{L^{q_1(x)}}^{\alpha_1(x)} + g_1(x, u, v)|\nabla v|_{L^{s_1(x)}}^{\gamma_1(x)}, \\ & -\mathcal{A}(x, |u|_{L^{r_2(x)}}) \operatorname{div}(a_2(|\nabla v|^{p_2(x)})|\nabla v|^{p_2(x)-2}\nabla v) \\ & = f_2(x, u, v)|\nabla u|_{L^{q_2(x)}}^{\alpha_2(x)} + g_2(x, u, v)|\nabla u|_{L^{s_2(x)}}^{\gamma_2(x)}, \end{aligned}$$

with Dirichlet boundary condition, where Ω is a bounded domain in \mathbb{R}^N ($N > 1$) with C^2 boundary. Using sub-supersolution method, we prove the existence of at least one positive weak solution. Also, we study a generalized logistic equation and a sublinear system.

1. INTRODUCTION

Partial differential equations involving the $p(x)$ -Laplacian arise in several areas of science and technology such as nonlinear elasticity, fluid mechanics, non-Newtonian fluids and image processing (see [8, 31, 37, 38]). In the previous decades there have been several works related to the p and $p(x)$ -Laplacian operators; see [1, 2, 6, 16, 17, 19, 20, 21, 22, 23, 29, 30, 34, 35, 40] and the references therein.

Nonlocal problems including Laplace operator have been intensively studied since their first appearance in the work of Kirchhoff [27] who studied a wave equation which is a generalization of the D'Alembert equation. On this subject the reader may also consult Carrier [5] and Lions [28].

However, non-local problems are not restricted to mechanical motivations as in the aforementioned works. They also appear in a wide variety of applications as population dynamics [9, 10, 12], Ohmic heating [26], the formation of shear bands in materials [32], heat transfer in thermistors [25], combustion theory [33], microwave heating of ceramic materials [3].

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Here, we consider the nonlocal system

$$\begin{aligned}
& -\mathcal{A}(x, |v|_{L^{r_1(x)}}) \operatorname{div} \left(a(|\nabla u|^{p_1(x)}) |\nabla u|^{p_1(x)-2} \nabla u \right) \\
& = f_1(x, u, v) |v|_{L^{q_1(x)}}^{\alpha_1(x)} + g_1(x, u, v) |v|_{L^{s_1(x)}}^{\gamma_1(x)} \quad \text{in } \Omega, \\
& -\mathcal{A}(x, |u|_{L^{r_2(x)}}) \operatorname{div} \left(a(|\nabla v|^{p_2(x)}) |\nabla v|^{p_2(x)-2} \nabla v \right) \\
& = f_2(x, u, v) |u|_{L^{q_2(x)}}^{\alpha_2(x)} + g_2(x, u, v) |u|_{L^{s_2(x)}}^{\gamma_2(x)} \quad \text{in } \Omega, \\
& u = v = 0 \quad \text{on } \partial\Omega,
\end{aligned} \tag{1.1}$$

where Ω is a bounded domain in \mathbb{R}^N ($N > 1$) with C^2 boundary, $|\cdot|_{L^m(x)}$ is the norm of the space $L^m(x)(\Omega)$, $-\Delta_{p(x)}u := -\operatorname{div}(|\nabla u|^{p(x)-2}\nabla u)$ is the $p(x)$ -Laplacian operator, $r_i, p_i, q_i, s_i, \alpha_i, \gamma_i : \Omega \rightarrow [0, \infty), i = 1, 2$ are measurable functions and $\mathcal{A}, f_1, f_2, g_1, g_2 : \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$ are continuous functions satisfying certain conditions. To be more specific about the structure of the operator in (1.1), we consider functions $a : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ of class C^1 satisfying the following conditions:

(A1) There exist constants $k_1, k_2, k_3, k_4 \geq 0, 2 < p_i \leq o_i < N$ such that

$$k_1 t^{p_i} + k_2 t^{o_i} \leq a(t^{p_i}) t^{p_i} \leq k_3 t^{p_i} + k_4 t^{o_i}, \quad \text{for all } t \geq 0.$$

(A2) The function $t \mapsto A_i(t^{p_i})$ is strictly convex, where $A_i(t) = \int_0^t a_i(s) ds$.

(A3) The function $t \mapsto a_i(t^{p_i}) t^{p_i-2}$ is increasing.

Various operators occurring in applications are included in models for the boundary value problem (1.1) as one can see from next examples. The following operators satisfy (A1)–(A3):

(i) If $a_i(t) = 1$ for $i = 1, 2$, we obtain the p -Laplacian and problem (1.1) becomes

$$\begin{aligned}
& -\mathcal{A}(x, |v|_{L^{r_1(x)}}) \Delta_{p_1} u = f_1(x, u, v) |\nabla v|_{L^{q_1(x)}}^{\alpha_1(x)} + g_1(x, u, v) |\nabla v_1|_{L^{s_1(x)}}^{\gamma_1(x)} \quad \text{in } \Omega, \\
& -\mathcal{A}(x, |u|_{L^{r_2(x)}}) \Delta_{p_2} v = f_2(x, u, v) |\nabla u|_{L^{q_2(x)}}^{\alpha_2(x)} + g_2(x, u, v) |\nabla u|_{L^{s_2(x)}}^{\gamma_2(x)} \quad \text{in } \Omega, \\
& u = v = 0 \quad \text{on } \partial\Omega,
\end{aligned}$$

with $q_i = p_i, k_1 + k_2 = 1$ and $k_3 + k_4 = 1$.

(ii) If $a_i(t) = 1 + t^{\frac{\alpha_i - p_i}{p_i}}$ for $i = 1, 2$, we obtain the (p, o) -Laplacian or $p \& o$ -Laplacian and problem (1.1) becomes

$$\begin{aligned}
& -\mathcal{A}(x, |v|_{L^{r_1(x)}}) (\Delta_{p_1} u + \Delta_{o_1} u) = f_1(x, u, v) |\nabla v|_{L^{q_1(x)}}^{\alpha_1(x)} + g_1(x, u, v) |\nabla v_1|_{L^{s_1(x)}}^{\gamma_1(x)} \quad \text{in } \Omega, \\
& -\mathcal{A}(x, |u|_{L^{r_2(x)}}) (\Delta_{p_2} v + \Delta_{o_2} v) = f_2(x, u, v) |\nabla u|_{L^{q_2(x)}}^{\alpha_2(x)} + g_2(x, u, v) |\nabla u|_{L^{s_2(x)}}^{\gamma_2(x)} \quad \text{in } \Omega, \\
& u = v = 0 \quad \text{on } \partial\Omega,
\end{aligned}$$

with $k_1 = k_2 = k_3 = k_4 = 1$.

(iii) If $a_i(t) = 1 + \frac{1}{(1+t)^{\frac{p_i-2}{p_i}}}$ for $i = 1, 2$, we obtain

$$\begin{aligned}
& -\mathcal{A}(x, |v|_{L^{r_1(x)}}) \operatorname{div} \left(|\nabla u|^{p_1-2} \nabla u + \frac{|\nabla u|^{p_1-2} \nabla u}{(1 + |\nabla u|^{p_1})^{\frac{p_1-2}{p_1}}} \right) \\
& = f_1(x, u, v) |\nabla v|_{L^{q_1(x)}}^{\alpha_1(x)} + g_1(x, u, v) |\nabla v|_{L^{s_1(x)}}^{\gamma_1(x)} \quad \text{in } \Omega, \\
& -\mathcal{A}(x, |u|_{L^{r_2(x)}}) \operatorname{div} \left(|\nabla v|^{p_2-2} \nabla v + \frac{|\nabla v|^{p_2-2} \nabla v}{(1 + |\nabla v|^{p_2})^{\frac{p_2-2}{p_2}}} \right) \\
& = f_2(x, u, v) |\nabla u|_{L^{q_2(x)}}^{\alpha_2(x)} + g_2(x, u, v) |\nabla u|_{L^{s_2(x)}}^{\gamma_2(x)} \quad \text{in } \Omega,
\end{aligned}$$

$$u = v = 0 \quad \text{on } \partial\Omega,$$

with $q_i = p_i$, $k_1 + k_2 = 1$, and $k_3 + k_4 = 2$.

(iv) If $a_i(t) = 1 + t^{\frac{\alpha_i - p_i}{p_i}} + \frac{1}{(1+t)^{\frac{p_i - 2}{p_i}}}$ for $i = 1, 2$, we obtain

$$\begin{aligned} & -\mathcal{A}(x, |v|_{L^{r_1}(x)}) \left(\Delta_{p_1} u + \Delta_{o_1} u + \operatorname{div} \left(\frac{|\nabla u|^{p_1 - 2} \nabla u}{(1 + |\nabla u|^{p_1})^{\frac{p_1 - 2}{p_1}}} \right) \right) \\ & = f_1(x, u, v) |\nabla v|_{L^{q_1}(x)}^{\alpha_1(x)} + g_1(x, u, v) |\nabla v|_{L^{s_1}(x)}^{\gamma_1(x)} \quad \text{in } \Omega, \\ & -\mathcal{A}(x, |u|_{L^{r_2}(x)}) \left(\Delta_{p_2} v + \Delta_{o_2} v + \operatorname{div} \left(\frac{|\nabla v|^{p_2 - 2} \nabla v}{(1 + |\nabla v|^{p_2})^{\frac{p_2 - 2}{p_2}}} \right) \right) \\ & = f_2(x, u, v) |\nabla u|_{L^{q_2}(x)}^{\alpha_2(x)} + g_2(x, u, v) |\nabla u|_{L^{s_2}(x)}^{\gamma_2(x)} \quad \text{in } \Omega, \\ & u = v = 0 \quad \text{on } \partial\Omega, \end{aligned}$$

with $k_1 = k_2 = k_4 = 1$ and $k_3 = 2$.

Several works related to (1.1) in the p -Laplacian case, that is, with $p(x) = p$ (a constant) can be found in [4, 7, 14, 15, 18, 24, 39] and their references. Chen et al. [7] proved the existence of positive solutions for a class of nonvariational elliptic system with nonlocal source

$$\begin{aligned} -\Delta u^m &= f_1(x, u) |v|_{L^p}^\alpha \quad \text{in } \Omega, \\ -\Delta v^n &= f_2(x, v) |u|_{L^q}^\beta \quad \text{in } \Omega, \\ u > 0, v > 0 &\quad \text{in } \Omega, \\ u = v = 0 &\quad \text{on } \partial\Omega. \end{aligned}$$

using the Galerkin method, a fixed point theorem in finite dimensions, and sub-supersolution technique. Corrêa et al [14] studied the existence of positive solutions for the nonlocal problem

$$\begin{aligned} -\Delta_{p_1} u &= |v|_{L^{q_1}}^{\alpha_1} \quad \text{in } \Omega, \\ -\Delta_{p_2} v &= |u|_{L^{q_2}}^{\alpha_2} \quad \text{in } \Omega, u = v = 0 \quad \text{on } \partial\Omega, \end{aligned}$$

by using Rabinowitz's theorem [36]. Santos et al [39] studied the system

$$\begin{aligned} -\mathcal{A}(x, |v|_{L^{r_1}(x)}) \Delta u &= f_1(x, u, v) |v|_{L^{q_1}(x)}^{\alpha_1(x)} + g_1(x, u, v) |v|_{L^{s_1}(x)}^{\gamma_1(x)} \quad \text{in } \Omega, \\ -\mathcal{A}(x, |u|_{L^{r_2}(x)}) \Delta v &= f_2(x, u, v) |u|_{L^{q_2}(x)}^{\alpha_2(x)} + g_2(x, u, v) |u|_{L^{s_2}(x)}^{\gamma_2(x)} \quad \text{in } \Omega, \\ u = v = 0 &\quad \text{on } \partial\Omega, \end{aligned}$$

where $\mathcal{A} : \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$ is a function satisfying certain conditions. They use an abstract result involving sub-supersolution, whose proof is based on the Schaefer's fixed point theorem. Specifically, it was considered a sublinear system, a concave-convex problem and a system of logistic equations.

The scalar version of (1.1),

$$\begin{aligned} -\mathcal{A}(x, |u|_{L^{r(x)}}) \Delta_{p(x)} u &= f(x, u) |u|_{L^{q(x)}}^{\alpha(x)} + g(x, u) |u|_{L^{s(x)}}^{\gamma(x)} \quad \text{in } \Omega, \\ u = 0 &\quad \text{on } \partial\Omega, \end{aligned} \tag{1.2}$$

was considered in [40]. The authors obtained an abstract result involving sub and super solutions for (1.1) that generalizes [39, Theorem 1]. As an application of

such result the authors presented three applications of [39, Theorem 1] for the $p(x)$ -Laplacian operator.

The main result of this paper proves the existence of at least one weak positive solution for (1.1) via sub-supersolution method. This is an extension of [39, Theorem 2] and [41, Theorem 1.1] for the $p(x)$ -Laplacian operator.

2. FUNCTION SPACES

Here, we introduce a suitable function space, where the solution of problem (1.1) make sense. Next we recall some facts about the known spaces $L^{p(x)}(\Omega)$, $W^{1,p(x)}(\Omega)$ and $W_0^{1,p(x)}(\Omega)$ (see [21] and the references therein for more details).

Let $\Omega \subset \mathbb{R}^N$, ($N \geq 1$) be a bounded domain. Given $p \in L_+^\infty(\Omega)$, the generalized Lebesgue space is

$$L^{p(x)}(\Omega) := \left\{ u \in \mathcal{S}(\Omega) : \int_{\Omega} |u(x)|^{p(x)} dx < \infty \right\},$$

where $\mathcal{S}(\Omega) := \{u : \Omega \rightarrow \mathbb{R} : u \text{ is measurable}\}$. The $L^{p(x)}(\Omega)$ is a Banach space with the norm

$$|u|_{p(x)} := \inf \left\{ \lambda > 0 : \int_{\Omega} \left| \frac{u(x)}{\lambda} \right|^{p(x)} dx \leq 1 \right\}.$$

Given $m \in L^\infty(\Omega)$, we define

$$m^+ := \operatorname{ess\,sup}_{\Omega} m(x), \quad m^- := \operatorname{ess\,inf}_{\Omega} m(x).$$

Proposition 2.1. *Let $\rho(u) := \int_{\Omega} |u|^{p(x)} dx$. Then for $u, u_n \in L^{p(x)}(\Omega)$, and $n \in \mathbb{N}$, the following assertions hold*

- (i) *Let $u \neq 0$ in $L^{p(x)}(\Omega)$, then $|u|_{L^{p(x)}} = \lambda \Leftrightarrow \rho\left(\frac{u}{\lambda}\right) = 1$.*
- (ii) *If $|u|_{L^{p(x)}} < 1$ ($= 1, > 1$), then $\rho(u) < 1$ ($= 1, > 1$).*
- (iii) *If $|u|_{L^{p(x)}} > 1$, then $|u|_{L^{p(x)}}^{p^-} \leq \rho(u) \leq |u|_{L^{p(x)}}^{p^+}$.*
- (iv) *If $|u|_{L^{p(x)}} < 1$, then $|u|_{L^{p(x)}}^{p^+} \leq \rho(u) \leq |u|_{L^{p(x)}}^{p^-}$.*
- (v) *$|u_n|_{L^{p(x)}} \rightarrow 0 \Leftrightarrow \rho(u_n) \rightarrow 0$, and $|u_n|_{L^{p(x)}} \rightarrow \infty \Leftrightarrow \rho(u_n) \rightarrow \infty$.*

Theorem 2.2. *Assume $p, q \in L_+^\infty(\Omega)$. The following statements hold*

- (i) *If $p^- > 1$ and $\frac{1}{q(x)} + \frac{1}{p(x)} = 1$ a.e. in Ω , then*

$$\left| \int_{\Omega} uvdx \right| \leq \left(\frac{1}{p} + \frac{1}{q} \right) |u|_{L^{p(x)}} |v|_{L^{q(x)}}.$$

- (ii) *If $q(x) \leq p(x)$ a.e. in Ω and $|\Omega| < \infty$, then $L^{p(x)}(\Omega) \hookrightarrow L^{q(x)}(\Omega)$.*

One can define the generalized Sobolev space

$$W^{1,p(x)}(\Omega) := \left\{ u \in L^{p(x)}(\Omega) : \frac{\partial u}{\partial x_j} \in L^{p(x)}(\Omega), j = 1, \dots, N \right\}$$

with the norm

$$\|u\|_* = |u|_{L^{p(x)}} + \sum_{j=1}^N \left| \frac{\partial u}{\partial x_j} \right|_{L^{p(x)}}.$$

The space $W_0^{1,p(x)}(\Omega)$ is defined as the closure of $C_0^\infty(\Omega)$ with respect to the norm $\|\cdot\|_*$.

Theorem 2.3. *If $p^- > 1$, then $W^{1,p(x)}(\Omega)$ is a separable and reflexive Banach space.*

Proposition 2.4. *Let $\Omega \subset \mathbb{R}^N$ be a bounded domain and $p, q \in C(\overline{\Omega})$. Define the function $p^*(x) = \frac{Np(x)}{N-p(x)}$ if $p(x) < N$ and $p^*(x) = \infty$ if $N \geq p(x)$. The following statements are hold.*

- (i) *(Poincaré inequality) If $p^- > 1$, then there is a constant $C > 0$ such that $|u|_{L^{p(x)}} \leq C|\nabla u|_{L^{p(x)}}$ for all $u \in W_0^{1,p(x)}(\Omega)$.*
- (ii) *If $p^-, q^- > 1$ and $q(x) < p^*(x)$ for all $x \in \overline{\Omega}$, then the embedding $W^{1,p(x)}(\Omega) \hookrightarrow L^{q(x)}(\Omega)$ is continuous and compact.*

By part (i) of Proposition 2.4, $\|u\| := |\nabla u|_{L^{p(x)}}$ defines a norm in $W_0^{1,p(x)}(\Omega)$ which is equivalent to the norm $\|\cdot\|_*$.

Definition 2.5. For $u, v \in W^{1,p(x)}(\Omega)$, we say that $-\Delta_{p(x)}u \leq -\Delta_{p(x)}v$, if

$$\int_{\Omega} |\nabla u|^{p(x)-2} \nabla u \nabla \varphi \leq \int_{\Omega} |\nabla v|^{p(x)-2} \nabla v \nabla \varphi,$$

for all $\varphi \in W_0^{1,p(x)}(\Omega)$ with $\varphi \geq 0$.

The following result appears in [23, Lemma 2.2] and [20, Proposition 2.3].

Proposition 2.6. *Let $u, v \in W^{1,p(x)}(\Omega)$. If $-\Delta_{p(x)}u \leq -\Delta_{p(x)}v$ and $u \leq v$ on $\partial\Omega$, (i.e., $(u - v)^+ \in W_0^{1,p(x)}(\Omega)$) then $u \leq v$ in Ω . If $u, v \in C(\overline{\Omega})$ and $S = \{x \in \Omega : u(x) = v(x)\}$ is a compact set of Ω , then $S = \emptyset$.*

Next we recall [20, Lemma 2.1].

Lemma 2.7. *Let $\lambda > 0$ be the unique solution of the problem*

$$\begin{aligned} -\Delta_{p(x)}z_\lambda &= \lambda \quad \text{in } \Omega, \\ u &= 0 \quad \text{on } \partial\Omega. \end{aligned} \tag{2.1}$$

Define $\rho_0 = \frac{p^-}{2|\Omega|^{\frac{1}{N}}C_0}$. If $\lambda \geq \rho_0$ then $|z_\lambda|_{L^\infty} \leq C^*\lambda^{\frac{1}{p^- - 1}}$, and $|z_\lambda|_{L^\infty} \leq C_*\lambda^{\frac{1}{p^+ - 1}}$ if $\lambda < \rho_0$. Here C^* and C_* are positive constants depending only on $p^+, p^-, N, |\Omega|$ and C_0 , where C_0 is the best constant of the embedding $W_0^{1,1}(\Omega) \hookrightarrow L^{\frac{N}{N-1}}(\Omega)$.

Regarding the function z_λ of the previous result, it follows from [19, Theorem 1.2] and [23, Theorem 1] that $z_\lambda \in C^1(\overline{\Omega})$ with $z_\lambda > 0$ in Ω . The proof of Theorem 3.5 is mainly based on the following result by Rabinowitz [36].

Theorem 2.8. *Let E be a Banach space and $\Phi : \mathbb{R}^+ \times E \rightarrow E$ a compact map such that $\Phi(0, u) = 0$ for all $u \in E$. Then the equation*

$$u = \Phi(\lambda, u)$$

possesses an unbounded continuum $\mathcal{C} \subset \mathbb{R}^+ \times E$ of solutions with $(0, 0) \in \mathcal{C}$.

We point out that a mapping $\Phi : E \rightarrow E$ is compact if it is continuous and for each bounded subset $U \subset E$, the set $\Phi(U)$ is compact.

3. EXISTENCE OF SOLUTIONS

In this section, we prove Theorem 3.5 which shows the existence of at least one weak solution for system (1.1), via new sub-supersolution method. For this, we recall preliminaries.

Definition 3.1. The pair (u_1, u_2) is called a weak solution of (1.1), if $u_i \in W_0^{1,p_i(x)}(\Omega) \cap L^\infty(\Omega)$ and

$$\begin{aligned} & \int_{\Omega} a_1(|\nabla u_1|^{p_1(x)})|\nabla u_1|^{p_1(x)-2}\nabla u_1\nabla\varphi dx \\ &= \int_{\Omega} \left(\frac{f_1(x, u_1, u_2)|u_2|_{L^{q_1(x)}}^{\alpha_1(x)}}{\mathcal{A}(x, |u_2|_{L^{r_1(x)}})} + \frac{g_1(x, u_1, u_2)|u_2|_{L^{s_1(x)}}^{\gamma_1(x)}}{\mathcal{A}(x, |u_2|_{L^{r_1(x)}})} \right) \varphi dx, \\ & \int_{\Omega} a_2(|\nabla u_2|^{p_2(x)})|\nabla u_2|^{p_2(x)-2}\nabla u_2\nabla\varphi dx \\ &= \int_{\Omega} \left(\frac{f_2(x, u_1, u_2)|u_1|_{L^{q_2(x)}}^{\alpha_2(x)}}{\mathcal{A}(x, |u_1|_{L^{r_2(x)}})} + \frac{g_2(x, u_1, u_2)|u_1|_{L^{s_2(x)}}^{\gamma_2(x)}}{\mathcal{A}(x, |u_1|_{L^{r_2(x)}})} \right) \varphi dx, \end{aligned}$$

for all $\varphi \in W_0^{1,p_i(x)}(\Omega)$ and $i \neq j$ with $i, j = 1, 2$.

Given $u, v \in \mathcal{S}(\Omega)$ we write $u \leq v$ if $u(x) \leq v(x)$ a.e. in Ω . If $u \leq v$ we define

$$[u, v] := \{w \in \mathcal{S}(\Omega) : u(x) \leq w(x) \leq v(x) \text{ a.e. in } \Omega\}.$$

To simplify notation in the next definition we denote

$$\begin{aligned} \tilde{f}_1(x, t, s) &= f_1(x, t, s), & \tilde{g}_1(x, t, s) &= g_1(x, t, s), \\ \tilde{f}_2(x, t, s) &= f_2(x, s, t), & \tilde{g}_2(x, t, s) &= g_2(x, s, t). \end{aligned}$$

Definition 3.2. The pairs $(\underline{u}_i, \bar{u}_i)$, $i = 1, 2$ are called sub-supersolutions for (1.1) if $\underline{u}_i \in W_0^{1,p_i(x)}(\Omega) \cap L^\infty(\Omega)$, $\bar{u}_i \in W^{1,p_i(x)}(\Omega) \cap L^\infty(\Omega)$ with $\underline{u}_i \leq \bar{u}_i$, $\underline{u}_i = 0 \leq \bar{u}_i$ on $\partial\Omega$ and for all $\varphi \in W_0^{1,p_i(x)}(\Omega)$ with $\varphi \geq 0$ the following inequalities hold

$$\begin{aligned} & \int_{\Omega} a_i(|\nabla \underline{u}_i|^{p_i(x)})|\nabla \underline{u}_i|^{p_i(x)-2}\nabla \underline{u}_i\nabla\varphi dx \\ & \leq \int_{\Omega} \left(\frac{\tilde{f}_i(x, \underline{u}_i, w)|\underline{u}_j|_{L^{q_i(x)}}^{\alpha_i(x)}}{\mathcal{A}(x, |w|_{L^{r_i(x)}})} + \frac{\tilde{g}_i(x, \underline{u}_i, w)|\underline{u}_j|_{L^{s_i(x)}}^{\gamma_i(x)}}{\mathcal{A}(x, |w|_{L^{r_i(x)}})} \right) \varphi dx, \\ & \int_{\Omega} |a_i(|\nabla \bar{u}_i|^{p_i(x)})|\nabla \bar{u}_i|^{p_i(x)-2}\nabla \bar{u}_i\nabla\varphi dx \\ & \geq \int_{\Omega} \left(\frac{\tilde{f}_i(x, \bar{u}_i, w)|\bar{u}_j|_{L^{q_i(x)}}^{\alpha_i(x)}}{\mathcal{A}(x, |w|_{L^{r_i(x)}})} + \frac{\tilde{g}_i(x, \bar{u}_i, w)|\bar{u}_j|_{L^{s_i(x)}}^{\gamma_i(x)}}{\mathcal{A}(x, |w|_{L^{r_i(x)}})} \right) \varphi dx, \end{aligned} \tag{3.1}$$

for all $w \in [\underline{u}_j, \bar{u}_j]$ where $i, j = 1, 2$ with $i \neq j$.

Remark 3.3. The space $L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$ with the norm

$$|(u, v)|_{1,2} = |u|_{L^{p_1(x)}} + |v|_{L^{p_2(x)}}.$$

is a Banach space.

In what follows, we study the existence and uniqueness of solution for

$$\begin{aligned} -\operatorname{div}(a_1(|\nabla u|^{p_1(x)})|\nabla u|^{p_1(x)-2}\nabla u) &= G_1(z_1, z_2) \quad \text{in } \Omega, \\ -\operatorname{div}(a_2(|\nabla v|^{p_2(x)})|\nabla v|^{p_2(x)-2}\nabla v) &= G_2(z_1, z_2) \quad \text{in } \Omega, \\ u = v = 0 &\quad \text{on } \partial\Omega, \end{aligned} \tag{3.2}$$

where $(z_1, z_2) \in L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$.

Lemma 3.4. *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a smooth bounded domain and $a_i : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be a C^1 function satisfying (A1), (A2) and (a₃). Assume $G_i : L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega) \rightarrow L^{p'_i(x)}(\Omega)$, where $p'_i(x) = \frac{p_i(x)}{(p_i(x)-1)}$, $G_i(z_1, z_2)$ are continuous and $|G_i(z_1, z_2)| \leq K_i$ for all $(z_1, z_2) \in L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$. Then problem (3.2) has a unique solution $(u, v) \in W_0^{1,l_1(x)}(\Omega) \times W_0^{1,l_2(x)}(\Omega)$.*

Proof. Consider the functional $\mathfrak{J} : W_0^{1,l_1(x)}(\Omega) \times W_0^{1,l_2(x)}(\Omega) \rightarrow \mathbb{R}$ defined as

$$\begin{aligned} \mathfrak{J}(u, v) = & \frac{1}{p_1} \int_{\Omega} A(|\nabla u|^{p_1(x)}) dx + \frac{1}{p_2} \int_{\Omega} A(|\nabla v|^{p_2(x)}) dx \\ & - \int_{\Omega} G_1(z, z) u dx - \int_{\Omega} G_2(z, z) v dx. \end{aligned} \tag{3.3}$$

From (A1) the functional (3.3) is well defined and so $\mathfrak{J} \in C^1(W_0^{1,q_1}(\Omega) \times W_0^{1,q_2}(\Omega), \mathbb{R})$. Notice that, (A2) implies that \mathfrak{J} is strictly convex and weakly lower semicontinuous. Also, (A1), $|G_i(z_1, z_2)| \leq K_i$ and Hölder’s inequality imply

$$\begin{aligned} \mathfrak{J}(u, v) \geq & \frac{k_1}{p_1} \|u\|_{W_0^{1,p_1(x)}(\Omega)}^{p_1(x)} + \frac{k_1}{p_2} \|v\|_{W_0^{1,p_2(x)}(\Omega)}^{p_2(x)} + \frac{k_2}{l_1} \|u\|_{W_0^{1,l_1(x)}(\Omega)}^{l_1(x)} \\ & + \frac{k_2}{l_2} \|v\|_{W_0^{1,l_2(x)}(\Omega)}^{l_2(x)} - K_0 C (\|u\|_{W_0^{1,l_1(x)}(\Omega)} + \|v\|_{W_0^{1,l_2(x)}(\Omega)}) \end{aligned}$$

for $C > 0$ and all $(u, v) \in W_0^{1,l_1(x)}(\Omega) \times W_0^{1,l_2(x)}(\Omega)$ with $\rho(|\nabla u|), \rho(|\nabla v|) \geq 1$, what shows that \mathfrak{J} is coercive. Hence \mathfrak{J} has a unique critical point (a global minimizer), which is the unique solution to (3.2). \square

To state the main result of this article we need the following assumptions on $r_i, p_i, q_i, s_i, \alpha_i, \gamma_i$ in (1.1):

(A4) $p_i \in C^1(\bar{\Omega}), r_i, q_i, s_i \in L^{\infty}_+(\Omega)$, where

$$L^{\infty}_+(\Omega) = \{m \in L^{\infty}(\Omega) \text{ with } \text{ess inf } m(x) \geq 1\}$$

and for $i = 1, 2$, we have $\alpha_i, \gamma_i \in L^{\infty}(\Omega)$ and

$$1 < p_i^- := \inf_{\Omega} p_i(x) \leq p_i^+ := \sup_{\Omega} p_i(x) < N, \quad \alpha_i(x), \gamma_i(x) \geq 0 \quad \text{a.e. in } \Omega.$$

We set

$$\begin{aligned} \underline{\sigma} := \min \{ |\underline{w}|_{L^{r_i(x)}}, \text{ for } i = 1, 2 \}, \quad \bar{\sigma} := \max \{ |\bar{w}|_{L^{r_i(x)}}, \text{ for } i = 1, 2 \}, \\ \underline{w} := \min \{ \underline{u}_i, \text{ for } i = 1, 2 \}, \quad \bar{w} := \max \{ \bar{u}_i, \text{ for } i = 1, 2 \}. \end{aligned} \tag{3.4}$$

Theorem 3.5. *Assume*

- $r_i, p_i, q_i, s_i, \alpha_i$ and γ_i satisfy (A4),
- $(\underline{u}_i, \bar{u}_i)$ is a sub-supersolution for (1.1) with $\underline{u}_i > 0$ a.e. in Ω ,
- $f_i(x, t, s), g_i(x, t, s) \geq 0$ in $\bar{\Omega} \times [0, |\bar{u}_1|_{L^{\infty}}] \times [0, |\bar{u}_2|_{L^{\infty}}]$,
- $\mathcal{A} : \bar{\Omega} \times (0, \infty) \rightarrow \mathbb{R}$ is a continuous function with $\mathcal{A}(x, t) > 0$ in $\bar{\Omega} \times [\underline{\sigma}, \bar{\sigma}]$,
- $a_i : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a C^1 function satisfying (A1), (A2) and (a₃).

Then (1.1) has at least one weak positive solution (u_1, u_2) with $u_i \in [\underline{u}_i, \bar{u}_i], i = 1, 2$.

Proof. For $i = 1, 2$ consider the operators $T_i : L^{p_i(x)}(\Omega) \rightarrow L^{\infty}(\Omega)$ defined by

$$T_i z(x) = \begin{cases} \underline{u}_i(x), & \text{if } z(x) \leq \underline{u}_i(x), \\ z(x), & \text{if } \underline{u}_i(x) \leq z(x) \leq \bar{u}_i(x), \\ \bar{u}_i(x), & \text{if } z(x) \geq \bar{u}_i(x). \end{cases}$$

Since $T_i z \in [\underline{u}_i, \bar{u}_i]$ and $\underline{u}_i, \bar{u}_i \in L^\infty(\Omega)$ it follows that the operators T_i are well-defined.

We define $p'_i(x) = p_i(x)/(p_i(x) - 1)$ and consider the operators $H_i : [\underline{u}_1, \bar{u}_1] \times [\underline{u}_2, \bar{u}_2] \rightarrow L^{p'_i(x)}(\Omega)$ given by

$$H_i(u_1, u_2)(x) = \frac{f_i(x, u_1(x), u_2(x))|u_j|_{L^{q_i(x)}}^{\alpha_i(x)}}{\mathcal{A}(x, |u_j|_{L^{r_i(x)}})} + \frac{g_i(x, u_1(x), u_2(x))|u_j|_{L^{s_i(x)}}^{\gamma_i(x)}}{\mathcal{A}(x, |u_j|_{L^{r_i(x)}})}$$

where $i \neq j$ with $i, j = 1, 2$, and $|\cdot|_{L^m(x)}$ denotes the norm of the space $L^m(x)(\Omega)$.

Since f_i, g_i, \mathcal{A} are continuous functions, $\mathcal{A}(x, t) > 0$ in the compact set $\bar{\Omega} \times [\underline{\sigma}, \bar{\sigma}]$, $T_i z_i \in [\underline{u}_i, \bar{u}_i]$ for all $z_i \in L^{p_i(x)}(\Omega)$, $\underline{u}_i, \bar{u}_i \in L^\infty(\Omega)$, and $|w|_{L^m(x)}^{\theta(x)} \leq |w|_{L^m(x)}^{\theta^-} + |w|_{L^m(x)}^{\theta^+}$ for all $w \in L^m(x)(\Omega)$ with $\theta \in L^\infty(\Omega)$, it follows that there are constants $K_i > 0$ such that

$$|H_i(T_1 z_1, T_2 z_2)| \leq K_i \quad (3.5)$$

for all $(z_1, z_2) \in L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$.

By the Lebesgue Dominated Convergence Theorem, the mappings $(z_1, z_2) \mapsto H_i(T_1 z_1, T_2 z_2)$ from $L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$ to $L^{p'_i(x)}(\Omega)$, $i = 1, 2$, are continuous.

The operator $\Phi : \mathbb{R}^+ \times L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega) \rightarrow L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$ given by

$$\Phi(\lambda, z_1, z_2) = (u_1, u_2),$$

is well-defined, by [21, Theorem 4.1], where $(u_1, u_2) \in W_0^{1, p_1(x)}(\Omega) \times W_0^{1, p_2(x)}(\Omega)$ is the unique solution of

$$\begin{aligned} -\operatorname{div}(a_1(|\nabla u_1|^{p_1(x)})|\nabla u_1|^{p_1(x)-2}\nabla u_1) &= \lambda H_1(T_1 z_1, T_2 z_2) \quad \text{in } \Omega, \\ -\operatorname{div}(a_2(|\nabla u_2|^{p_2(x)})|\nabla u_2|^{p_2(x)-2}\nabla u_2) &= \lambda H_2(T_1 z_1, T_2 z_2) \quad \text{in } \Omega, \\ u_1 = u_2 = 0 &\quad \text{on } \partial\Omega, \end{aligned} \quad (3.6)$$

by Lemma 3.4, where $(z_1, z_2) \in L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$.

Claim 1: Φ is compact. Let $(\lambda_n, z_n^1, z_n^2) \subset \mathbb{R}^+ \times L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$ be a bounded sequence and consider $(u_n^1, u_n^2) = \Phi(\lambda_n, z_n^1, z_n^2)$. The definition of Φ implies that

$$\int_{\Omega} a_i(|\nabla u_n^i|^{p_i(x)-2})|\nabla u_n^i|^{p_i(x)-2}\nabla u_n^i \nabla \varphi = \lambda_n \int_{\Omega} H_i(T_1 z_n^1, T_2 z_n^2)\varphi,$$

for all $\varphi \in W_0^{1, p_i(x)}(\Omega)$, where $i, j = 1, 2$ blue with $i \neq j$.

Considering the test function $\varphi = u_n^i$, the boundness of (λ_n) and inequality (3.5), we obtain

$$\int_{\Omega} |\nabla u_n^i|^{p_i(x)} \leq \bar{\lambda} K_i \int_{\Omega} |u_n^i|$$

for all $n \in \mathbb{N}$. Here $\bar{\lambda}$ is a constant that does not depend on $n \in \mathbb{N}$.

Since $p_i^- > 1$, the embedding $L^{p_i(x)}(\Omega) \hookrightarrow L^1(\Omega)$ is hold. Combining such embedding with the Poincaré inequality we obtain

$$\int_{\Omega} |\nabla u_n^i|^{p_i(x)} \leq C K_i \|u_n^i\|,$$

for all $n \in \mathbb{N}$. Suppose that $|\nabla u_n^i|_{L^{p_i(x)}} > 1$. Thus by Proposition 2.1 we have $\|u_n^i\|^{p^- - 1} \leq C K_i$ for all $n \in \mathbb{N}$ where C is a constant that does not depend on n . Then (u_n^i) is bounded in $W_0^{1, p_i(x)}(\Omega)$. The reflexivity of $W_0^{1, p_i(x)}(\Omega)$ and the compact embedding $W_0^{1, p_i(x)}(\Omega) \hookrightarrow L^{p_i(x)}(\Omega)$ provides the result.

Claim 2: Φ is continuous. Consider a sequence $(\lambda_n, z_n^1, z_n^2)$ in $\mathbb{R}^+ \times L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$ converging to (λ, z^1, z^2) in $\mathbb{R}^+ \times L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$. Define $(u_n^1, u_n^2) = \Phi(\lambda_n, z_n^1, z_n^2)$ and $(u^1, u^2) = \Phi(\lambda, z^1, z^2)$. Using the definition of Φ we obtain

$$\int_{\Omega} a_i(|\nabla u_n^i|^{p_i(x)-2})|\nabla u_n^i|^{p_i(x)-2}\nabla u_n^i\nabla\varphi = \lambda_n \int_{\Omega} H_i(T_1 z_n^1, T_2 z_n^2)\varphi, \tag{3.7}$$

$$\int_{\Omega} a_i(|\nabla u^i|^{p_i(x)-2})|\nabla u^i|^{p_i(x)-2}\nabla u^i\nabla\varphi = \lambda \int_{\Omega} H_i(T_1 z^1, T_2 z^2)\varphi \tag{3.8}$$

for all $\varphi \in W_0^{1,p_i(x)}(\Omega)$ where $i, j = 1, 2$, and $i \neq j$.

Considering $\varphi = (u_n^i - u^i)$ in (3.7) and (3.8) and subtracting (3.8) from (3.7) we obtain

$$\begin{aligned} & \int_{\Omega} \langle a(|\nabla u_n^i|^{p_i(x)-2})|\nabla u_n^i|^{p_i(x)-2}\nabla u_n^i \\ & - a(|\nabla u^i|^{p_i(x)-2})|\nabla u^i|^{p_i(x)-2}\nabla u^i, \nabla(u_n^i - u^i) \rangle \\ & = \int_{\Omega} \lambda_n H(T_1 z_n^1, T_2 z_n^2)(u_n^i - u^i) - \int_{\Omega} \lambda H(T_1 z^1, T_2 z^2)(u_n^i - u^i). \end{aligned}$$

Using Hölder’s inequality we have

$$\begin{aligned} & \left| \int_{\Omega} \langle a(|\nabla u_n^i|^{p_i(x)-2})|\nabla u_n^i|^{p_i(x)-2}\nabla u_n^i \right. \\ & \left. - a(|\nabla u^i|^{p_i(x)-2})|\nabla u^i|^{p_i(x)-2}\nabla u^i, \nabla(u_n^i - u^i) \rangle \right| \\ & \leq |u_n^i - u^i|_{p_i(x)} |\lambda_n H_i(T_1 z_n^1, T_2 z_n^2) - \lambda H_i(T_1 z^1, T_2 z^2)|_{p_i'(x)} \end{aligned}$$

The arguments above ensures that (u_n^i) is bounded in $W_0^{1,p_i(x)}(\Omega)$. Since $\lambda_n \rightarrow \lambda$ and $H_i(T_1 z_n^1, T_2 z_n^2) \rightarrow H_i(T_1 z^1, T_2 z^2)$ in $L^{p_i'(x)}(\Omega)$ for $i = 1, 2$ we have

$$\begin{aligned} & \left| \int_{\Omega} \langle a(|\nabla u_n^i|^{p_i(x)-2})|\nabla u_n^i|^{p_i(x)-2}\nabla u_n^i \right. \\ & \left. - a(|\nabla u^i|^{p_i(x)-2})|\nabla u^i|^{p_i(x)-2}\nabla u^i, \nabla(u_n^i - u^i) \rangle \right| \rightarrow 0. \end{aligned}$$

Therefore $u_n^i \rightarrow u^i$ in $L^{p_i(x)}(\Omega)$ for $i = 1, 2$ which proves the continuity of Φ .

Combining the fact that $\Phi(0, z_1, z_2) = (0, 0, 0)$ for all $(z_1, z_2) \in L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$ with the previous claims we have by Theorem 2.8 that the equation $\Phi(\lambda, u, v) = (u, v)$ possesses an unbounded continuum $\mathcal{C} \subset \mathbb{R}^+ \times L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$ of solutions with $(0, 0, 0) \in \mathcal{C}$.

Claim 3: \mathcal{C} is bounded with respect to the parameter λ . Suppose that there exists $\lambda^* > 0$ such that $\lambda \leq \lambda^*$ for all $(\lambda, u^1, u^2) \in \mathcal{C}$. For $(\lambda, u^1, u^2) \in \mathcal{C}$ the definition of Φ imply that

$$\begin{aligned} & -\operatorname{div}(a(|\nabla u_1|^{p_1(x)-2})|\nabla u_1|^{p_1(x)-2}\nabla u_1) = \lambda H_1(T_1 u_1, T_2 u_2) \quad \text{in } \Omega, \\ & -\operatorname{div}(a(|\nabla u_2|^{p_2(x)-2})|\nabla u_2|^{p_2(x)-2}\nabla u_2) = \lambda H_2(T_1 u_1, T_2 u_2) \quad \text{in } \Omega, \tag{3.9} \\ & u_1 = u_2 = 0 \quad \text{on } \partial\Omega. \end{aligned}$$

Using the test function u_i in (3.9) and considering (3.5), we obtain

$$\int_{\Omega} |\nabla u_i|^{p_i(x)} \leq \lambda^* C |u_i|_{L^{p_i(x)}}.$$

Suppose that $|\nabla u_i|_{L^{p(x)}} > 1$. Then using Proposition 2.1 and the Poincaré inequality we obtain that

$$|u_i|_{L^{p_i(x)}}^{p_i-1} \leq \lambda^* C.$$

Thus \mathcal{C} is bounded in $\mathbb{R}^+ \times L^{p_1(x)}(\Omega) \times L^{p_2(x)}(\Omega)$, which is a contradiction.

Considering $\lambda = 1$, by (3.9) we have

$$\begin{aligned} & \int_{\Omega} a(|\nabla u_i|^{p_i(x)-2}) |\nabla u_i|^{p_i(x)-2} \nabla u_i \nabla \varphi \\ &= \int_{\Omega} \left(\frac{f_i(x, T_1 u_1, T_2 u_2) |T_j u_j|_{L^{q_i(x)}}^{\alpha_i(x)}}{\mathcal{A}(x, |T_j u_j|_{L^{r_i(x)}})} \right) \varphi \\ & \quad + \int_{\Omega} \left(\frac{g_i(x, T_1 u_1, T_2 u_2) |T_j u_j|_{L^{s_i(x)}}^{\gamma_i(x)}}{\mathcal{A}(x, |T_j u_j|_{L^{r_i(x)}})} \right) \varphi, \end{aligned} \quad (3.10)$$

for all $\varphi \in W_0^{1,p_i(x)}(\Omega)$ where $i, j = 1, 2$ with $i \neq j$.

Now we claim that $u_i \in [\underline{u}_i, \bar{u}_i]$ for $i = 1, 2$. To prove this claim we define

$$\begin{aligned} L_1(\underline{u}_1 - u_1)_+ &:= \int_{\{\underline{u}_1 \geq u_1\}} \langle a(|\nabla \underline{u}_1|^{p_1(x)-2}) |\nabla \underline{u}_1|^{p_1(x)-2} \nabla \underline{u}_1 \\ & \quad - a(|\nabla u_1|^{p_1(x)-2}) |\nabla u_1|^{p_1(x)-2} \nabla u_1, \nabla(\underline{u}_1 - u_1) \rangle dx. \end{aligned}$$

Using the facts that $T_2 u_2 \in [\underline{u}_2, \bar{u}_2]$, $\underline{u}_i(x) > 0$ a.e. in Ω , $i = 1, j = 2$, considering $w = T_2 u_2$ and $\varphi = (\underline{u}_1 - u_1)_+$ in the first inequality of (3.1) and combining with equation (3.10) we obtain

$$\begin{aligned} L_1(\underline{u}_1 - u_1)_+ &\leq \int_{\{\underline{u}_1 \geq u_1\}} \frac{f_1(x, \underline{u}_1, T_2 u_2) (|\underline{u}_2|_{L^{q_1(x)}}^{\alpha_1(x)} - |T_2 u_2|_{L^{q_1(x)}}^{\alpha_1(x)})}{\mathcal{A}(x, |T_2 u_2|_{L^{r_1(x)}})} (\underline{u}_1 - u_1) \\ & \quad + \int_{\{\underline{u}_1 \geq u_1\}} \frac{g_1(x, \underline{u}_1, T_2 u_2) (|\underline{u}_2|_{L^{s_1(x)}}^{\gamma_1(x)} - |T_2 u_2|_{L^{s_1(x)}}^{\gamma_1(x)})}{\mathcal{A}(x, |T_2 u_2|_{L^{r_1(x)}})} (\underline{u}_1 - u_1), \end{aligned}$$

which implies that

$$\begin{aligned} & \int_{\{\underline{u}_1 \geq u_1\}} \langle a(|\nabla \underline{u}_1|^{p_1(x)-2}) |\nabla \underline{u}_1|^{p_1(x)-2} \nabla \underline{u}_1 \\ & \quad - a(|\nabla u_1|^{p_1(x)-2}) |\nabla u_1|^{p_1(x)-2} \nabla u_1, \nabla(\underline{u}_1 - u_1) \rangle \leq 0. \end{aligned}$$

Therefore $\underline{u}_1 \leq u_1$. The same reasoning imply the other inequalities. Since $u_i \in [\underline{u}_i, \bar{u}_i]$, we have $T_i u_i = u_i$. Therefore the pair (u_1, u_2) is a weak positive solution of (S) . \square

4. APPLICATIONS

The main goal of this section is to apply Theorem 3.5 to some nonlocal problems.

4.1. A generalized logistic equation. Here we present a generalization of the classic logistic equation studied in [11, 13, 39] and [39, Theorem 8]. We consider

$$\begin{aligned} -\mathcal{A}(x, |v|_{L^{r_1(x)}}) \operatorname{div}(a_1(|\nabla u|^{p_1(x)}) |\nabla u|^{p_1(x)-2} \nabla u) &= \lambda f_1(u) |v|_{L^{q_1(x)}}^{\alpha_1(x)} \quad \text{in } \Omega, \\ -\mathcal{A}(x, |u|_{L^{r_2(x)}}) \operatorname{div}(a_1(|\nabla v|^{p_2(x)}) |\nabla v|^{p_2(x)-2} \nabla v) &= \lambda f_2(v) |u|_{L^{q_2(x)}}^{\alpha_2(x)} \quad \text{in } \Omega, \\ u = v = 0 & \quad \text{on } \partial\Omega. \end{aligned} \quad (4.1)$$

where the function $\mathcal{A}(x, t)$ satisfies

$$\mathcal{A}(x, 0) \geq 0, \quad \lim_{t \rightarrow 0^+} \mathcal{A}(x, t) = \infty, \quad \lim_{t \rightarrow +\infty} \mathcal{A}(x, t) = \pm\infty.$$

Assume that there are numbers $\theta_i > 0$, for $i = 1, 2$ such that the functions $f_i : [0, \infty) \rightarrow \mathbb{R}$ satisfy the conditions:

- (A5) $f_i \in C^0([0, \theta_i], \mathbb{R})$, for $i = 1, 2$,
- (A6) $f_i(0) = f_i(\theta_i) = 0$, $f_i(t) > 0$ in $(0, \theta_i)$ for $i = 1, 2$.

Remark 4.1. Notice that $W_0^{1,p_1(x)}(\Omega) \times W_0^{1,p_2(x)}(\Omega)$ is a Banach space endowed with the norm

$$|(u, v)| := \max \{ |\nabla u|_{p_1(x)}, |\nabla v|_{p_2(x)} \}.$$

Theorem 4.2. *Suppose that r_i, p_i, q_i, α_i satisfy (A4). Assume f_i satisfies (A5), (A6) and $a_i : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a C^1 function satisfying (A1)–(A3) for $i = 1, 2$. If $\mathcal{A}(x, t) > 0$ in $\bar{\Omega} \times (0, \max\{\theta_1|_{L^{r_2(x)}}, \theta_2|_{L^{r_1(x)}}\}]$, then there exists $\lambda_0 > 0$ such that (4.1) has a positive weak solution for $\lambda \geq \lambda_0$.*

Proof. Consider the functions $\tilde{f}_i(t) = f_i(t)$ for $t \in [0, \theta_i]$, and $\tilde{f}_i(t) = 0$ for $t \in \mathbb{R} \setminus [0, \theta_i]$, $i = 1, 2$. The functional

$$\begin{aligned} J_\lambda(u, v) &= \int_\Omega \frac{1}{p_1(x)} A(|\nabla u|^{p_1(x)}) dx + \int_\Omega \frac{1}{p_2(x)} A(|\nabla v|^{p_2(x)}) dx \\ &\quad - \lambda \int_\Omega \tilde{F}_1(u) dx - \lambda \int_\Omega \tilde{F}_2(v) dx \\ &:= J_{1,\lambda}(u) + J_{2,\lambda}(v), \end{aligned}$$

where $\tilde{F}_i(t) = \int_0^t \tilde{f}_i(s) ds$ is of class $C^1(W_0^{1,p_1(x)} \times W_0^{1,p_2(x)}(\Omega), \mathbb{R})$.

Since $|\tilde{f}_i(t)| \leq C$, $t \in \mathbb{R}$ for some constant which does not depends on $i = 1, 2$ we have that J is coercive. Thus J has a minimum $(z_\lambda, w_\lambda) \in W_0^{1,p_1(x)}(\Omega) \times W_0^{1,p_2(x)}(\Omega)$ with

$$\begin{aligned} -\operatorname{div}(a_1(|\nabla z_\lambda|^{p_1(x)})|\nabla z_\lambda|^{p_1(x)-2}\nabla z_\lambda) &= \lambda \tilde{f}_1(z_\lambda) \quad \text{in } \Omega, \\ z_\lambda &= 0 \quad \text{on } \partial\Omega, \end{aligned} \tag{4.2}$$

and

$$\begin{aligned} -\operatorname{div}(a_2(|\nabla w_\lambda|^{p_2(x)})|\nabla w_\lambda|^{p_2(x)-2}\nabla w_\lambda) &= \lambda \tilde{f}_2(w_\lambda) \quad \text{in } \Omega, \\ w_\lambda &= 0 \quad \text{on } \partial\Omega. \end{aligned} \tag{4.3}$$

Note that the unique solutions of (4.2) and (4.3) are given by the minimum of functionals $J_{1,\lambda}$ and $J_{2,\lambda}$ respectively.

Consider a function $\varphi_0 \in W_0^{1,p_i(x)}(\Omega)$ for for $i = 1, 2$, with $\tilde{F}_i(\varphi_0) > 0$, for $i = 1, 2$. Define $(z_0, w_0) := (z_{\tilde{\lambda}_0}, w_{\tilde{\lambda}_0})$, where $\tilde{\lambda}_0$ satisfies

$$\int_\Omega \frac{1}{p_i(x)} A(|\nabla \varphi_0|^{p_i(x)}) dx < \tilde{\lambda}_0 \int_\Omega \tilde{F}_i(\varphi_0) dx,$$

for $i = 1, 2$. We have $J_{1,\tilde{\lambda}_0}(z_0) \leq J_{1,\tilde{\lambda}_0}(\varphi_0) < 0$ and also that $J_{2,\tilde{\lambda}_0}(z_0) < 0$. Therefore $z_0 \neq 0$ and $w_0 \neq 0$. Since $-\operatorname{div}(a_1(|\nabla z_0|^{p_1(x)})|\nabla z_0|^{p_1(x)-2}\nabla z_0)$ and $-\operatorname{div}(a_2(|\nabla w_0|^{p_2(x)})|\nabla w_0|^{p_2(x)-2}\nabla w_0)$ are nonnegative, we have $z_0, w_0 > 0$ in Ω . Note that by [22, Theorem 4.1] and [19, Theorem 1.2], we obtain that $z_0, w_0 \in C^{1,\alpha}(\bar{\Omega})$ for some $\alpha \in (0, 1]$.

Using the test function $\varphi = (z_0 - \theta_1)^+ \in W_0^{1,p_1(x)}(\Omega)$ in (4.2) we obtain

$$\begin{aligned} & \int_{\Omega} a_1(|\nabla z_0|^{p_1(x)})|\nabla z_0|^{p_1(x)-2}\nabla z_0\nabla(z_0 - \theta_1)^+ dx \\ &= \tilde{\lambda}_0 \int_{\{z_0 > \theta_1\}} \tilde{f}_1(z_0)(z_0 - \theta_1) dx = 0. \end{aligned}$$

Therefore

$$\begin{aligned} & \int_{\{z_0 > \theta_1\}} \langle a_1(|\nabla z_0|^{p_1(x)})|\nabla z_0|^{p_1(x)-2}\nabla z_0 \\ & - a_1(|\nabla \theta_1|^{p_1(x)})|\nabla \theta_1|^{p_1(x)-2}\nabla \theta_1, \nabla(z_0 - \theta_1) \rangle dx = 0, \end{aligned}$$

which imply $(z_0 - \theta_1)_+ = 0$ in Ω . Thus $0 < z_0 \leq \theta_1$. A similar reasoning provides $0 < w_0 \leq \theta_2$.

Note that there is a constant $C > 0$ such that $|z_0|_{L^{q_1(x)}}, |w_0|_{L^{q_2(x)}} \geq C$. Define

$$\begin{aligned} \mathcal{A}_0 := \max \{ & \mathcal{A}(x, t) : (x, t) \in \bar{\Omega} \times [\min\{|z_0|_{L^{r_2(x)}}, |w_0|_{L^{r_1(x)}}\}, \\ & \max\{|\theta_1|_{L^{r_2(x)}}, |\theta_2|_{L^{r_1(x)}}\}] \} \end{aligned}$$

and $\mu_0 = \mathcal{A}_0/C$. Then

$$\begin{aligned} -\operatorname{div}(a_1(|\nabla z_\lambda|^{p_1(x)})|\nabla z_\lambda|^{p_1(x)-2}\nabla z_\lambda) &= \tilde{\lambda}_0 f_1(z_0) \\ &= \frac{1}{\mathcal{A}_0} \tilde{\lambda}_0 \mu_0 f_1(z_0) |w_0|_{L^{q_1(x)}}, \frac{\mathcal{A}_0}{\mu_0 |z_0|_{L^{q_1(x)}}} \\ &\leq \frac{1}{\mathcal{A}_0} \tilde{\lambda}_0 \mu_0 f_1(z_0) |w_0|_{L^{q_1(x)}}. \end{aligned}$$

Thus for each $\lambda \geq \lambda_0 := \tilde{\lambda}_0 \mu_0$ and $w \in [w_0, \theta_2]$, we obtain

$$-\operatorname{div}(a_1(|\nabla z_\lambda|^{p_1(x)})|\nabla z_\lambda|^{p_1(x)-2}\nabla z_\lambda) \leq \frac{1}{\mathcal{A}(x, |w|_{L^{r_1(x)}})} \lambda f_1(z_0) |w_0|_{L^{q_1(x)}}.$$

If necessary, we can consider a larger $\lambda_0 > 0$ such that

$$-\operatorname{div}(a_2(|\nabla w_0|^{p_2(x)})|\nabla w_0|^{p_2(x)-2}\nabla w_0) \leq \frac{1}{\mathcal{A}(x, |w|_{L^{r_2(x)}})} \lambda f_2(w_0) |z_0|_{L^{q_2(x)}},$$

for all $\lambda \geq \lambda_0$ and $w \in [z_0, \theta_1]$. Since $f_i(\theta_i) = 0$ for $i = 1, 2$, we have that (z_0, θ_1) and (w_0, θ_2) are sub-supersolutions pairs for (4.1). \square

4.2. Sublinear problem. Here, we study a nonlocal problem to generalize [39, Theorem 6]. We prove the following theorem.

Theorem 4.3. *Assume that*

- p_i, q_i, r_i, s_i for $i = 1, 2$ satisfy (A4);
- $\alpha_i, \beta_i \in L^\infty(\Omega)$, for $i = 1, 2$;
- for $i = 1, 2$, we have

$$\begin{aligned} 0 < \alpha_1^+ + \gamma_1^+ < p_i^- - 1, \quad 0 < \frac{\alpha_1^+}{p_2^- - 1} + \frac{\beta_1^+}{p_1^- - 1} < 1, \\ 0 < \alpha_2^+ + \gamma_2^+ < p_i^- - 1, \quad 0 < \frac{\alpha_2^+}{p_1^- - 1} + \frac{\beta_2^+}{p_2^- - 1} < 1; \end{aligned}$$

- $a_0 > 0$ is a positive constant;
- One of the following two conditions holds

- (A7) $\mathcal{A}(x, t) \geq a_0$ on $\overline{\Omega} \times [0, \infty)$,
- (A8) $0 < \mathcal{A}(x, t) \leq a_0$ on $\overline{\Omega} \times (0, \infty)$, and $\lim_{t \rightarrow +\infty} \mathcal{A}(x, t) = a_\infty > 0$ uniformly on Ω .

Then the problem

$$\begin{aligned} -\mathcal{A}(x, |v|_{L^{r_1(x)}}) (\Delta_{p_1(x)} u - \Delta u) &= (u^{\beta_1(x)} + v^{\gamma_1(x)}) |v|_{L^{q_1(x)}}^{\alpha_1(x)} \quad \text{in } \Omega, \\ -\mathcal{A}(x, |u|_{L^{r_2(x)}}) (\Delta_{p_2(x)} v - \Delta v) &= (u^{\beta_2(x)} + v^{\gamma_2(x)}) |u|_{L^{q_2(x)}}^{\alpha_2(x)} \quad \text{in } \Omega, \\ u = v = 0 &\quad \text{on } \partial\Omega, \end{aligned} \tag{4.4}$$

has a positive solution.

Proof. Suppose that (A7) is hold, that is, $\mathcal{A}(x, t) \geq a_0$ in $\overline{\Omega} \times [0, +\infty)$. We start by constructing (\bar{u}, \bar{v}) . Let $\lambda > 0$ be a positive number, which will be chosen later and denote by $z_\lambda \in W_0^{1,p_1(x)}(\Omega) \cap L^\infty(\Omega)$ and $y_\lambda \in W_0^{1,p_2(x)}(\Omega) \cap L^\infty(\Omega)$ the unique solutions of (2.1) respectively.

For $\lambda > 0$ sufficiently large it follows from Lemma 2.7 that there is a constant $K > 1$ that does not depend on λ such that

$$0 < z_\lambda(x) \leq K \lambda^{\frac{1}{p_1^- - 1}} \quad \text{in } \Omega, \tag{4.5}$$

$$0 < y_\lambda(x) \leq K \lambda^{\frac{1}{p_2^- - 1}} \quad \text{in } \Omega. \tag{4.6}$$

Since $\alpha_1^+ + \gamma_1^+ < p_2^- - 1$ and $\frac{\alpha_1^+}{p_2^- - 1} + \frac{\beta_1^+}{p_1^- - 1} < 1$, it is possible to choose $\lambda > 1$ such that (4.5), (4.6) and

$$\frac{1}{a_0} (K^{\beta_1^+} \lambda^{\frac{\beta_1^+}{p_1^- - 1} + \frac{\alpha_1^+}{p_2^- - 1}} + K^{\gamma_1^+} \lambda^{\frac{\alpha_1^+ + \gamma_1^+}{p_2^- - 1}}) \max\{|K|_{L^{q_1(x)}}^{\alpha_1^-}, |K|_{L^{q_1(x)}}^{\alpha_1^+}\} \leq \lambda \tag{4.7}$$

occur. By (4.5), (4.6) and (4.7), we obtain

$$\frac{1}{a_0} (z_\lambda^{\beta_1(x)} + w^{\gamma_1(x)}) |y_\lambda|_{L^{q_1(x)}}^{\alpha_1(x)} \leq \lambda, w \in [0, y_\lambda].$$

Thus for $w \in [0, y_\lambda]$ we obtain

$$\begin{aligned} -\Delta_{p_1(x)} z_\lambda - \Delta z_\lambda &\geq \frac{1}{\mathcal{A}(x, |w|_{L^{r_1(x)}})} (z_\lambda^{\beta_1(x)} + w^{\gamma_1(x)}) |y_\lambda|_{L^{q_1(x)}}^{\alpha_1(x)} \quad \text{in } \Omega, \\ z_\lambda &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

Considering, if necessary, a larger $\lambda > 0$ the previous reasoning implies that

$$\begin{aligned} -\Delta_{p_2(x)} y_\lambda - \Delta y_\lambda &\geq \frac{1}{\mathcal{A}(x, |w|_{L^{r_2(x)}})} (w^{\beta_2(x)} + y_\lambda^{\gamma_2(x)}) |z_\lambda|_{L^{q_2(x)}}^{\alpha_2(x)} \quad \text{in } \Omega, \\ y_\lambda &= 0 \quad \text{on } \partial\Omega, \end{aligned}$$

for all $w \in [0, z_\lambda]$.

Now, we construct $(u_i, v_i), i = 1, 2$. Since $\partial\Omega$ is C^2 , there is a constant $\delta > 0$ such that $d \in C^2(\overline{\Omega_{3\delta}})$ and $|\nabla d(x)| \equiv 1$, where $d(x) := \text{dist}(x, \partial\Omega)$ and $\overline{\Omega_{3\delta}} := \{x \in \overline{\Omega}; d(x) \leq 3\delta\}$. From [29, Page 12], for $\sigma \in (0, \delta)$ sufficiently small, the function $\phi_i = \phi_i(k, \sigma), i = 1, 2$ defined by

$$\phi_i(x) = \begin{cases} e^{kd(x)} - 1 & \text{if } d(x) < \sigma, \\ e^{k\sigma} - 1 + \int_\sigma^{d(x)} k e^{k\sigma} \left(\frac{2\delta-t}{2\delta-\sigma}\right)^{\frac{2}{p_i^- - 1}} dt & \text{if } \sigma \leq d(x) < 2\delta, \\ e^{k\sigma} - 1 + \int_\sigma^{2\delta} k e^{k\sigma} \left(\frac{2\delta-t}{2\delta-\sigma}\right)^{\frac{2}{p_i^- - 1}} dt & \text{if } 2\delta \leq d(x), \end{cases}$$

belongs to $C_0^1(\bar{\Omega})$, where $k > 0$ is an arbitrary number and that

$$-\Delta_{p_i(x)}(\mu\phi_i) = \begin{cases} -k(k\mu e^{kd(x)})^{p_i(x)-1} \left[(p_i(x) - 1) + (d(x) + \frac{\ln k\mu}{k}) \nabla p_i(x) \nabla d(x) + \frac{\Delta d(x)}{k} \right] & \text{if } d(x) < \sigma, \\ \left\{ \frac{1}{2\delta - \sigma} \frac{2(p_i(x)-1)}{p_i^- - 1} - \left(\frac{2\delta - d(x)}{2\delta - \sigma} \right) \times \left[\ln k\mu e^{k\sigma} \right. \right. \\ \left. \left. \left(\frac{2\delta - d(x)}{2\delta - \sigma} \right)^{p_i^- - 1} \nabla p_i(x) \nabla d(x) + \Delta d(x) \right] \right\} \\ \times (k\mu e^{k\sigma})^{p_i(x)-1} \left(\frac{2\delta - d(x)}{2\delta - \sigma} \right)^{\frac{2(p_i(x)-1)}{p_i^- - 1} - 1} & \text{if } \sigma < d(x) < 2\delta, \\ 0 & \text{if } 2\delta < d(x), \end{cases}$$

and

$$-\Delta(\mu\phi_i) = \begin{cases} -k(k\mu e^{kd(x)}) \left[1 + \frac{\Delta d(x)}{k} \right] & \text{if } d(x) < \sigma, \\ \left\{ \frac{2}{2\delta - \sigma} - \left(\frac{2\delta - d(x)}{2\delta - \sigma} \right) \Delta d(x) \right\} (k\mu e^{k\sigma}) \left(\frac{2\delta - d(x)}{2\delta - \sigma} \right) & \text{if } \sigma < d(x) < 2\delta, \\ 0 & \text{if } 2\delta < d(x), \end{cases}$$

for all $\mu > 0$ and $i = 1, 2$.

Define $\mathcal{A}_\lambda := \max\{\mathcal{A}(x, t) : (x, t) \in \bar{\Omega} \times [0, \max\{|y_\lambda|_{L^{r_1(x)}}|z_\lambda|_{L^{r_2(x)}}\}]\}$. We have

$$a_0 \leq \mathcal{A}(x, |w|_{L^{r_1(x)}}) \leq \mathcal{A}_\lambda \quad \text{in } \Omega$$

for all $w \in [0, y_\lambda]$.

Let $\sigma = \frac{1}{k} \ln 2$ and $\mu = e^{-ak}$ where

$$a = \frac{\min\{p_1^- - 1, p_2^- - 1\}}{\max\{\max_{\bar{\Omega}} |\nabla p_1| + 1, \max_{\bar{\Omega}} |\nabla p_2| + 1\}}.$$

Then $e^{k\sigma} = 2$ and $k\mu \leq 1$ if $k > 0$ is sufficiently large.

Let $x \in \Omega$ with $d(x) < \sigma$. If $k > 0$ is large enough we have $|\nabla d(x)| = 1$ and then we have

$$\begin{aligned} \left| d(x) + \frac{\ln(k\mu)}{k} \right| |\nabla p_1(x)| |\nabla d(x)| &\leq \left(|d(x)| + \frac{|\ln(k\mu)|}{k} \right) |\nabla p_1(x)| \\ &\leq \left(\sigma - \frac{\ln(k\mu)}{k} \right) |\nabla p_1(x)| \\ &= \left(\frac{\ln 2}{k} - \frac{\ln k}{k} \right) |\nabla p_1(x)| + a |\nabla p_1(x)| \\ &< p_1^- - 1. \end{aligned} \tag{4.8}$$

Note that there exists a constant $A > 0$, that does not depend on k , such that $|\Delta d(x)| < A$ for all $x \in \bar{\Omega}_{3\delta}$. Using the above inequality and the expression of $-\Delta_{p_1(x)}(\mu\phi)$ and $-\Delta(\mu\phi)$, we obtain $-\Delta_{p_1(x)}(\mu\phi_1) - \Delta(\mu\phi_1) \leq 0$ for $x \in \Omega$ with $d(x) < \sigma$ or $d(x) > 2\delta$ for $k > 0$ large enough. Therefore

$$\begin{aligned} -\Delta_{p_1(x)}(\mu\phi_1) - \Delta(\mu\phi_1) &\leq 0 \leq \frac{1}{\mathcal{A}_\lambda} (\mu\phi_1)^{\beta_1(x)} |\mu\phi_2|_{L^{q_1(x)}}^{\alpha_1(x)} \\ &\leq \frac{1}{\mathcal{A}_\lambda} ((\mu\phi_1)^{\beta_1(x)} + w^{\gamma_1(x)}) |\mu\phi_2|_{L^{q_1(x)}}^{\alpha_1(x)} \end{aligned}$$

for all $w \in L^\infty(\Omega)$ with $w \geq \mu\phi_2$ and $d(x) < \sigma$ or $2\delta < d(x)$. Using an idea in [29, estimate (3.10)], if $\sigma < d(x) < 2\delta$, then

$$\begin{aligned}
 -\Delta_{p_1(x)}(\mu\phi_1) - \Delta(\mu\phi_1) &\leq \tilde{C}(k\mu)^{p_1^- - 1} |\ln k\mu| + \tilde{C}(k\mu) |\ln k\mu| \\
 &= \tilde{C}((k\mu)^{p_1^- - 1} + k\mu) \left| \ln \frac{k}{e^{ak}} \right|.
 \end{aligned}
 \tag{4.9}$$

[40, Theorem 2] and $\alpha_1^+ + \gamma_1^+ < p_1^- - 1$ imply

$$\lim_{k \rightarrow +\infty} \frac{\tilde{C}k^{p_1^- - 1} + \tilde{C}k}{e^{ak(p_1^- - 1 - (\alpha_1^+ + \gamma_1^+))}} \left| \ln \frac{k}{e^{ak}} \right| = 0.
 \tag{4.10}$$

Note that $\phi_1(x) \geq 1$ if $\sigma \leq d(x) < 2\delta$ because $\phi_1(x) \geq e^{k\sigma} - 1$ and $e^{k\sigma} = 2$ for all $k > 0$. Thus, there is a constant $C_0 > 0$ that does not depend on k such that $|\phi_2|_{L^{q_1(x)}(\Omega)}^{\alpha_1(x)} \geq C_0$ if $\sigma < d(x) < 2\delta$. By (4.10), we can choose $k > 0$ large enough such that

$$\frac{\tilde{C}k^{p_1^- - 1} \tilde{C}k}{e^{ak[(p_1^- - 1) - (\alpha_1^+ + \beta_1^+)]}} \left| \ln \frac{k}{e^{ak}} \right| \leq \frac{C_0}{\mathcal{A}_\lambda}.
 \tag{4.11}$$

Therefore from (4.9) and (4.11), we have

$$-\Delta_{p_1(x)}(\mu\phi_1) - \Delta(\mu\phi_1) \leq \frac{1}{\mathcal{A}_\lambda} ((\mu\phi_1)^{\beta_1(x)} + w^{\gamma_1(x)}) |\mu\phi_2|_{L^{q_1(x)}(\Omega)}^{\alpha_1(x)},$$

for all $w \in L^\infty(\Omega)$ with $w \geq \mu\phi_2$ and $\sigma < d(x) < 2\delta$ for $k > 0$ large enough. Thus it is possible to conclude that

$$-\Delta_{p_1(x)}(\mu\phi_1) - \Delta(\mu\phi_1) \leq \frac{1}{\mathcal{A}_\lambda} ((\mu\phi_1)^{\beta_1(x)} + w^{\gamma_1(x)}) |\mu\phi_2|_{L^{q_1(x)}(\Omega)}^{\alpha_1(x)} \quad \text{in } \Omega.$$

Fix $k > 0$ satisfying the above property and the inequality $-\Delta_{p_1(x)}(\mu\phi_1) - \Delta(\mu\phi_1) \leq 1$. For $\lambda > 1$ we have $-\Delta_{p_1(x)}(\mu\phi_1) - \Delta(\mu\phi_1) \leq -\Delta_{p_1(x)}z_\lambda - \Delta z_\lambda$. Therefore $\mu\phi_1 \leq z_\lambda$.

Since $\alpha_2^+ + \gamma_2^+ < p_2^- - 1$, a similar reasoning imply that there is $\mu > 0$ small enough such that

$$-\Delta_{p_2(x)}(\mu\phi_2) - \Delta(\mu\phi_2) \leq \frac{1}{\mathcal{A}(x, |w|_{L^{r_2(x)}})} (w^{\beta_2} + (\mu\phi_2)^{\gamma_2}) |\mu\phi_1|_{L^{q_2(x)}(\Omega)}^{\alpha_2(x)}$$

in Ω for all $w \in L^\infty(\Omega)$ with $w \geq \mu\phi_1$ and that $\mu_2\phi \leq y_\lambda$. The first part of the result is proved.

Now suppose that $0 < \mathcal{A}(x, t) \leq a_0$ in $\bar{\Omega} \times (0, \infty)$. Let $\delta, \sigma, \mu, a, \lambda, z_\lambda, y_\lambda$ and $\phi_i, i = 1, 2$ as before. From the previous arguments there exist $k > 0$ large enough and $\mu > 0$ small such that

$$\begin{aligned}
 -\Delta_{p_1(x)}(\mu\phi_1) - \Delta(\mu\phi_1) &\leq 1 \quad \text{in } \Omega, \\
 -\Delta_{p_1(x)}(\mu\phi) - \Delta(\mu\phi) &\leq \frac{1}{a_0} ((\mu\phi_1)^{\beta_1(x)} + w^{\gamma_1(x)}) |\mu\phi_2|_{L^{q_1(x)}(\Omega)}^{\alpha_1(x)} \quad \text{in } \Omega
 \end{aligned}
 \tag{4.12}$$

for all $w \in [\mu\phi_2, y_\lambda]$, also that

$$\begin{aligned}
 -\Delta_{p_2(x)}(\mu\phi_2) - \Delta(\mu\phi_2) &\leq 1 \quad \text{in } \Omega \\
 -\Delta_{p_2(x)}(\mu\phi_2) - \Delta(\mu\phi_2) &\leq \frac{1}{a_0} (w^{\beta_2(x)} + (\mu\phi_2)^{\gamma_2(x)}) |\mu\phi_1|_{L^{q_2(x)}(\Omega)}^{\alpha_2(x)} \quad \text{in } \Omega
 \end{aligned}
 \tag{4.13}$$

for all $w \in [\mu\phi_1, z_\lambda]$. Since $\lim_{t \rightarrow \infty} \mathcal{A}(x, t) = a_\infty > 0$ uniformly in Ω there is a large constant $a_1 > 0$ such that $\mathcal{A}(x, t) \geq \frac{a_\infty}{2}$ in $\bar{\Omega} \times (a_1, \infty)$. Let

$$m_k := \min \{ \mathcal{A}(x, t) : (x, t) \in \bar{\Omega} \times [\min\{|\mu\phi_1|_{L^{r_1}(x)}, |\mu\phi_2|_{L^{r_2}(x)}\}, a_1] \} > 0,$$

$$\mathcal{A}_k := \min \left\{ m_k, \frac{a_\infty}{2} \right\}.$$

We have $\mathcal{A}(x, t) \geq \mathcal{A}_k$ in $\bar{\Omega} \times [\min\{|\mu\phi_1|_{L^{r_1}(x)}, |\mu\phi_2|_{L^{r_2}(x)}\}, \infty)$.

Fix $k > 0$ satisfying (4.12) and (4.13). Consider $\lambda > 1$ such that (4.5), (4.6), and

$$\frac{1}{\mathcal{A}_k} \left(K^{\beta_1^+} \lambda^{\frac{\beta_1^+}{p_1-1} + \frac{\alpha_1^+}{p_2-1}} + K^{\gamma_1^+} \lambda^{\frac{\alpha_1^+ + \gamma_1^+}{p_2-1}} \right) \max\{|K|_{L^{q_1}(x)}^{\alpha_1^-}, |K|_{L^{q_1}(x)}^{\alpha_1^+}\} \leq \lambda,$$

$$\frac{1}{\mathcal{A}_k} \left(K^{\beta_2^+} \lambda^{\frac{\beta_2^+ + \alpha_2^+}{p_1-1}} + K^{\gamma_2^+} \lambda^{\frac{\gamma_2^+}{p_2-1} + \frac{\alpha_2^+}{p_1-1}} \right) \max\{|K|_{L^{q_2}(x)}^{\alpha_2^+}, |K|_{L^{q_2}(x)}^{\alpha_2^-}\} \leq \lambda$$

where $K > 1$ is a constant that does not depend on k and λ (see Lemma 2.7). Therefore,

$$-\Delta_{p_1(x)} z_\lambda - \Delta z_\lambda \leq \frac{1}{\mathcal{A}(x, |w|_{L^{r_1}(x)})} (z_\lambda^{\beta_1(x)} + w^{\gamma_1(x)}) |y_\lambda|_{L^{q_1}(x)}^{\alpha_1(x)}$$

in $\Omega, w \in [\mu\phi_2, y_\lambda]$. Arguing as before and considering a suitable choice for λ and k , we obtain

$$-\Delta_{p_2(x)} y_\lambda - \Delta y_\lambda \leq \frac{1}{\mathcal{A}(x, |w|_{L^{r_2}(x)})} (w^{\beta_2(x)} + y_\lambda^{\gamma_2(x)}) |z_\lambda|_{L^{q_2}(x)}^{\alpha_2(x)}$$

in $\Omega, w \in [\mu\phi_1, z_\lambda]$. The comparison principle imply that $\mu\phi_1 \leq z_\lambda$ and $\mu\phi_2 \leq y_\lambda$ if μ is small. \square

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