

## EXISTENCE AND STABILITY OF SOLUTIONS FOR A VISCOELASTIC COUPLED SYSTEM OF TWO WAVE EQUATIONS

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ABSTRACT. In this work, we consider the coupled viscoelastic wave system

$$\begin{aligned}u_{tt} - \Delta u + \int_0^t g(t-s)\Delta u \, ds + \alpha v &= 0, & \text{in } \Omega \times (0, T), \\v_{tt} - \Delta v + \alpha u &= 0, & \text{in } \Omega \times (0, T), \\u = v = 0, & \text{on } \partial\Omega \times (0, T), \\u(0) = u_0, \quad u_t(0) = u_1, \quad v(0) = v_0, \quad v_t(0) = v_1, & \text{in } \Omega,\end{aligned}$$

where  $\Omega$  is a bounded domain in  $\mathbb{R}^N$ ,  $\alpha > 0$ , and the initial data belong to suitable spaces. The relaxation function  $g$  satisfies  $g'(t) \leq -\xi(t)G(g(t))$ , where  $G$  is an increasing and convex function near the origin and  $\xi$  is a non-increasing function. We first prove the well-posedness of the problem, and then we establish a general decay rate of the system energy, highlighting the influence of the relaxation function on the stability of the solutions. Numerical tests were also conducted to validate our theoretical findings.

### 1. INTRODUCTION

Wave equations with memory effects have been a central topic in the analysis of partial differential equations, owing to their applications in physics, engineering, and material science. The focus has been on the existence, stability, and energy decay of solutions, with significant progress made for both single and coupled wave equations. To motivate our work, data collected and results are reviewed to provide a thorough study of both the single and coupled viscoelastic wave equation. We start with the pioneer works of Dafermos [10, 11], where the author showed that solutions decay to zero for smooth, monotone relaxation functions  $g$ , but the decay rate remained unspecified. Cavalcanti et al. [7] studied

$$|u_t|^\rho u_{tt} - \Delta u - \Delta u_{tt} + \int_0^t g(t-s)\Delta u(s) \, ds - \gamma \Delta u_t = 0, \quad \text{in } \Omega \times \mathbb{R}_+^*$$

proving global existence for  $\gamma \geq 0$  and exponential energy decay for  $\gamma > 0$ . Messaoudi and Tatar [25, 26] extended these results to include source terms, showing exponential and polynomial decay depending on the rate of decay of  $g(t)$ . Cavalcanti et al. [8] considered a viscoelastic wave equation with a local frictional damping, where the kernel  $g$  satisfies, for two positive constants  $\xi_1$  and  $\xi_2$ ,

$$-\xi_1 g(t) \leq g'(t) \leq -\xi_2 g(t), \quad \forall t \in \mathbb{R}_+.$$

Under the above assumptions and subject to certain restrictions on the control zone, they established an exponential decay result. Berrimi and Messaoudi [5] later improved this result by proving that the viscoelastic dissipation alone is sufficient to stabilize the system, and subsequently extended it to the case where a source term competes with the dissipation [6]. Further contributions including the analysis of nonlinear damping with polynomially decaying kernels [9] and global existence with uniform decay for source-type problems [17] appeared later. Without restricting  $g(t)$

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to exponential or polynomial decay, Messaoudi [20, 21] generalized all the existing decay results by considering the following equation

$$u_{tt} - \Delta u + \int_0^t g(t-\tau)\Delta u(\tau) d\tau = b|u|^\gamma u, \quad b \geq 0,$$

where  $g'(t) \leq -\xi(t)g(t)$ , for a non-increasing differentiable  $\xi(t)$ . These latter results inspired other authors and more results have been established, see [33, 14, 32, 34, 23].

Further improvement was established by Messaoudi and Al-Khulaifi [24], who addressed the problem in [7], for  $\gamma = 0$  and for a kernel satisfying, for  $1 \leq p \leq \frac{3}{2}$ , the condition

$$g'(t) \leq -\xi(t)g^p(t), \quad \forall t \in \mathbb{R}_+.$$

They proved that the energy of solutions converges to zero at the same rate as  $g(t)$ , provided  $g(t)$  decays faster than  $s^{-2}$  at infinity. Later, Mustafa [27] extended his earlier joint work with Messaoudi [28], which dealt with kernels satisfying  $g'(t) \leq -G(g(t))$ , to the more general condition

$$g'(t) \leq -\xi(t)G(g(t)), \quad \forall t \in \mathbb{R}_+,$$

where  $G$  is strictly increasing and convex function. This extension provided explicit energy decay estimates and encompassed a wider range of decay behaviors.

Coupled wave systems also have consistently drawn attention due to their fundamental role in understanding stability and long-term dynamics. In a recent contribution, Guesmia, Messaoudi, and Zahri [13] analyzed an abstract coupled system involving a viscoelastic component interacting with a purely elastic one. Precisely, they looked into the problem

$$\begin{aligned} u_{tt}(t) + Au(t) - \int_0^t g(s)A^\theta u(t-s) ds + \alpha u + \beta Bv(t) &= f(u), \quad t > 0, \\ v_{tt}(t) + Av(t) + \beta Bu(t) &= 0, \quad t > 0, \\ u(0) = u_0, \quad u_t(0) = u_1, \quad v(0) = v_0, \quad v_t(0) = v_1, \end{aligned}$$

where  $A$  is a self-adjoint positive operator on a Hilbert space  $H$ ,  $\theta \in [0, 1]$ ,  $\alpha > 0$ , and  $g$  is a positive nonincreasing relaxation function. Their analysis established general decay rates for the system energy, showing that the asymptotic behavior depends strongly on the relaxation function and the coupling parameter. Numerical experiments were also provided, highlighting the impact of memory effects on the qualitative behavior of solutions. Earlier, Feng and Li [12] considered a viscoelastic Lamé system with strong damping terms. For two distinct relaxation kernels  $g_1$  and  $g_2$ , they assumed conditions of the form  $g'_i(t) \leq -\xi_i(t)H_i(g_i(t))$  ( $i = 1, 2$ ), which led to explicit and general decay results. Their work improved earlier results of Beniani, Taouaf, and Benaissa [4], who had previously established a general decay property for similar coupled viscoelastic structures. Further investigations were carried out by Jin et al. [15], who studied a coupled system of two abstract evolution equations with finite memory, given by

$$\begin{aligned} u_{tt}(t) + Au(t) - \int_0^t g(s)Au(t-s) ds + \alpha u + \beta Bv(t) &= f(u), \quad t > 0, \\ v_{tt}(t) + Av(t) + \beta Bu(t) &= 0, \quad t > 0, \end{aligned}$$

where  $A$  and  $B$  are operators,  $\alpha \geq 0$ ,  $\beta > 0$ , and  $f$  is a nonlinear source. Under appropriate assumptions on  $g$  and structural conditions on  $A$ ,  $B$ , and  $f$ , they proved polynomial stability with decay rates of order  $t^{-1}$ . Several extensions and related contributions in this direction may be found in [31, 3]. In addition to viscoelastic systems, purely elastic coupled wave models have also been studied. For instance, a weakly coupled system

$$\begin{aligned} u_{tt} - \Delta u + u_t + \alpha v &= 0, \quad \text{in } \Omega \times (0, \infty), \\ v_{tt} - \Delta v + \alpha u &= 0, \quad \text{in } \Omega \times (0, \infty), \end{aligned}$$

was analyzed in [19], where  $\Omega \subset \mathbb{R}^n$  is a bounded domain and  $\alpha$  a positive constant. The authors showed that the energy decays polynomially, with the rate being optimal, and provided numerical validation in the one-dimensional case. Similar results on stability and decay rates had earlier been obtained for systems with boundary damping, notably by Komornik et al. [16] and Aassila [1, 2],

where exponential stability was achieved in the case of linear damping and polynomial stability in the case of nonlinear damping mechanisms.

Motivated by the findings in [13], the present work investigates the coupled viscoelastic wave system

$$\begin{aligned} u_{tt} - \Delta u + \int_0^t g(t-s)\Delta u \, ds + \alpha v &= 0, & \text{in } \Omega \times (0, T), \\ v_{tt} - \Delta v + \alpha u &= 0, & \text{in } \Omega \times (0, T), \\ u = v = 0, & & \text{on } \partial\Omega \times (0, T), \\ u(0) = u_0, u_t(0) = u_1, v(0) = v_0, v_t(0) = v_1, & & \text{in } \Omega, \end{aligned} \tag{1.1}$$

where  $\Omega$  is a bounded domain in  $\mathbb{R}^N$ ,  $\alpha > 0$ , and the initial data belong to suitable spaces. The relaxation function  $g$  satisfies  $g'(t) \leq -\xi(t)G(g(t))$ , where  $G$  is an increasing and convex function near the origin and  $\xi$  is a nonincreasing function. We establish, in details, an existence and uniqueness result, then we prove a general and explicit result for energy decay and provide some numerical illustration to validate our theoretical findings.

The structure of this paper is as follows: the next section presents some assumptions, remarks and functionals needed in our results. In Section 3, we establish the existence of solutions by combining energy estimates with the Faedo-Galerkin method. Section 4 presents several technical lemmas and contains the statement and proof of the decay results. In section 5, two numerical tests are conducted aiming to verify our decay result.

## 2. PRELIMINARIES

This section presents the foundation for our main result. We set

$$\begin{aligned} (h \star \varphi)(t) &= \int_0^t h(t-s)\varphi(s) \, ds, & (h \diamond \varphi)(t) &= \int_0^t h(t-s)\|\varphi(t) - \varphi(s)\| \, ds, \\ (h \circ \varphi)(t) &= \int_0^t h(t-s) \int_{\Omega} \|\varphi(t) - \varphi(s)\|^2 \, dx \, ds. \end{aligned}$$

For the relaxation function  $g$ , we assume:

(A1)  $g : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is a  $C^1$  function satisfying

$$g(0) > 0, \quad 1 - \int_0^\infty g(s) \, ds = l > 0.$$

(A2) There exists a  $C^1$  function  $G : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  which is linear or it is strictly increasing and strictly convex  $C^2$  function on  $(0, r]$ ,  $r \leq g(0)$ , with  $G(0) = G'(0) = 0$ , such that

$$g'(t) \leq -\xi(t)G(g(t)), \quad \forall t \geq 0, \tag{2.1}$$

where  $\xi$  is a positive non-increasing differentiable function.

(A3) The constant  $\alpha$  is such that

$$0 < \alpha < \frac{\sqrt{l}}{C_p}, \tag{2.2}$$

where  $C_p$  is the Poincaré constant.

**Lemma 2.1** ([30]). *For any function  $h \in C^1(\mathbb{R})$  and any  $k \in H^1(0, T)$ , we have*

$$(h \star k)(t)k_t = -\frac{1}{2}h(t)\|k\|^2 + \frac{1}{2}(h' \circ k)(t) - \frac{1}{2} \frac{d}{dt} \left\{ (h \circ k)(t) - \left( \int_0^t h(\tau) \, d\tau \right) \|k\|^2 \right\}.$$

**Lemma 2.2** ([20]). *For  $u \in H_0^1(\Omega)$ , we have*

$$\int_{\Omega} \left( \int_0^t g(t-s)(u(t) - u(s)) \, ds \right)^2 \, dx \leq (1-l)C_p^2(g \circ \nabla u)(t), \tag{2.3}$$

where  $l$  is given in (A1).

## 3. EXISTENCE OF WEAK SOLUTIONS

Now, we examine the well-posedness of problem (1.1). To establish this, we will combine some energy estimates and the Faedo-Galerkin method.

**Theorem 3.1.** *Assume that (A1)–(A3) hold. Then, for each  $(u_0, v_0) \in (H^2(\Omega) \cap H_0^1(\Omega))^2$  and  $(u_1, v_1) \in (H_0^1(\Omega))^2$ , problem (1.1) has a unique strong solution  $(u, v)$  satisfying, for every  $T > 0$ ,*

$$\begin{aligned} u, v &\in L^\infty([0, T], H^2(\Omega) \cap H_0^1(\Omega)), \\ u_t, v_t &\in L^2((0, T), H_0^1(\Omega)) \cap H_0^1((0, T) \times \Omega), \\ u_{tt}, v_{tt} &\in L^\infty((0, T), L^2(\Omega)). \end{aligned}$$

*Proof.*

**Step 1.** Faedo-Galerkin approximation. We take  $\{\phi_j\}_{j=1}^\infty$  to be the eigenfunctions of the Laplacian operator subject to Dirichlet boundary conditions, satisfying  $-\Delta\phi_i = \lambda_i\phi_i$ . Then  $\{\phi_j\}_{j=1}^\infty$  forms an orthogonal basis of  $H_0^1(\Omega)$ ,  $H^2(\Omega) \cap H_0^1(\Omega)$ , and  $L^2(\Omega)$ . Let  $V_N$  be spanned by the  $N$  first functions  $\phi_1, \phi_2, \dots, \phi_N$ . We seek an approximate solution  $(u, v)$  of the form

$$u^N(x, t) = \sum_{j=1}^N a_j(t)\phi_j(x), \quad v^N(x, t) = \sum_{j=1}^N b_j(t)\phi_j(x), \quad t \in (0, T),$$

which satisfies

$$\begin{aligned} \int_{\Omega} u_{tt}^N \phi_j dx + \int_{\Omega} \nabla u^N \cdot \nabla \phi_j dx - \int_{\Omega} \int_0^t g(t-s) \nabla u^N(s) \cdot \nabla \phi_j ds dx + \alpha \int_{\Omega} v^N \phi_j dx &= 0, \\ \int_{\Omega} v_{tt}^N \phi_j dx + \int_{\Omega} \nabla v^N \cdot \nabla \phi_j dx + \alpha \int_{\Omega} u^N \phi_j dx &= 0, \quad 1 \leq j \leq N \end{aligned}$$

and

$$\begin{aligned} u^N(0) &= u_0^N = \sum_{i=1}^N \langle u_0, \phi_i \rangle \phi_i \rightarrow u_0, \\ v^N(0) &= v_0^N = \sum_{i=1}^N \langle v_0, \phi_i \rangle \phi_i \rightarrow v_0 \quad \text{in } H^2(\Omega) \cap H_0^1(\Omega), \\ u_t^N(0) &= u_1^N = \sum_{i=1}^N \langle u_1, \phi_i \rangle \phi_i \rightarrow u_1, \\ v_t^N(0) &= v_1^N = \sum_{i=1}^N \langle v_1, \phi_i \rangle \phi_i \rightarrow v_1 \quad \text{in } H_0^1(\Omega). \end{aligned} \tag{3.1}$$

Standard results of ordinary differential equations guarantee the existence of a unique local solution  $(u^N, v^N)$  of (3)-(3.1) defined on  $[0, t_N)$ ,  $0 < t_N \leq T$ . Our next step is to obtain a priori estimates that enable us to extend the solution to the entire interval.

**Step 2.** A priori estimate 1. By multiplying the first equation in (3) by  $a_j'(t)$  and summing the results over  $j$  from 1 to  $N$ , we obtain, for all  $0 < t \leq t_N$ ,

$$\frac{d}{dt} \left( \frac{1}{2} \|u_t^N(t)\|^2 + \frac{1}{2} \|\nabla u^N(t)\|^2 \right) + \alpha \int_{\Omega} v^N(t) u_t^N(t) dx - \int_0^t g(t-s) \int_{\Omega} \nabla u^N(s) \nabla u_t^N(t) dx ds = 0. \tag{3.2}$$

Using Lemma 2.1 for the last term of the left-hand side of (3.2) we find that

$$\begin{aligned} \frac{d}{2dt} \left( \|u_t^N(t)\|^2 + \left[ 1 - \int_0^t g(s) ds \right] \|\nabla u^N(t)\|^2 + (g \circ \nabla u^N)(t) \right) + \alpha \int_{\Omega} v^N(t) u_t^N(t) dx \\ + \frac{1}{2} g(t) \|\nabla u^N(t)\|^2 - \frac{1}{2} (g' \circ \nabla u^N)(t) = 0. \end{aligned} \tag{3.3}$$

Multiplying the second equation in (3) by  $b'_j(t)$  and summing with respect to  $j$ , we obtain

$$\frac{d}{2dt} \left( \|v_t^N(t)\|^2 + \|\nabla v^N(t)\|^2 \right) + \alpha \int_{\Omega} u^N(t) v_t^N(t) dx = 0, \quad 0 < t \leq t_N. \quad (3.4)$$

Then, combining (3.3) and (3.4) yields

$$\begin{aligned} & \frac{d}{2dt} \left( \|u_t^N(t)\|^2 + \left[ 1 - \int_0^t g(s) ds \right] \|\nabla u^N(t)\|^2 + (g \circ \nabla u^N)(t) + \|v_t^N(t)\|^2 + \|\nabla v^N(t)\|^2 \right. \\ & \left. + 2\alpha \int_{\Omega} v^N(t) u^N(t) dx \right) \\ & = -\frac{1}{2} g(t) \|\nabla u^N(t)\|^2 + \frac{1}{2} (g' \circ \nabla u^N)(t). \end{aligned} \quad (3.5)$$

By assumptions (A1)–(A3) we obtain

$$\begin{aligned} & \frac{d}{2dt} \left( \|u_t^N(t)\|^2 + \left[ 1 - \int_0^t g(s) ds \right] \|\nabla u^N(t)\|^2 + (g \circ \nabla u^N)(t) + \|v_t^N(t)\|^2 + \|\nabla v^N(t)\|^2 \right. \\ & \left. + 2\alpha \int_{\Omega} v^N(t) u^N(t) dx \right) \leq 0. \end{aligned} \quad (3.6)$$

Integrating (3.6) over  $(0, t)$  yields

$$E_N(t) \leq E_N(0), \quad (3.7)$$

where

$$\begin{aligned} E_N(t) &= \|u_t^N(t)\|^2 + \left[ 1 - \int_0^t g(s) ds \right] \|\nabla u^N(t)\|^2 + (g \circ \nabla u^N)(t) + \|v_t^N(t)\|^2 + \|\nabla v^N(t)\|^2 \\ & \quad + 2\alpha \int_{\Omega} v^N(t) u^N(t) dx, \\ E_N(0) &= \|u_1^N\|^2 + \|v_1^N\|^2 + \|\nabla u_0^N\|^2 + \|\nabla v_0^N\|^2 + 2\alpha \int_{\Omega} v_0^N u_0^N dx. \end{aligned}$$

Using Young's and Poincaré's inequalities, for  $\varepsilon_1 > 0$ , we have

$$2 \int_{\Omega} v^N(t) u^N(t) dx \geq -\varepsilon_1 C_p \|\nabla u^N(t)\|^2 - \frac{C_p}{\varepsilon_1} \|\nabla v^N(t)\|^2 \quad (3.8)$$

and

$$2\alpha \int_{\Omega} v_0^N u_0^N dx \leq \alpha C_p \|\nabla u_0^N\|^2 + \alpha C_p \|\nabla v_0^N\|^2. \quad (3.9)$$

Thus

$$E_N(0) \leq \|u_1^N\|^2 + \|v_1^N\|^2 + (1 + \alpha C_p) \|\nabla u_0^N\|^2 + (1 + \alpha C_p) \|\nabla v_0^N\|^2. \quad (3.10)$$

Since the sequences  $(u_0^N)_{N \in \mathbb{N}}$ ,  $(u_1^N)_{N \in \mathbb{N}}$ ,  $(v_0^N)_{N \in \mathbb{N}}$ ,  $(v_1^N)_{N \in \mathbb{N}}$  converge, there exists a positive constant  $L_1$ , independent of  $N$ , such that

$$E_N(0) \leq L_1. \quad (3.11)$$

On the other hand,

$$\begin{aligned} E_N(t) &\geq \|u_t^N(t)\|^2 + \left[ 1 - \int_0^t g(s) ds - \alpha \varepsilon_1 C_p \right] \|\nabla u^N(t)\|^2 + (g \circ \nabla u^N)(t) + \|v_t^N(t)\|^2 \\ & \quad + \left( 1 - \frac{\alpha C_p}{\varepsilon_1} \right) \|\nabla v^N(t)\|^2. \end{aligned} \quad (3.12)$$

Let us select  $\varepsilon_1$  such that it satisfies  $\alpha C_p \leq \varepsilon_1 \leq \frac{1}{\alpha C_p}$ . Then, there exists  $C > 0$ , such that

$$E_N(t) \geq C \left( \|u_t^N(t)\|^2 + \|\nabla u^N(t)\|^2 + (g \circ \nabla u^N)(t) + \|v_t^N(t)\|^2 + \|\nabla v^N(t)\|^2 \right). \quad (3.13)$$

From (3.7) and (3.11), we deduce

$$\|u_t^N(t)\|^2 + \|v_t^N(t)\|^2 + \|\nabla u^N(t)\|^2 + \|\nabla v^N(t)\|^2 + (g \circ \nabla u^N)(t) \leq \frac{L_1}{C}, \quad \forall t \leq t_N \leq T, \quad (3.14)$$

where  $\frac{L_1}{C}$  is a constant independent of  $t$  and  $N$ .

**A priori estimate 2.** In (3), we substitute  $\phi_j$  by  $-\Delta\phi_j$  then multiply the equation (3)<sub>1</sub> by  $a'_j(t)$  and the second equation (3)<sub>2</sub> by  $b'_j(t)$ , sum the resulting equations, and use (A1)–(A3), we arrive at

$$\begin{aligned} & \frac{d}{2dt} \left[ \|\nabla u_t^N(t)\|^2 + \left(1 - \int_0^t g(s) ds\right) \|\Delta u^N(t)\|^2 + (g \circ \Delta u^N)(t) + \|\nabla v_t^N(t)\|^2 + \|\Delta v^N(t)\|^2 \right. \\ & \left. + 2\alpha \int_{\Omega} \nabla v^N(t) \nabla u^N(t) dx \right] - \frac{1}{2} (g' \circ \Delta u^N)(t) + \frac{1}{2} g(t) \|\Delta u^N(t)\|^2 \leq 0. \end{aligned}$$

Applying Young's and Poincaré's inequalities, we have for  $\varepsilon_3 > 0$ ,

$$2 \int_{\Omega} \nabla v^N(t) \nabla u^N(t) dx \geq -\varepsilon_3 C_p \|\Delta u^N(t)\|^2 - \frac{C_p}{\varepsilon_3} \|\Delta v^N(t)\|^2,$$

and

$$2 \int_{\Omega} \nabla v_0^N \nabla u_0^N dx \leq C_p \|\Delta u_0^N\|^2 + C_p \|\Delta v_0^N\|^2.$$

Then

$$\begin{aligned} & \|\nabla u_1^N\|^2 + \|\nabla v_1^N\|^2 + \|\Delta u_0^N\|^2 + \|\Delta v_0^N\|^2 + 2\alpha \int_{\Omega} \nabla v_0^N \nabla u_0^N dx \\ & \leq \|\nabla u_1^N\|^2 + \|\nabla v_1^N\|^2 + (1 + \alpha C_p) \|\Delta u_0^N\|^2 + (1 + \alpha C_p) \|\Delta v_0^N\|^2. \end{aligned} \quad (3.15)$$

Since the sequences  $(u_0^N)_{N \in \mathbb{N}}$ ,  $(u_1^N)_{N \in \mathbb{N}}$ ,  $(v_0^N)_{N \in \mathbb{N}}$ ,  $(v_1^N)_{N \in \mathbb{N}}$  converge, there exists a positive constant  $L_2$ , independent of  $N$ , such that

$$\|\nabla u_1^N\|^2 + \|\nabla v_1^N\|^2 + \|\Delta u_0^N\|^2 + \|\Delta v_0^N\|^2 + 2\alpha \int_{\Omega} \nabla v_0^N \nabla u_0^N dx \leq L_2. \quad (3.16)$$

Furthermore,

$$\begin{aligned} & \|\nabla u_t^N(t)\|^2 + \left(1 - \int_0^t g(s) ds\right) \|\Delta u^N(t)\|^2 + (g \circ \Delta u^N)(t) + \|\nabla v_t^N(t)\|^2 + \|\Delta v^N(t)\|^2 \\ & + 2\alpha \int_{\Omega} \nabla v^N(t) \nabla u^N(t) dx \\ & \geq \|\nabla u_t^N(t)\|^2 + \left(1 - \int_0^t g(s) ds - \varepsilon_3 C_p\right) \|\Delta u^N(t)\|^2 \\ & + (g \circ \Delta u^N)(t) + \|\nabla v_t^N(t)\|^2 + \left(1 - \frac{\alpha C_p}{\varepsilon_3}\right) \|\Delta v^N(t)\|^2. \end{aligned}$$

We choose  $\varepsilon_3$  such that it satisfies  $\alpha C_p \leq \varepsilon_3 \leq \frac{1}{\alpha C_p}$ . Then there exists  $C > 0$ , such that

$$\begin{aligned} & \|\nabla u_t^N(t)\|^2 + \left(1 - \int_0^t g(s) ds\right) \|\Delta u^N(t)\|^2 + (g \circ \Delta u^N)(t) + \|\nabla v_t^N(t)\|^2 + \|\Delta v^N(t)\|^2 \\ & + 2\alpha \int_{\Omega} \nabla v^N(t) \nabla u^N(t) dx \\ & \geq C \left( \|\nabla u_t^N(t)\|^2 + \|\Delta u^N(t)\|^2 + (g \circ \Delta u^N)(t) + \|\nabla v_t^N(t)\|^2 + \|\Delta v^N(t)\|^2 \right). \end{aligned} \quad (3.17)$$

From (3.15), (3.16) and (3.17), it follows that

$$\|\nabla u_t^N(t)\|^2 + \|\Delta u^N(t)\|^2 + (g \circ \Delta u^N)(t) + \|\nabla v_t^N(t)\|^2 + \|\Delta v^N(t)\|^2 \leq \frac{L_2}{C}, \quad \forall t \leq t_N \leq T, \quad (3.18)$$

where  $\frac{L_2}{C}$  is a constant independent of  $t$  and  $N$ .

**A priori estimate 3.** By multiplying the first equation in (3)<sub>1</sub> by  $a''_j(t)$  and summing the results over  $j$  from 1 to  $k$ , we obtain

$$\begin{aligned} & \int_{\Omega} |u''_{tt}(t)|^2 dx \\ & = \int_{\Omega} \Delta u^N(t) u''_{tt}(t) dx - \int_{\Omega} \int_0^t g(t-s) \Delta u^N(s) u''_{tt}(t) ds dx - \alpha \int_{\Omega} v^N(t) u''_{tt}(t) dx \end{aligned}$$

$$\begin{aligned}
 &= \int_{\Omega} \Delta u^N(t) u_{tt}^N(t) dx + \int_{\Omega} u_{tt}^N(t) \int_0^t g(t-s) (\Delta u^N(t) - \Delta u^N(s)) ds dx \\
 &\quad - \int_0^t g(s) ds \int_{\Omega} u_{tt}^N(t) \Delta u^N(t) dx - \alpha \int_{\Omega} v^N(t) u_{tt}^N(t) dx \\
 &\leq \varepsilon \int_{\Omega} |u_{tt}^N(t)|^2 dx + \frac{1}{4\varepsilon} \int_{\Omega} |\Delta u^N(t)|^2 dx + \varepsilon \int_{\Omega} |u_{tt}^N(t)|^2 dx + \frac{1-l}{4\varepsilon} (g \circ \Delta u^N)(t) \\
 &\quad + \varepsilon(1-l) \int_{\Omega} |u_{tt}^N(t)|^2 dx + \frac{1-l}{4\varepsilon} \int_{\Omega} |\Delta u^N(t)|^2 dx + \varepsilon \int_{\Omega} |u_{tt}^N(t)|^2 dx + \frac{\alpha^2}{4\varepsilon} \int_{\Omega} |v^N(t)|^2 dx \\
 &\leq \varepsilon(4-l) \int_{\Omega} |u_{tt}^N(t)|^2 dx + \frac{2-l}{4\varepsilon} \int_{\Omega} |\Delta u^N(t)|^2 dx + \frac{1-l}{4\varepsilon} (g \circ \Delta u^N)(t) + \frac{\alpha^2}{4\varepsilon} \int_{\Omega} |v^N(t)|^2 dx.
 \end{aligned}$$

Hence, for some  $c > 0$ , we have

$$(1 - \varepsilon(4 - l)) \int_{\Omega} |u_{tt}^N(t)|^2 dx \leq \frac{c}{4\varepsilon} (L_1 + L_2). \tag{3.19}$$

We take  $\varepsilon > 0$  small enough, so

$$\|u_{tt}^N(t)\|^2 \leq \tilde{c}(L_1 + L_2) = L_3. \tag{3.20}$$

Similarly, we obtain  $\|v_{tt}^N(t)\|^2 \leq L_4$ , where  $L_3, L_4$  are constants independent of  $t$  and  $N$ .

From (3.14), (3.18) and (3.20), we conclude that

$$\begin{aligned}
 &(u^N)_N \text{ and } (v^N)_N \text{ are bounded in } L^\infty((0, T), H^2(\Omega) \cap H_0^1(\Omega)), \\
 &(u_t^N)_N \text{ and } (v_t^N)_N \text{ are bounded in } L^\infty((0, T), H_0^1(\Omega)), \\
 &(u_{tt}^N)_N \text{ and } (v_{tt}^N)_N \text{ are bounded in } L^\infty((0, T), L^2(\Omega)).
 \end{aligned} \tag{3.21}$$

**Step 3.** From (3.21), there exist subsequences of  $(u^N)_N$  and  $(v^N)_N$  (still denoted by  $(u^N)_N$  and  $(v^N)_N$ ), and two functions  $u, v : \Omega \times [0, T] \rightarrow \mathbb{R}$ , such that

$$\begin{aligned}
 &u^N \overset{*}{\rightharpoonup} u \text{ and } v^N \overset{*}{\rightharpoonup} v \text{ in } L^\infty((0, T), H^2(\Omega) \cap H_0^1(\Omega)), \\
 &u_t^N \overset{*}{\rightharpoonup} u_t \text{ and } v_t^N \overset{*}{\rightharpoonup} v_t \text{ in } L^\infty((0, T), H_0^1(\Omega)), \\
 &u_{tt}^N \overset{*}{\rightharpoonup} u_{tt} \text{ and } v_{tt}^N \overset{*}{\rightharpoonup} v_{tt} \text{ in } L^\infty((0, T), L^2(\Omega)).
 \end{aligned} \tag{3.22}$$

Thanks to convergences (3.1) and (3.22), taking  $N \rightarrow +\infty$  in (3), we obtain

$$\begin{aligned}
 &\int_{\Omega} u_{tt} \phi_j dx + \int_{\Omega} \nabla u \cdot \nabla \phi_j dx - \int_{\Omega} \int_0^t g(t-s) \nabla u(s) \cdot \nabla \phi_j ds dx + \alpha \int_{\Omega} v \phi_j dx = 0, \\
 &\int_{\Omega} v_{tt} \phi_j dx + \int_{\Omega} \nabla v \cdot \nabla \phi_j dx + \alpha \int_{\Omega} u \phi_j dx = 0, \quad 1 \leq j \leq N.
 \end{aligned} \tag{3.23}$$

Consequently, for every  $\phi \in H_0^1(\Omega) \cap H^2(\Omega)$ ,

$$\begin{aligned}
 &\int_{\Omega} \left[ u_{tt} - \Delta u + \int_0^t g(t-s) \Delta u(s) ds + \alpha v \right] \phi dx = 0, \\
 &\int_{\Omega} [v_{tt} - \Delta v + \alpha u] \phi dx = 0.
 \end{aligned}$$

Therefore,  $(u, v)$  solves the equations in (1.1).

**Step 4. Initial conditions.** First, by Lions' lemma [18] and since

$$\begin{aligned}
 &u^N \overset{*}{\rightharpoonup} u \text{ in } L^\infty((0, T), H^2(\Omega) \cap H_0^1(\Omega)), \\
 &u_t^N \overset{*}{\rightharpoonup} u_t \text{ in } L^\infty((0, T), H_0^1(\Omega)),
 \end{aligned}$$

we deduce, up to a subsequence, that

$$u^N \rightarrow u \text{ in } C([0, T], H_0^1(\Omega)). \tag{3.24}$$

Therefore,  $u^N(\cdot, 0)$  is defined and

$$u^N(\cdot, 0) \rightarrow u(\cdot, 0) \text{ in } H_0^1(\Omega).$$

But,

$$u^N(\cdot, 0) = u_0^N \rightarrow u_0 \text{ in } H^2(\Omega) \cap H_0^1(\Omega).$$

Then  $u(\cdot, 0) = u_0$ . Similarly, we obtain  $v(\cdot, 0) = v_0$ .

Noting that

$$u_{tt}^N \xrightarrow{*} u_{tt} \quad \text{and} \quad v_{tt}^N \xrightarrow{*} v_{tt} \quad \text{in } L^\infty((0, T), L^2(\Omega)),$$

we obtain  $u_t, v_t \in C([0, T], L^2(\Omega))$ , as in Lions [18], and thus  $u_t(\cdot, 0)$  has a meaning. Furthermore

$$u_t^N(\cdot, 0) \rightarrow u_t(\cdot, 0) \quad \text{and} \quad v_t^N(\cdot, 0) \rightarrow v_t(\cdot, 0) \quad \text{in } L^2(\Omega).$$

But,

$$u_t^N(\cdot, 0) = u_1^N \rightarrow u_1 \quad \text{and} \quad v_t^N(\cdot, 0) = v_1^N \rightarrow v_1 \quad \text{in } H_0^1(\Omega).$$

Hence,  $u_t(x, 0) = u_1(x)$  and  $v_t(x, 0) = v_1(x)$ .

**Uniqueness.** Assume that problem (1.1) has two weak solutions,  $(u, v)$  and  $(\bar{u}, \bar{v})$ . Then,  $(\mathbf{u}, \mathbf{v}) = (u - \bar{u}, v - \bar{v})$  satisfies

$$\mathbf{u}_{tt} - \Delta \mathbf{u} + \int_0^t g(t-s) \Delta \mathbf{u} ds + \alpha \mathbf{v} = 0, \quad \text{in } \Omega \times (0, T), \quad (3.25)$$

$$\mathbf{v}_{tt} - \Delta \mathbf{v} + \alpha \mathbf{u} = 0, \quad \text{in } \Omega \times (0, T), \quad (3.26)$$

$$\mathbf{u}(x, t) = \mathbf{v}(x, t) = 0, \quad \text{on } \partial\Omega \times (0, T), \quad (3.27)$$

$$\mathbf{u}(x, 0) = \mathbf{u}_t(x, 0) = 0, \quad \mathbf{v}(x, 0) = \mathbf{v}_t(x, 0) = 0, \quad \text{in } \Omega. \quad (3.28)$$

Multiplying (3.25) by  $\mathbf{u}_t$  and (3.26) by  $\mathbf{v}_t$ , integrating over  $\Omega$ , and adding the two resulting equations, we find

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \left( \|\mathbf{u}_t(t)\|^2 + \left[ 1 - \int_0^t g(s) ds \right] \|\nabla \mathbf{u}(t)\|^2 + (g \circ \nabla \mathbf{u})(t) \right) \\ & + 2\alpha \int_{\Omega} \mathbf{v} \cdot \mathbf{u} dx + \|\mathbf{v}_t(t)\|^2 + \|\nabla \mathbf{v}(t)\|^2 \\ & = -\frac{1}{2} g(t) \|\nabla \mathbf{u}(t)\|^2 + \frac{1}{2} (g' \circ \nabla \mathbf{u})(t). \end{aligned} \quad (3.29)$$

Using assumptions (A1)–(A3), and integrating over  $(0, t)$ ,  $t \leq T$ , we obtain

$$\|\mathbf{u}_t(t)\|^2 + \left[ 1 - \int_0^t g(s) ds \right] \|\nabla \mathbf{u}(t)\|^2 + (g \circ \nabla \mathbf{u})(t) + 2\alpha \int_{\Omega} \mathbf{v} \cdot \mathbf{u} dx + \|\mathbf{v}_t(t)\|^2 + \|\nabla \mathbf{v}(t)\|^2 \leq 0.$$

From Young and Poincaré's inequalities, we obtain

$$\begin{aligned} & \|\mathbf{u}_t(t)\|^2 + \left[ 1 - \int_0^t g(s) ds - \alpha \varepsilon_1 C_p \right] \|\nabla \mathbf{u}(t)\|^2 + (g \circ \nabla \mathbf{u})(t) \\ & + \|\mathbf{v}_t(t)\|^2 + \left( 1 - \frac{\alpha C_p}{\varepsilon_1} \right) \|\nabla \mathbf{v}(t)\|^2 \leq 0. \end{aligned}$$

We select  $\varepsilon_1$  such that it satisfies  $\alpha C_p \leq \varepsilon_1 \leq \frac{1}{\alpha C_p}$ . Then

$$\|\mathbf{u}_t\|^2 + \|\nabla \mathbf{u}\|^2 + (g \circ \nabla \mathbf{u})(t) + \|\mathbf{v}_t\|^2 + \|\nabla \mathbf{v}\|^2 = 0.$$

Hence,  $\mathbf{u}_t(\cdot, t) = \mathbf{v}_t(\cdot, t) = 0$  and  $\nabla \mathbf{u}(\cdot, t) = \nabla \mathbf{v}(\cdot, t) = 0$ , for all  $t \in (0, T)$ . This implies that  $\mathbf{u} = \mathbf{v} = 0$  on  $\Omega \times (0, T)$ , given that  $\mathbf{u} = \mathbf{v} = 0$  on  $\partial\Omega \times (0, T)$ . This establishes the uniqueness.  $\square$

#### 4. ASYMPTOTIC BEHAVIOR

Now, we introduce the first and the second order energy functionals corresponding to system (1.1),

$$\begin{aligned} E(t) &= \frac{1}{2} \|u_t(t)\|^2 + \frac{1}{2} \|v_t(t)\|^2 + \frac{1}{2} \left( 1 - \int_0^t g(s) ds \right) \|\nabla u(t)\|^2 + \frac{1}{2} \|\nabla v(t)\|^2 \\ &+ \frac{1}{2} (g \circ \nabla u)(t) + \alpha \int_{\Omega} uv dx \end{aligned} \quad (4.1)$$

and

$$\begin{aligned} e(t) &= \frac{1}{2} \|\nabla u_t(t)\|^2 + \frac{1}{2} \|\nabla v_t(t)\|^2 + \frac{1}{2} \|\Delta v(t)\|^2 + \frac{1}{2} \left(1 - \int_0^t g(s) ds\right) \|\Delta u(t)\|^2 \\ &\quad + \frac{1}{2} (g \circ \Delta u)(t) + \alpha \int_{\Omega} \nabla v \nabla u dx. \end{aligned} \quad (4.2)$$

**Lemma 4.1.** *Under the conditions of Theorem 3, there exists a constant  $m > 0$  such that, for all  $t \geq 0$ ,*

$$E(t) \geq m (\|u_t(t)\|^2 + \|v_t(t)\|^2 + \|\nabla u(t)\|^2 + \|\nabla v(t)\|^2 + (g \circ \nabla u)(t)), \quad (4.3)$$

$$e(t) \geq m (\|\nabla u_t(t)\|^2 + \|\nabla v_t(t)\|^2 + \|\Delta v(t)\|^2 + \|\Delta u(t)\|^2 + (g \circ \Delta u)(t)). \quad (4.4)$$

*Proof.* Applying Cauchy-Schwarz and Young's inequalities, for  $\varepsilon_1 > 0$ , we obtain

$$E(t) \geq \frac{1}{2} \left( \|u_t(t)\|^2 + \|v_t(t)\|^2 + [l - \alpha \varepsilon_1 C_p] \|\nabla u(t)\|^2 + \left(1 - \frac{\alpha C_p}{\varepsilon_1}\right) \|\nabla v(t)\|^2 + (g \circ \nabla u)(t) \right),$$

for all  $t \geq 0$ . Keeping in mind (2.2), we can select  $\varepsilon_1$  such that  $\alpha C_p \leq \varepsilon_1 \leq \frac{l}{\alpha C_p}$ . Consequently, we derive (4.3) with  $m = \frac{1}{2} \min\{l - \alpha \varepsilon_1 C_p, 1 - \frac{\alpha C_p}{\varepsilon_1}\}$ . Using similar reasoning, (4.4) can also be established with the same constant.  $\square$

**Lemma 4.2.** *Under the conditions of Theorem 3.1, the energy functional satisfies*

$$E'(t) = \frac{1}{2} (g' \circ \nabla u)(t) - \frac{1}{2} g(t) \|\nabla u(t)\|^2 \leq 0, \quad (4.5)$$

$$e'(t) = \frac{1}{2} (g' \circ \Delta u)(t) - \frac{1}{2} g(t) \|\Delta u(t)\|^2 \leq 0. \quad (4.6)$$

*Proof.* To obtain (4.5), we multiply the first equation of system (1.1) by  $u_t$ , the second one by  $v_t$ , we integrate each one over  $\Omega$ , utilizing the boundary conditions, it follows that

$$\begin{aligned} &\frac{d}{dt} \left( \frac{1}{2} \|u_t(t)\|^2 + \frac{1}{2} \|v_t(t)\|^2 + \frac{1}{2} \|\nabla u(t)\|^2 + \frac{1}{2} \|\nabla v(t)\|^2 + \alpha \int_{\Omega} u v \right) dx \\ &\quad - \int_0^t g(t-s) \int_{\Omega} \nabla u(s) \nabla u_t dx ds = 0. \end{aligned}$$

Applying Lemma 2.1, we arrive at

$$\begin{aligned} &\frac{d}{2dt} \left( \|u_t(t)\|^2 + \|v_t(t)\|^2 + \left[1 - \int_0^t g(s) ds\right] \|\nabla u(t)\|^2 + \frac{1}{2} \|\nabla v(t)\|^2 + (g \circ \nabla u)(t) + \alpha \int_{\Omega} v u dx \right) \\ &\quad + \frac{1}{2} g(t) \|\nabla u(t)\|^2 - \frac{1}{2} (g' \circ \nabla u)(t) = 0. \end{aligned}$$

To obtain (4.6), we multiply the equation (1.1)<sub>1</sub> and (1.1)<sub>2</sub> by  $-\Delta u_t$  and  $-\Delta v_t$ , respectively, and sum, to obtain

$$\begin{aligned} &\frac{d}{dt} \left( \frac{1}{2} \|\nabla u_t(t)\|^2 + \frac{1}{2} \|\Delta u(t)\|^2 + \frac{1}{2} \|\nabla v_t(t)\|^2 + \frac{1}{2} \|\Delta v(t)\|^2 + \alpha \int_{\Omega} \nabla v \nabla u \right) dx \\ &\quad - \int_0^t g(t-s) \int_{\Omega} \Delta u(s) \Delta u_t(t) dx ds = 0. \end{aligned}$$

Applying Lemma 1, we arrive at

$$\begin{aligned} &\frac{d}{2dt} \left( \|\nabla u_t(t)\|^2 + \|\nabla v_t(t)\|^2 + \|\Delta v(t)\|^2 + \left[1 - \int_0^t g(s) ds\right] \|\Delta u(t)\|^2 \right. \\ &\quad \left. + (g \circ \Delta u)(t) + 2\alpha \int_{\Omega} \nabla v \nabla u dx \right) - \frac{1}{2} (g' \circ \Delta u)(t) + \frac{1}{2} g(t) \|\Delta u(t)\|^2 = 0. \end{aligned}$$

Then our conclusion follows.  $\square$

Now we construct a Lyapunov functional  $L$  equivalent to  $E + e$ , with which we can show the desired result. Similarly to [15], we define

$$C_\mu = \int_0^\infty \frac{g^2(s)}{\mu g(s) - g'(s)} ds, \quad h(t) = \mu g(t) - g'(t) \quad \text{for } 0 < \mu < 1.$$

**Remark 4.3** ([29]). (1) The well-known Jensen's inequality will be of essential use in establishing our main result. For the sake of completeness, let us present it here. If  $F$  is a convex function on  $[a, b]$ ,  $f : \Omega \rightarrow [a, b]$ , and  $h$  are integrable functions on  $\Omega$  with  $h(x) \geq 0$  and  $\int_\Omega h(x) dx = \kappa > 0$ , then Jensen's inequality states that

$$F\left(\frac{1}{\kappa} \int_\Omega f(x)h(x) dx\right) \leq \frac{1}{\kappa} \int_\Omega F(f(x))h(x) dx.$$

(2) From condition (A1), it follows that  $\lim_{t \rightarrow +\infty} g(t) = 0$ . Thus, there exists  $t_0 \geq 0$  large enough such that

$$g(t_0) = r \quad \text{and} \quad g(t) \leq r, \quad \forall t \geq t_0.$$

Since  $g$  and  $\zeta$  are positive, non-increasing and continuous functions, and  $G$  is a positive and continuous function, we have for all  $t \in [0, t_0]$ ,

$$0 < g(t_0) \leq g(t) \leq g(0), \quad 0 < \zeta(t_0) \leq \zeta(t) \leq \zeta(0).$$

This implies the existence of two positive constants  $a$  and  $b$  such that

$$a \leq \zeta(t)G(g(t)) \leq b.$$

As a result, we have, for all  $t \in [0, t_0]$ ,

$$g'(t) \leq -\zeta(t)G(g(t)) \leq -a,$$

consequently,

$$g'(t) \leq -\frac{a}{g(0)}g(0) \leq -\frac{a}{g(0)}g(t).$$

(3) Given that

$$\frac{\mu g^2(s)}{\mu g(s) - g'(s)} < g(s),$$

and applying the Lebesgue dominated convergence theorem, we easily check that

$$\mu C_\mu = \int_0^\infty \frac{\mu g^2(s)}{\mu g(s) - g'(s)} ds \rightarrow 0 \quad \text{as } \mu \rightarrow 0.$$

(4) If  $G$  is a strictly increasing and strictly convex  $C^2$  function on  $(0, r]$ , with  $G(0) = G'(0) = 0$ , then it has an extension  $\bar{G}$  which is strictly increasing and strictly convex  $C^2$  function on  $(0, \infty)$ . See [29].

**Lemma 4.4.** *Let  $(u, v)$  be the solution of (1.1). Consider the functional*

$$\psi(t) = \int_\Omega uu_t dx + \int_\Omega vv_t dx.$$

Then, for any  $\epsilon > 0$ ,

$$\psi'(t) \leq \|u_t(t)\|^2 + \|v_t(t)\|^2 - (l - \epsilon)\|\nabla u(t)\|^2 - \|\nabla v(t)\|^2 - 2\alpha \int_\Omega u v dx + \frac{C_\mu}{4\epsilon}(h \circ \nabla u)(t). \quad (4.7)$$

*Proof.* Using system (1.1), a direct computation leads to

$$\begin{aligned} \psi'(t) &= \|u_t(t)\|^2 + \|v_t(t)\|^2 - \|\nabla u(t)\|^2 - \|\nabla v(t)\|^2 + \int_\Omega \nabla u(t) \left( \int_0^t g(t-s)\nabla u(s) ds \right) dx \\ &\quad - 2\alpha \int_\Omega u v dx. \end{aligned} \quad (4.8)$$

Using Young's inequality and the fact that  $\int_0^t g(s) ds \leq \int_0^\infty g(s) ds = 1 - l$ , we estimate the fifth term in (4.8) to obtain

$$\begin{aligned} \psi'(t) &\leq \|u_t(t)\|^2 + \|v_t(t)\|^2 - l\|\nabla u(t)\|^2 - \|\nabla v(t)\|^2 + \epsilon\|\nabla u(t)\|^2 \\ &\quad + \frac{1}{4\epsilon} \int_{\Omega} \left( \int_0^t g(t-s)|\nabla u(s) - \nabla u(t)| ds \right)^2 dx - 2\alpha \int_{\Omega} u v dx. \end{aligned} \quad (4.9)$$

Now, the Cauchy-Schwarz inequality gives

$$\begin{aligned} &\int_{\Omega} \left( \int_0^t g(t-s)|\nabla u(s) - \nabla u(t)| ds \right)^2 dx \\ &= \int_{\Omega} \left( \int_0^t \frac{g(t-s)}{\sqrt{\mu g(t-s) - g'(t-s)}} \sqrt{\mu g(t-s) - g'(t-s)} |\nabla u(s) - \nabla u(t)| ds \right)^2 dx \\ &\leq \left( \int_0^t \frac{g^2(s)}{\mu g(s) - g'(s)} ds \right) \int_{\Omega} \left( \int_0^t [\mu g(t-s) - g'(t-s)] |\nabla u(s) - \nabla u(t)|^2 ds \right) dx \\ &\leq C_{\mu}(h \circ \nabla u)(t). \end{aligned} \quad (4.10)$$

By substituting (4.10) into (4.9), we obtain (4.7).  $\square$

**Lemma 4.5.** *Let  $(u, v)$  be the solution of (1.1). Then, the functional*

$$\chi(t) = - \int_{\Omega} u_t \int_0^t g(t-s)(u(t) - u(s)) ds dx,$$

*satisfies, for any  $\delta_1 > 0$ , the estimate*

$$\begin{aligned} \chi'(t) &\leq \left( \delta_1 - \int_0^t g(s) ds \right) \|u_t(t)\|^2 + \delta_1 \|\nabla u(t)\|^2 + \alpha^2 C_p \frac{\delta_1}{2} \|\nabla v(t)\|^2 \\ &\quad + \left( C + C_{\mu} \left( 1 + \frac{C}{\delta_1} \right) \right) (h \circ \nabla u)(t), \end{aligned} \quad (4.11)$$

where  $C = \max\{c_1, c_2\}$ , with  $c_1 = \frac{C_p(\alpha(1-l)+g(0))}{2}$ ,  $c_2 = c + \frac{C_p(1+\mu^2)}{2}$ .

*Proof.* From (1.1) and integration by parts, we obtain

$$\begin{aligned} \chi'(t) &= \left( 1 - \int_0^t g(s) ds \right) \int_{\Omega} \nabla u(t) \int_0^t g(t-s)(\nabla u(t) - \nabla u(s)) ds dx \\ &\quad + \int_{\Omega} \left( \int_0^t g(t-s)(\nabla u(s) - \nabla u(t)) ds \right)^2 dx - \int_{\Omega} u_t \int_0^t g'(t-s)(u(t) - u(s)) ds dx \\ &\quad - \left( \int_0^t g(s) ds \right) \|u_t(t)\|^2 + \alpha \int_{\Omega} v \int_0^t g(t-s)(u(t) - u(s)) ds dx. \end{aligned} \quad (4.12)$$

By Cauchy-Schwarz inequality, the second term of (4.12) satisfies

$$\int_{\Omega} \left( \int_0^t g(t-s)(\nabla u(s) - \nabla u(t)) ds \right)^2 dx \leq C_{\mu}(h \circ \nabla u)(t). \quad (4.13)$$

Similarly, for any  $\delta_1 > 0$ , we have

$$\begin{aligned} &\left( 1 - \int_0^t g(s) ds \right) \int_{\Omega} \nabla u \int_0^t g(t-s)(\nabla u(t) - \nabla u(s)) ds dx \\ &\leq \delta_1 \|\nabla u(t)\|^2 + \frac{(1-g_0)^2 C_{\mu}}{4\delta_1} (h \circ \nabla u)(t) \\ &\leq \delta_1 \|\nabla u(t)\|^2 + \frac{cC_{\mu}}{\delta_1} (h \circ \nabla u)(t), \end{aligned} \quad (4.14)$$

$$\begin{aligned}
& - \int_{\Omega} u_t \int_0^t g'(t-s)(u(t) - u(s)) ds dx \\
& = \int_{\Omega} u_t \int_0^t h(t-s)(u(t) - u(s)) ds dx - \int_{\Omega} u_t \int_0^t \mu g(t-s)(u(t) - u(s)) ds dx \\
& \leq \delta_1 \|u_t(t)\|^2 + \frac{1}{2\delta_1} \int_{\Omega} \left( \int_0^t \sqrt{h(t-s)} \sqrt{h(t-s)} |u(s) - u(t)| ds \right)^2 dx \\
& \quad + \frac{\mu^2}{2\delta_1} \int_{\Omega} \left( \int_0^t g(t-s) |u(s) - u(t)| ds \right)^2 dx \\
& \leq \delta_1 \|u_t(t)\|^2 + \frac{\int_0^t h(s) ds}{2\delta_1} (h \circ u)(t) + \frac{\mu^2 C_{\mu}}{2\delta_1} (h \circ u)(t) \\
& \leq \delta_1 \|u_t(t)\|^2 + \frac{C_p(\alpha(1-l) + g(0))}{2\delta_1} (h \circ \nabla u)(t) + \frac{C_p \mu^2 C_{\mu}}{2\delta_1} (h \circ \nabla u)(t)
\end{aligned} \tag{4.15}$$

and

$$\alpha \int_{\Omega} v \int_0^t g(t-s)(u(t) - u(s)) ds dx \leq \alpha^2 C_p \frac{\delta_1}{2} \|\nabla v(t)\|^2 + C_p \frac{C_{\mu}}{2\delta_1} (h \circ \nabla u)(t). \tag{4.16}$$

Collecting (4.13)–(4.16), we obtain the required estimate.  $\square$

**Lemma 4.6.** *Assume that (A1)–(A3) hold. Then, the functional*

$$I(t) = \int_{\Omega} u_{tt} v_t dx - \int_{\Omega} v_{tt} u_t dx$$

*satisfies along the solution of (1.1) and for any  $\delta_2 > 0$ ,*

$$I'(t) \leq -(\alpha - \delta_2) \|v_t(t)\|^2 + \alpha \|u_t(t)\|^2 + \frac{Cg^2(t)}{\delta_2} \|\Delta u(t)\|^2 - \frac{C}{\delta_2} (g' \circ \Delta u)(t). \tag{4.17}$$

*Proof.* By using equations (1.1) and integrating by parts, we have

$$\begin{aligned}
\frac{d}{dt} \int_{\Omega} u_{tt} v_t dx & = \int_{\Omega} u_{tt} v_{tt} dx - \int_{\Omega} \nabla u_t \nabla v_t dx - \alpha \|v_t(t)\|^2 \\
& \quad + \int_{\Omega} v_t \int_0^t g'(t-s)(\Delta u(t) - \Delta u(s)) ds dx - g(t) \int_{\Omega} \Delta u v_t dx,
\end{aligned}$$

and

$$-\frac{d}{dt} \int_{\Omega} v_{tt} u_t dx = - \int_{\Omega} v_{tt} u_{tt} dx + \int_{\Omega} \nabla u_t \nabla v_t dx + \alpha \|u_t(t)\|^2.$$

Addition of the last two identities leads to

$$I'(t) = \int_{\Omega} v_t \int_0^t g'(t-s)(\Delta u(t) - \Delta u(s)) ds dx - g(t) \int_{\Omega} \Delta u v_t dx - \alpha \|v_t(t)\|^2 + \alpha \|u_t(t)\|^2$$

and Young's inequality yields

$$\begin{aligned}
\int_{\Omega} v_t \int_0^t g'(t-s)(\Delta u(t) - \Delta u(s)) ds dx & \leq \frac{\delta_2}{2} \|v_t(t)\|^2 - \frac{C}{\delta_2} (g' \circ \Delta u)(t), \\
g(t) \int_{\Omega} \Delta u v_t dx & \leq \frac{\delta_2}{2} \|v_t(t)\|^2 + \frac{Cg^2(t)}{\delta_2} \|\Delta u(t)\|^2.
\end{aligned}$$

We finally get the estimate (4.17).  $\square$

**Lemma 4.7** ([29]). *Assume that (A1)–(A3) hold. Then*

$$K(t) = \int_{\Omega} \int_0^t f(t-s) |\nabla u(s)|^2 ds dx,$$

*where  $f(t) = \int_t^{\infty} g(s) ds$ , satisfies along the solution of (1.1), the estimate*

$$K'(t) \leq -\frac{1}{2} (g \circ \nabla u)(t) + 3(1-l) \int_{\Omega} |\nabla u(t)|^2 dx. \tag{4.18}$$

At this stage, we introduce the Lyapunov functional

$$L(t) = \eta(E(t) + e(t)) + \eta_1 \psi(t) + \eta_2 \chi(t) + I(t), \quad (4.19)$$

where  $\eta, \eta_1, \eta_2 > 0$ , are constants to be suitably specified later.

**Proposition 4.8.** *There exist  $\rho_i > 0$ , ( $i = 1, 2$ ) such that*

$$\rho_1(E(t) + e(t)) \leq L(t) \leq \rho_2(E(t) + e(t)), \quad t \geq 0. \quad (4.20)$$

*Proof.* Using Young's and Cauchy-Schwarz inequalities, we see that

$$\begin{aligned} \psi(t) &\leq \frac{1}{2} \int_{\Omega} |u|^2 dx + \frac{1}{2} \int_{\Omega} |u_t|^2 dx + \frac{1}{2} \int_{\Omega} |v|^2 dx + \frac{1}{2} \int_{\Omega} |v_t|^2 dx \\ &\leq \frac{C_p}{2} \|\nabla u(t)\|^2 + \frac{1}{2} \|u_t(t)\|^2 + \frac{C_p}{2} \|\nabla v(t)\|^2 + \frac{1}{2} \|v_t(t)\|^2, \end{aligned}$$

and

$$\begin{aligned} \chi(t) &\leq \frac{1}{2} \int_{\Omega} |u_t|^2 dx + \frac{1}{2} \int_{\Omega} \left( \int_0^t g(t-s) |u(t) - u(s)| ds \right)^2 dx \\ &\leq \frac{1}{2} \|u_t(t)\|^2 + \frac{C_p^2}{2} (1-l) (g \circ \nabla u)(t). \end{aligned}$$

Similarly, using (1.1), we obtain

$$\begin{aligned} I(t) &\leq \frac{1}{2} \|\Delta u(t)\|^2 + \frac{1}{2} \|v_t(t)\|^2 + \int_{\Omega} |v_t| \int_0^t g(t-s) |\Delta u(s) - \Delta u(t)| ds dx + \frac{(1-l)}{2} \|v_t(t)\|^2 \\ &\quad + \frac{(1-l)}{2} \|\Delta u(t)\|^2 + \frac{\alpha}{2} C_p \|\nabla v(t)\|^2 + \frac{\alpha}{2} \|v_t(t)\|^2 + \frac{1}{2} \|\Delta v(t)\|^2 + \frac{1}{2} \|u_t(t)\|^2 \\ &\quad + \frac{\alpha}{2} C_p \|\nabla u(t)\|^2 + \frac{\alpha}{2} \|u_t(t)\|^2 \\ &\leq \left( \frac{1}{2} + \frac{(1-l)}{2} \right) \|\Delta u(t)\|^2 + \left( 1 + \frac{(1-l)}{2} + \frac{\alpha}{2} \right) \|v_t(t)\|^2 + \frac{(1-l)}{2} (g \circ \Delta u)(t) \\ &\quad + \frac{\alpha}{2} C_p \|\nabla v(t)\|^2 + \frac{\alpha}{2} C_p \|\nabla u(t)\|^2 + \frac{1}{2} \|\Delta v(t)\|^2 + \left( \frac{1}{2} + \frac{\alpha}{2} \right) \|u_t(t)\|^2. \end{aligned}$$

Then

$$\begin{aligned} |L(t) - \eta(E(t) + e(t))| &\leq \frac{C_p}{2} (\eta_1 + \alpha) \|\nabla u(t)\|^2 + \left( \frac{\eta_1}{2} + \frac{\eta_2}{2} + \frac{\alpha}{2} + \frac{1}{2} \right) \|u_t(t)\|^2 + \frac{C_p \eta_1}{2} \|\nabla v(t)\|^2 \\ &\quad + \left( \frac{\eta_1}{2} + 1 + \frac{(1-l)}{2} + \frac{\alpha}{2} \right) \|v_t(t)\|^2 + \frac{C_p^2 \eta_2}{2} (1-l) (g \circ \nabla u)(t) \\ &\quad + \left( \frac{1}{2} + \frac{(1-l)}{2} \right) \|\Delta u(t)\|^2 + \frac{1}{2} \|\Delta v(t)\|^2 + \frac{(1-l)}{2} (g \circ \Delta u)(t) \\ &\leq C (\eta_1 + \eta_2) \left( \|\nabla u(t)\|^2 + \|u_t(t)\|^2 + \|\nabla v(t)\|^2 + \|v_t(t)\|^2 + (g \circ \nabla u)(t) \right. \\ &\quad \left. + \|\Delta u(t)\|^2 + \|\Delta v(t)\|^2 + (g \circ \Delta u)(t) \right). \end{aligned}$$

Therefore,

$$|L(t) - \eta(E(t) + e(t))| \leq C (\eta_1 + \eta_2) (E(t) + e(t)),$$

which yields

$$(\eta - C (\eta_1 + \eta_2))(E(t) + e(t)) \leq L(t) \leq (\eta + C (\eta_1 + \eta_2))(E(t) + e(t)).$$

So, by choosing  $\eta > C (\eta_1 + \eta_2)$ , we obtain (4.20).  $\square$

**Lemma 4.9.** *Assume that conditions (A1)–(A3) hold. Then, for any  $M, N > 0$  and for suitable choice of  $\eta, \eta_1, \eta_2 > 0$ , we have*

$$\begin{aligned} L'(t) &\leq -\frac{l\alpha}{8} \|v_t(t)\|^2 - \left( \frac{3\alpha}{2} - \frac{3\alpha l}{N} \right) \|u_t(t)\|^2 - \alpha^2 \int_{\Omega} u v dx - \left( \frac{\alpha}{2} (l - \epsilon) - \frac{3\alpha l}{N} \right) \|\nabla u(t)\|^2 \\ &\quad - \left( \frac{\alpha}{2} - 3C_p \alpha^3 \frac{l}{2N} \right) \|\nabla v(t)\|^2 + \frac{1}{2M} (g \circ \nabla u)(t), \quad \text{for all } t \geq t_0, \end{aligned} \quad (4.21)$$

where  $t_0$  is introduced in remark 4.3.

*Proof.* By combining (4.5), (4.6), (4.7), (4.11) and (4.17), we obtain

$$\begin{aligned} L'(t) \leq & \frac{\eta}{2}(g' \circ \nabla u)(t) - \frac{\eta}{2}g(t)\|\nabla u(t)\|^2 + \frac{\eta}{2}(g' \circ \Delta u)(t) - \frac{\eta}{2}g(t)\|\Delta u(t)\|^2 + \eta_1\|u_t(t)\|^2 + \eta_1\|v_t(t)\|^2 \\ & - \eta_1\|\nabla v(t)\|^2 - \eta_1(l - \epsilon)\|\nabla u(t)\|^2 - 2\alpha\eta_1 \int_{\Omega} uv \, dx + \frac{C_{\mu}\eta_1}{4\epsilon}(h \circ \nabla u)(t) + \eta_2\delta_1\|\nabla u(t)\|^2 \\ & + \eta_2\left(\delta_1 - \int_0^t g(s) \, ds\right)\|u_t(t)\|^2 + \eta_2\alpha^2 C_p \frac{\delta_1}{2}\|\nabla v(t)\|^2 + \eta_2\left(C + C_{\mu}\left(1 + \frac{C}{\delta_1}\right)\right)(h \circ \nabla u)(t) \\ & - (\alpha - \delta_2)\|v_t(t)\|^2 + \alpha\|u_t(t)\|_2^2 + \frac{Cg^2(t)}{\delta_2}\|\Delta u(t)\|_2^2 - \frac{C}{\delta_2}(g' \circ \Delta u)(t). \end{aligned}$$

Letting  $g_0 = \int_0^{t_0} g(s) \, ds$  and recalling that  $g' = (\mu g - h)$ , we obtain

$$\begin{aligned} L'(t) \leq & -(\alpha - \delta_2 - \eta_1)\|v_t(t)\|^2 - (\eta_2(g_0 - \delta_1) - \eta_1 - \alpha)\|u_t(t)\|^2 - 2\alpha\eta_1 \int_{\Omega} u \, v \, dx \\ & - (\eta_1(l - \epsilon) - \eta_2\delta_1)\|\nabla u(t)\|^2 - \left(\eta_1 - \eta_2 C_p \alpha^2 \frac{\delta_1}{2}\right)\|\nabla v(t)\|^2 + \left(\frac{\eta}{2} - \frac{C}{\delta_2}\right)(g' \circ \Delta u)(t) \\ & - g(t)\left(\frac{\eta}{2} - \frac{Cg(t)}{\delta_2}\right)\|\Delta u(t)\|^2 - \left(\frac{\eta}{2} - C\eta_2 - C_{\mu}\left(\frac{\eta_1}{4\epsilon} + \eta_2\left(1 + \frac{C}{\delta_1}\right)\right)\right)(h \circ \nabla u)(t) \\ & - \frac{\eta}{2}g(t)\|\nabla u(t)\|^2 + \frac{\eta}{2}\mu(g \circ \nabla u)(t), \quad \forall t \geq t_0. \end{aligned}$$

Taking  $\delta_2 \leq \frac{\alpha l}{4}$ ,  $\delta_1 = \frac{lg_0}{N}$  ( $N \geq 12$ , to be chosen later) and  $\eta_2 = \frac{3\alpha}{g_0}$ , we find that for all  $t \geq t_0$ ,

$$\begin{aligned} L'(t) \leq & -(\alpha - \delta_2 - \eta_1)\|v_t(t)\|^2 - \left(2\alpha - \frac{3\alpha l}{N} - \eta_1\right)\|u_t(t)\|^2 - 2\alpha\eta_1 \int_{\Omega} u \, v \, dx \\ & - \left(\eta_1(l - \epsilon) - \frac{3\alpha l}{N}\right)\|\nabla u(t)\|^2 - \left(\eta_1 - 3C_p \alpha^3 \frac{l}{2N}\right)\|\nabla v(t)\|^2 + \left(\frac{\eta}{2} - \frac{C}{\delta_2}\right)(g' \circ \Delta u)(t) \\ & - g(t)\left(\frac{\eta}{2} - \frac{Cg(t)}{\delta_2}\right)\|\Delta u(t)\|^2 - \left(\frac{\eta}{2} - C\frac{3\alpha}{g_0} - C_{\mu}\left(\frac{\eta_1}{4\epsilon} + \frac{3\alpha}{g_0}\left(1 + \frac{NC}{lg_0}\right)\right)\right)(h \circ \nabla u)(t) \\ & + \frac{\eta\mu}{2}(g \circ \nabla u)(t) - \frac{\eta}{2}g(t)\|\nabla u(t)\|^2. \end{aligned}$$

For  $0 < \epsilon < \frac{l^2}{2}$ , we choose  $\eta_1$  such that

$$\begin{aligned} (l - \epsilon)\eta_1 - \frac{3\alpha l}{N} &> \frac{l\alpha}{4}(1 - l), \quad \alpha - \delta_2 - \eta_1 > \frac{l\alpha}{8}, \\ 2\alpha - \frac{3\alpha l}{N} - \eta_1 &> \frac{\alpha(1 + l)}{4}, \quad \eta_1 - 3C_p \alpha^3 \frac{l}{2N} > \frac{\alpha}{4}. \end{aligned} \tag{4.22}$$

In particular, we take  $\eta_1 = \frac{\alpha}{2}$  and  $N$  large so that

$$\frac{\alpha}{2} - 3C_p \alpha^3 \frac{l}{2N} > \frac{\alpha}{4},$$

and the inequalities (4.22) are satisfied.

By applying Remark 4.3, there exists  $0 < \mu_0 < 1$ , such that if  $\mu < \mu_0$ , then

$$\mu C_{\mu} < \frac{1}{8\left(\frac{\alpha}{16\epsilon} + \frac{3\alpha}{g_0}\left(1 + \frac{NC}{lg_0}\right)\right)}.$$

Now, we choose  $\eta$  large enough and  $\mu$  so that

$$\frac{\eta}{2} - \frac{C}{\delta_2} > 0, \quad \frac{\eta}{2} - \frac{3\alpha C}{g_0} > 0 \quad \text{and} \quad \mu = \frac{1}{M\eta} < \mu_0,$$

which gives

$$\frac{\eta}{2} - C\frac{3\alpha}{g_0} - C_{\mu}\left(\frac{\alpha}{16\epsilon} + \frac{3\alpha}{g_0}\left(1 + \frac{NC}{lg_0}\right)\right) > 0.$$

Hence,

$$\begin{aligned} L'(t) &\leq -\frac{l\alpha}{8}\|v_t(t)\|^2 - \left(\frac{3\alpha}{2} - \frac{3\alpha l}{N}\right)\|u_t(t)\|^2 - \alpha^2 \int_{\Omega} uv \, dx - \left(\frac{\alpha}{2}(l - \epsilon) - \frac{3\alpha l}{N}\right)\|\nabla u(t)\|^2 \\ &\quad - \left(\frac{\alpha}{2} - 3C_p\alpha^3 \frac{l}{2N}\right)\|\nabla v(t)\|^2 + \frac{1}{2M}(g \circ \nabla u)(t). \end{aligned}$$

We further choose  $\epsilon$  even smaller,  $N$  and  $\eta$  larger, such that (4.20) remains valid, we obtain (4.21).  $\square$

**Theorem 4.10.** *Assume that (A1)–(A3) hold and  $u_0, v_0 \in H^2(\Omega) \cap H_0^1(\Omega)$ ,  $u_1, v_1 \in H_0^1(\Omega)$ . Then, there exist positive constants  $k_0$ ,  $C$  and  $\gamma$  such that the energy functional  $E$  satisfies*

$$E(t) \leq k_0 \frac{(E + e)(t_0)}{\int_{t_0}^t \xi(s) ds}, \quad \forall t \geq t_0, \quad \text{if } G \text{ is linear.} \quad (4.23)$$

$$E(t) \leq CG_2^{-1} \left( \frac{\gamma}{\int_{t_0}^t \xi(s) ds} \right), \quad \forall t > t_0, \quad \text{if } G \text{ is non linear,} \quad (4.24)$$

where  $G_2(\tau) = \tau G'(\tau)$ .

*Proof.* Recalling (4.21), then for some constant  $k > 0$  and for all  $t \geq t_0$ , we obtain

$$\begin{aligned} L'(t) &\leq -\frac{l\alpha}{8}\|v_t(t)\|^2 - \left(\frac{3\alpha}{2} - \frac{3\alpha l}{N}\right)\|u_t(t)\|^2 - \alpha^2 \int_{\Omega} u v \, dx - \left(\frac{\alpha}{2}(l - \epsilon) - \frac{3\alpha l}{N}\right)\|\nabla u(t)\|^2 \\ &\quad - \left(\frac{\alpha}{2} - 3C_p\alpha^3 \frac{l}{2N}\right)\|\nabla v(t)\|^2 + \frac{1}{2M}(g \circ \nabla u)(t) \\ &\leq -kE(t) + c(g \circ \nabla u)(t). \end{aligned} \quad (4.25)$$

**Case (I):  $G(t)$  is linear.** Multiplying (4.25) by  $\xi(t)$  and using (A1) and (4.5), we find

$$\begin{aligned} \xi(t)L'(t) &\leq -k\xi(t)E(t) + c\xi(t) \int_0^t g(s) \int_{\Omega} |\nabla u(t) - \nabla u(t-s)|^2 \, dx \, ds \\ &\leq -k\xi(t)E(t) - cE'(t), \quad \forall t \geq t_0. \end{aligned}$$

As  $\xi$  is non-increasing and  $L \geq 0$ , we reach

$$(\xi(t)L(t))' \leq \xi(t)L'(t) \leq -k\xi(t)E(t) - cE'(t), \quad \forall t \geq t_0;$$

which yields

$$\xi(t)E(t) \leq -\frac{1}{k}(\xi L + cE)'(t), \quad \forall t \geq t_0.$$

Simple integration over  $(t_0, t)$  leads to

$$\begin{aligned} E(t) \int_{t_0}^t \xi(s) ds &\leq \int_{t_0}^t \xi(s)E(s) ds \\ &\leq -\int_{t_0}^t \frac{1}{k}(\xi L + cE)'(s) ds \\ &\leq \frac{1}{k}(\xi L + cE)(t_0), \quad \forall t \geq t_0. \end{aligned}$$

Using  $\xi L + cE \sim E + e$ , estimate (4.23) is established.

**Case (II):  $G(t)$  nonlinear.** As in [27], we use (4.5) and (4.3) to deduce that, for any  $t \geq t_0$ ,

$$\begin{aligned} &\int_0^{t_0} g(s) \int_{\Omega} |\nabla u(t) - \nabla u(t-s)|^2 \, dx \, ds \\ &\leq -\frac{g(0)}{a} \int_0^{t_0} g'(s) \int_{\Omega} |\nabla u(t) - \nabla u(t-s)|^2 \, dx \, ds \\ &\leq -cE'(t), \end{aligned}$$

which can be utilized in (4.25), to obtain, for all  $t \geq t_0$ ,

$$\begin{aligned} L'(t) &\leq -kE(t) + c(g \circ \nabla u)(t) \\ &\leq -kE(t) - cE'(t) + c \int_{t_0}^t g(s) \int_{\Omega} |\nabla u(t) - \nabla u(t-s)|^2 dx ds. \end{aligned}$$

By taking  $F(t) = L(t) + cE(t)$ , which is equivalent to  $E(t) + e(t)$ , we infer that

$$F'(t) \leq -kE(t) + c \int_{t_0}^t g(s) \int_{\Omega} |\nabla u(t) - \nabla u(t-s)|^2 dx ds. \quad (4.26)$$

We use Lemmas 4.7 and 4.9 to conclude that, for  $\beta > 0$ ,

$$\mathcal{L}(t) = L(t) + \beta K(t)$$

is nonnegative and for all  $t \geq t_0$  satisfies

$$\begin{aligned} \mathcal{L}'(t) &\leq -\frac{l\alpha}{8} \|v_t(t)\|^2 - \left(\frac{3\alpha}{2} - \frac{3\alpha l}{N}\right) \|u_t(t)\|^2 - \alpha^2 \int_{\Omega} u v dx - \left(\frac{\alpha}{2}(l-\epsilon) - \frac{3\alpha l}{N}\right) \|\nabla u(t)\|^2 \\ &\quad - \left(\frac{\alpha}{2} - 3C_p \alpha^3 \frac{l}{2N}\right) \|\nabla v(t)\|^2 + \frac{1}{2M} (g \circ \nabla u)(t) - \frac{\beta}{2} (g \circ \nabla u)(t) + 3\beta(1-l) \|\nabla u(t)\|^2 \\ &\leq -\frac{l\alpha}{8} \|v_t(t)\|^2 - \left(\frac{3\alpha}{2} - \frac{3\alpha l}{N}\right) \|u_t(t)\|^2 - \alpha^2 \int_{\Omega} u v dx \\ &\quad - \left(\frac{\alpha}{2}(l-\epsilon) - \frac{3\alpha l}{N} - 3\beta(1-l)\right) \|\nabla u(t)\|^2 \\ &\quad - \left(\frac{\alpha}{2} - 3C_p \alpha^3 \frac{l}{2N}\right) \|\nabla v(t)\|^2 - \left(\frac{\beta}{2} - \frac{1}{2M}\right) (g \circ \nabla u)(t). \end{aligned}$$

By selecting  $\beta$  sufficiently small and then  $M$  sufficiently large such that

$$\begin{aligned} \frac{\alpha}{2}(l-\epsilon) - \frac{3\alpha l}{N} - 3\beta(1-l) &> 0, \\ \frac{\beta}{2} - \frac{1}{2M} &> 0, \end{aligned}$$

we easily obtain  $\mathcal{L}'(t) \leq -dE(t)$ , where  $d$  is some positive constant. So,

$$d \int_{t_0}^t E(s) ds \leq \mathcal{L}(t_0) - \mathcal{L}(t) \leq \mathcal{L}(t_0),$$

which implies that

$$\int_0^{\infty} E(s) ds < \infty. \quad (4.27)$$

As in [27], we take

$$J(t) := q \int_{t_0}^t \int_{\Omega} |\nabla u(t) - \nabla u(t-s)|^2 dx ds,$$

where (4.27) allows us to choose a constant  $0 < q < 1$  so that

$$J(t) < 1, \quad \forall t \geq t_0. \quad (4.28)$$

Then, we take

$$\lambda(t) := - \int_{t_0}^t g'(s) \int_{\Omega} |\nabla u(t) - \nabla u(t-s)|^2 dx ds$$

and observe that  $\lambda(t) \leq -cE'(t)$ . Since  $G$  is strictly convex on  $(0, r]$  and  $G(0) = 0$ , it follows that

$$G(\theta z) \leq \theta G(z), \quad \text{for } 0 \leq \theta \leq 1 \text{ and } z \in (0, r].$$

By employing the above estimate, hypothesis (A1), (4.28) and Jensen's inequality, we obtain

$$\lambda(t) = \frac{1}{J(t)} \int_{t_0}^t J(t)(-g'(s)) \int_{\Omega} (|\nabla u(t) - \nabla u(t-s)|^2) dx ds$$

$$\begin{aligned}
&\geq \frac{1}{J(t)} \int_{t_0}^t J(t)\xi(s)G(g(s)) \int_{\Omega} (|\nabla u(t) - \nabla u(t-s)|^2) dx ds \\
&\geq \frac{\xi(t)}{J(t)} \int_{t_0}^t G(J(t)g(s)) \int_{\Omega} (|\nabla u(t) - \nabla u(t-s)|^2) dx ds \\
&\geq \frac{\xi(t)}{q} G\left(\frac{1}{J(t)} \int_{t_0}^t J(t)g(s)q \int_{\Omega} (|\nabla u(t) - \nabla u(t-s)|^2) dx ds\right) \\
&= \frac{\xi(t)}{q} G\left(q \int_{t_0}^t g(s) \int_{\Omega} (|\nabla u(t) - \nabla u(t-s)|^2) dx ds\right) \\
&= \frac{\xi(t)}{q} \bar{G}\left(q \int_{t_0}^t g(s) \int_{\Omega} (|\nabla u(t) - \nabla u(t-s)|^2) dx ds\right),
\end{aligned}$$

where  $\bar{G}$  is an extension of  $G$  such that  $\bar{G}$  is strictly increasing and strictly convex  $C^2$  function on  $(0, \infty)$ . This indicates that

$$\int_{t_0}^t g(s) \int_{\Omega} (|\nabla u(t) - \nabla u(t-s)|^2) dx ds \leq \frac{1}{q} \bar{G}^{-1}\left(\frac{q\lambda(t)}{\xi(t)}\right),$$

and (4.26) becomes

$$F'(t) \leq -kE(t) + \frac{c}{q} \bar{G}^{-1}\left(\frac{q\lambda(t)}{\xi(t)}\right), \quad \forall t \geq t_0. \quad (4.29)$$

For  $\varepsilon_0 < r$ , using (4.4), and the fact that  $E' \leq 0$ ,  $\bar{G}' > 0$ ,  $\bar{G}'' > 0$ , we find that the functional  $F_1$ , defined by

$$F_1(t) := \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) F(t),$$

satisfies

$$\begin{aligned}
F_1'(t) &= \frac{\varepsilon_0 E'(t)}{E(0)} \bar{G}''\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) F(t) + \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) F'(t) \\
&\leq -kE(t) \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) + \frac{c}{q} \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) \bar{G}^{-1}\left(\frac{q\lambda(t)}{\xi(t)}\right).
\end{aligned} \quad (4.30)$$

Consider  $\bar{G}^*$  the convex conjugate of  $\bar{G}$  in the sense of Young [3, pp. 61-64], given by

$$\bar{G}^* = s(\bar{G}')^{-1}(s) - \bar{G}[(\bar{G}')^{-1}(s)], \quad (4.31)$$

and which satisfies the generalized Young inequality

$$AB \leq \bar{G}^*(A) + \bar{G}(B). \quad (4.32)$$

Then, with  $A = \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right)$  and  $B = \bar{G}^{-1}\left(\frac{q\lambda(t)}{\xi(t)}\right)$ , and using (3) and (4.5)–(4.3), we attain

$$\begin{aligned}
F_1'(t) &\leq -kE(t) \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) + \frac{c}{q} \bar{G}^*\left(\bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right)\right) + \frac{c}{q} \frac{q\lambda(t)}{\xi(t)} \\
&\leq -kE(t) \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) + \frac{c}{q} \frac{E(t)}{E(0)} \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) + \frac{c\lambda(t)}{\xi(t)} \\
&\leq -kE(t) \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) + \widehat{c}\varepsilon_0 \frac{E(t)}{E(0)} \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) + \frac{c\lambda(t)}{\xi(t)} \\
&= -(kE(0) - \widehat{c}\varepsilon_0) \frac{E(t)}{E(0)} \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) + \frac{c\lambda(t)}{\xi(t)}.
\end{aligned}$$

After fixing  $\varepsilon_0$  much smaller (if needed), we arrive at

$$F_1'(t) \leq -k_1 \frac{E(t)}{E(0)} \bar{G}'\left(\frac{\varepsilon_0 E(t)}{E(0)}\right) + \frac{c\lambda(t)}{\xi(t)},$$

where  $k_1 > 0$ .

Then, we multiply by  $\xi(t)$  and take  $\varepsilon_0$  so small that,  $\varepsilon_0 \frac{E(t)}{E(0)} < r$ ,  $\overline{G}'\left(\varepsilon_0 \frac{E(t)}{E(0)}\right) = G'\left(\varepsilon_0 \frac{E(t)}{E(0)}\right)$  to arrive at

$$\begin{aligned}\xi(t)F_1'(t) &\leq -k_1\xi(t)\frac{E(t)}{E(0)}G'\left(\varepsilon_0\frac{E(t)}{E(0)}\right) + cq\lambda(t) \\ &\leq -k_1\xi(t)\frac{E(t)}{E(0)}G'\left(\varepsilon_0\frac{E(t)}{E(0)}\right) - cE'(t).\end{aligned}$$

Let  $F_2 = \xi F_1 + cE$  and recall that  $\xi$  is non-increasing, to obtain

$$F_2'(t) \leq \xi(t)F_1'(t) + cE'(t) \leq -k_1\xi(t)\frac{E(t)}{E(0)}G'\left(\varepsilon_0\frac{E(t)}{E(0)}\right),$$

or

$$k_1\xi(t)\frac{E(t)}{E(0)}G'\left(\varepsilon_0\frac{E(t)}{E(0)}\right) \leq -F_2'(t). \quad (4.33)$$

Using the strictly increasing property of  $G'$ , non-increasing properties of  $E$  and  $\xi$ , we obtain for  $t \geq t_0$ ,

$$k_1\frac{\varepsilon_0 E(t)}{E(0)}G'\left(\varepsilon_0\frac{E(t)}{E(0)}\right)\int_{t_0}^t \xi(s)ds \leq \varepsilon_0 F_2(t_0).$$

Next, we set  $G_2(\tau) = \tau G'(\tau)$  which is strictly increasing, then we obtain, for some fixed positive constants  $C$  and  $\gamma$

$$E(t) \leq CG_2^{-1}\left(\frac{\gamma}{\int_{t_0}^t \xi(s)ds}\right), \quad \forall t \geq t_0.$$

This complete the proof.  $\square$

**Examples.** Here we give several examples to illustrate our decay result given by Theorem 4.10.

(1) Consider the relaxation function

$$g(t) = \frac{a}{[\ln(e+t)]^p}, \quad a > 0, p > 2,$$

where  $a$  is chosen so that hypothesis (A1) is satisfied.

$$g'(t) = -\xi(t)G(g(t)), \quad \text{with } \xi(t) = \frac{p}{(e+t)\ln(e+t)}, \quad G(s) = s.$$

Therefore, estimate (4.23) implies that

$$E(t) \leq \frac{C}{\ln \ln(e+t) - \ln \ln(e+t_0)}, \quad \forall t \geq t_0.$$

(2) Consider the relaxation function

$$g(t) = e^{-at},$$

where  $a$  is chosen so that condition (A1) is satisfied, then

$$g'(t) = -\xi(t)G(g(t)), \quad \xi(t) = a, \quad G(s) = s.$$

Therefore, estimate (4.23) implies that

$$E(t) \leq \frac{C}{t-t_0}, \quad \forall t \geq t_0.$$

(3) Consider the relaxation function

$$g(t) = ae^{-(1+t)^\nu}, \quad 0 < \nu < 1,$$

and  $a$  is chosen so that condition (A1) is satisfied. Then

$$g'(t) = -\xi(t)G(g(t)), \quad \xi(t) = \nu(1+t)^{\nu-1}, \quad G(s) = s$$

and estimate (4.23) entails

$$E(t) \leq \frac{C}{(1+t)^\nu - (1+t_0)^\nu}, \quad \forall t \geq t_0.$$

(4) Consider the relaxation function, for  $\nu > 1$ ,

$$g(t) = \frac{a}{(1+t)^\nu}$$

and  $a$  is chosen so that hypothesis (A1) remains valid. Then

$$g'(t) = -\xi(t)G(g(t)), \quad \text{with } \xi(t) = b, \quad G(s) = s^p,$$

where  $b$  is a fixed constant,  $p = \frac{1+\nu}{\nu}$ , and  $1 < p < 2$ . Then  $G_2(t) = pt^p$ , and from (4.24), we deduce that

$$E(t) \leq C \left[ (1+t)^\nu - (1+t_0)^\nu \right]^{-\frac{\nu}{1+\nu}}, \quad \forall t > t_0.$$

### 5. NUMERICAL APPROACH

In this section, we examine the computational behavior of the system (1.1) using the finite volume method by discretizing the system on the space-time domain  $(0, 1) \times (0, 60)$  using second order finite difference method. For a similar construction, we refer to [22, 13]. Our numerical simulations are realized in the one-dimensional case. Then, we consider the system

$$\begin{aligned} u_{tt} - u_{xx} + \int_0^t g(t-s)u_{xx}(s) ds + \alpha v &= 0, \quad \text{in } (0, 1) \times (0, T), \\ v_{tt} - v_{xx} + \alpha u &= 0, \quad \text{in } (0, 1) \times (0, T), \\ u(0, t) = u(1, t) = 0, \quad v(0, t) = v(1, t) = 0, \quad 0 < t < T, \\ u(x, 0) = u_0(x), \quad u_t(x, 0) = u_1(x), \\ v(x, 0) = v_0(x), \quad v_t(x, 0) = v_1(x), \quad 0 < x < 1. \end{aligned}$$

**5.1. Explicit time integration method.** For our purpose, we set  $\Delta x = L/(J + 1)$  and  $\Delta t = L/(N + 1)$  for  $J, N \in \mathbb{N}$ , and consider the discretization

$$\begin{aligned} x_0 = 0 < x_1 = \Delta x < \dots < x_J = J\Delta x < x_{J+1} = L, \\ t_0 = 0 < t_1 = \Delta t < \dots < t_N = N\Delta t < t_{N+1} = T, \end{aligned}$$

where  $x_j = j\Delta x$  and  $t_n = n\Delta t$ , for  $j = 1, 2, \dots, J$  and  $n = 1, 2, \dots, N$ . For the memory term

$$\int_0^t g(t-s)\Delta u(s) ds,$$

we apply the trapezoidal rule

$$I_j^n = \sum_{i=0}^{n-1} \frac{\Delta t}{2} \left[ g(t_n - t_i)u_{xx_j}^i + g(t_n - t_{i+1})u_{xx_j}^{i+1} \right], \quad \text{where } u_{xx_j}^i = \frac{u_{j+1}^i - 2u_j^i + u_{j-1}^i}{\Delta x^2}.$$

Thus, we obtain from the cumulative sum the numerical approximation of (5.1)

$$I_j^n = \frac{\Delta t}{2} \left[ g(t_n - t_0)u_{xx_j}^0 + \sum_{i=1}^{n-1} \left( g(t_n - t_i)u_{xx_j}^i + g(t_n - t_{i+1})u_{xx_j}^{i+1} \right) + g(t_n - t_n)u_{xx_j}^n \right].$$

We consider the finite-difference discretization of (5)-(5)

$$\frac{u_j^{n+1} - 2u_j^n + u_j^{n-1}}{\Delta t^2} - \frac{u_{j+1}^n - 2u_j^n + u_{j-1}^n}{\Delta x^2} + I_j^n + \alpha v_j^n = 0, \tag{5.1}$$

$$\frac{v_j^{n+1} - 2v_j^n + v_j^{n-1}}{\Delta t^2} - \frac{v_{j+1}^n - 2v_j^n + v_{j-1}^n}{\Delta x^2} + \alpha u_j^n = 0, \tag{5.2}$$

for all  $j = 1, 2, \dots, J$ ,  $n = 1, 2, \dots, N$ . Such a scheme is in fact explicit and its implementation is straightforward. The boundary conditions are

$$u_0^n = u_{J+1}^n = 0, \quad v_0^n = v_{J+1}^n = 0, \quad \forall n = 1, 2, \dots, N \tag{5.3}$$

and the initial conditions are

$$u_j^0 = u(x_j, 0), \quad u_j^1 = u_j^0 + \Delta t u_t(x_j, 0), \quad \forall j = 1, 2, \dots, J, \tag{5.4}$$

$$v_j^0 = v(x_j, 0), \quad v_j^1 = v_j^0 + \Delta t v_t(x_j, 0), \quad \forall j = 1, 2, \dots, J. \quad (5.5)$$

Finally, we obtain this discrete system

$$\begin{aligned} u_j^{n+1} &= 2u_j^n - u_j^{n-1} + \frac{\Delta t^2}{\Delta x^2} (u_{j+1}^n - 2u_j^n + u_{j-1}^n) - \Delta t^2 I_j^n - \Delta t^2 \alpha v_j^n, \\ v_j^{n+1} &= 2v_j^n - v_j^{n-1} + \frac{\Delta t^2}{\Delta x^2} (v_{j+1}^n - 2v_j^n + v_{j-1}^n) - \Delta t^2 \alpha u_j^n. \end{aligned}$$

**5.2. Energy conserving scheme.** In this subsection, we construct the numerical energy associated with the system (5.1)-(5.2)

$$\begin{aligned} E^n &:= \frac{\Delta x}{2} \left[ \sum_{j=0}^J \left( \frac{u_j^{n+1} - u_j^n}{\Delta t} \right)^2 + \sum_{j=0}^J \left( \frac{v_j^{n+1} - v_j^n}{\Delta t} \right)^2 + \left( 1 - \int_0^{t_n} g(s) ds \right) \sum_{j=1}^{J-1} \left( \frac{u_{j+1}^n - u_j^n}{\Delta x} \right)^2 \right. \\ &\quad + \sum_{j=1}^{J-1} \left( \frac{v_{j+1}^n - v_j^n}{\Delta x} \right)^2 + \sum_{k=0}^{n-1} \frac{\Delta t}{2} \sum_{j=1}^{J-1} g(t_n - t_k) \left( \left( \frac{u_{j+1}^n - u_j^n}{\Delta x} \right)^2 - \left( \frac{u_{j+1}^k - u_j^k}{\Delta x} \right)^2 \right)^2 \\ &\quad \left. + \sum_{j=0}^J \alpha v_j^n u_j^n \right]. \end{aligned}$$

We note that  $E^n$  is the discrete version of the continuous energy (4.1) in the one-dimensional setting. Instead of computing the time derivative of the energy we can use the summation by parts. The discrete energy  $E^n$  is an important numerical instrument to certify our analytical results concerning the stabilization of system (5)-(5). Now, we present our tests.

**Test 1.** We present the decay case using the exponential function  $g_1(t) = 0.5 e^{-2t}$  and the polynomial function  $g_2(t) = (1/(1+t)^{5/2})$ , where we consider the following initial conditions

$$\begin{aligned} u(x, 0) &= \sin(\pi x), \quad u_t(x, 0) = 0, \quad x \in [0, 1], \\ v(x, 0) &= -\sin(\pi x), \quad v_t(x, 0) = -\sin(\pi x), \quad x \in [0, 1]. \end{aligned}$$

**Test 2.** We examine the energy decay using the function  $g_2(t) = (1/(1+t)^{5/2})$  and taking the following initial conditions

$$\begin{aligned} u(x, 0) &= \sin(\pi x), \quad u_t(x, 0) = \sin(\pi x), \quad x \in [0, 1], \\ v(x, 0) &= 2x(1-x), \quad v_t(x, 0) = 2x(1-x), \quad x \in [0, 1]. \end{aligned}$$

To ensure numerical stability, we impose the Courant-Friedrichs-Lewy (CFL) condition, which requires the time step  $\Delta t$  and spatial step  $\Delta x$  to satisfy  $\Delta t < \Delta x$ . In our implementation, we set  $\Delta t = 0.005$  and  $\Delta x = 0.02$ , ensuring the stability criterion is met. The spatial domain  $[0, 1]$  is discretized into 200 subintervals, and the temporal interval is determined based on the stability condition. The simulation is executed for 10,000 time steps with  $\Delta t = 2 \times 10^{-3}$ .

In Figures 1–3, we plot the damping behavior of the two waves,  $u$  and  $v$ , at the cross-sections  $x = 0.25$ ,  $x = 0.5$ , and  $x = 0.75$ , and the decay behavior of the resulting energies. As a key conclusion, we conducted multiple tests for two types of decaying relaxation functions: exponential decay and polynomial decay. In each case, we observed that the energy decays at least at a polynomial rate, which aligns with our theoretical predictions.

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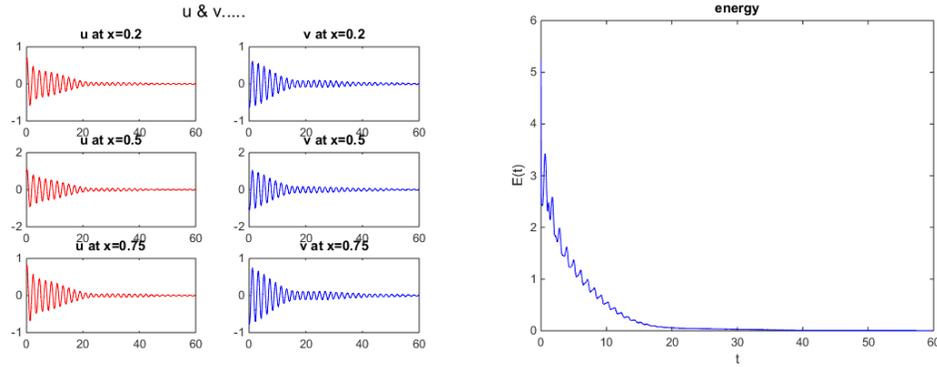


FIGURE 1. Test 1: Wave propagation of  $u$  and  $v$  over time and energy decay, with  $g_1(t) = 0.5 e^{-2t}$ .

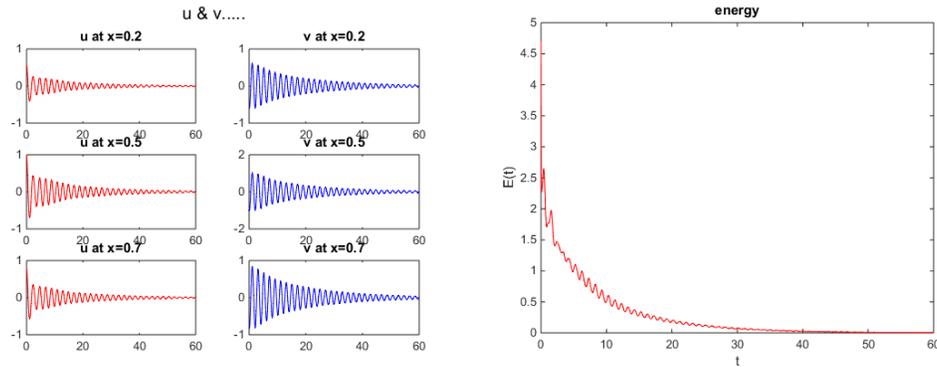


FIGURE 2. Test 1: Wave propagation of  $u$  and  $v$  over time and energy decay, with  $g_2(t) = (1/(1+t)^{5/2})$ .

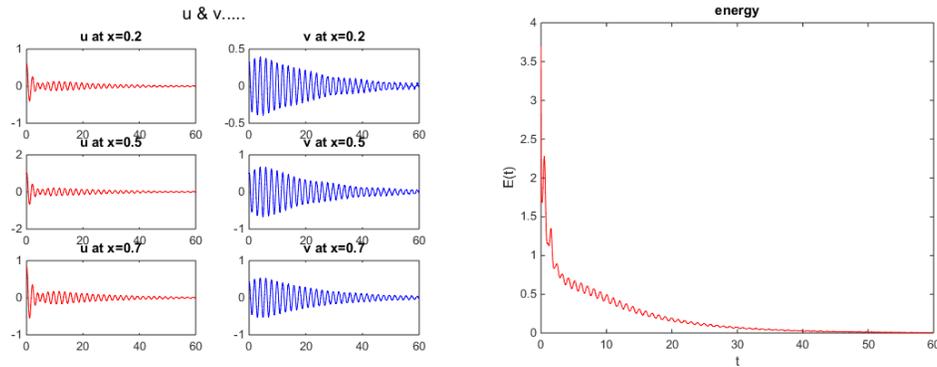


FIGURE 3. Test 2: Wave propagation of  $u$  and  $v$  over time and energy decay, with  $g_2(t) = (1/(1+t)^{5/2})$ .

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